

习题课 1

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基本概念：

一、一些数学结论

1.坐标系/积分、 ∇ 算符

除了直角坐标系，还有两个常用正交曲线坐标系：柱坐标系、球坐标系；
其他：环坐标系（可控核聚变 Tokamak）、椭球坐标系（Landau 椭球面电荷面密度）

①微分：（坐标： (q_i, q_j, q_k) ），对应方向矢量 $\vec{e}_i, \vec{e}_j, \vec{e}_k$ ）

(1)弧元、面元、体积元表达式

$$dl_i = h_i dq_i$$

（垂直 $\vec{e}_i$ 的面元记为 dS_i ）

$$d\vec{S}_i = dS_i \vec{e}_i = dl_j dl_k \vec{e}_i = h_j h_k dq_j dq_k \vec{e}_i$$

$$dV = dl_i dl_j dl_k = h_i h_j h_k dq_i dq_j dq_k$$

(2)Lamé 系数，以直角坐标系为跳板

$$h_i = \left| \frac{\partial \vec{l}}{\partial q_i} \right| = \left| \frac{\partial x}{\partial q_i} \hat{x} + \frac{\partial y}{\partial q_i} \hat{y} + \frac{\partial z}{\partial q_i} \hat{z} \right| = \sqrt{\left(\frac{\partial x}{\partial q_i} \right)^2 + \left(\frac{\partial y}{\partial q_i} \right)^2 + \left(\frac{\partial z}{\partial q_i} \right)^2}$$

(3) ∇ 算符：

$$\text{梯度 } \vec{E} = -\nabla U、\text{散度} \begin{cases} \nabla \cdot \vec{E} = \frac{\rho_e}{\varepsilon_0} \\ \nabla \cdot \vec{P} = \rho'_e \\ \nabla \cdot \vec{D} = \rho_{e0} \end{cases}、\text{旋度 } \nabla \times \vec{E} = \vec{0}$$

a)梯度

$$\nabla U = \sum_i \frac{\partial U}{\partial r_i} \vec{e}_i = \sum_i \frac{1}{h_i} \frac{\partial U}{\partial q_i} \vec{e}_i$$

b)散度。定义（邻域的通量）：

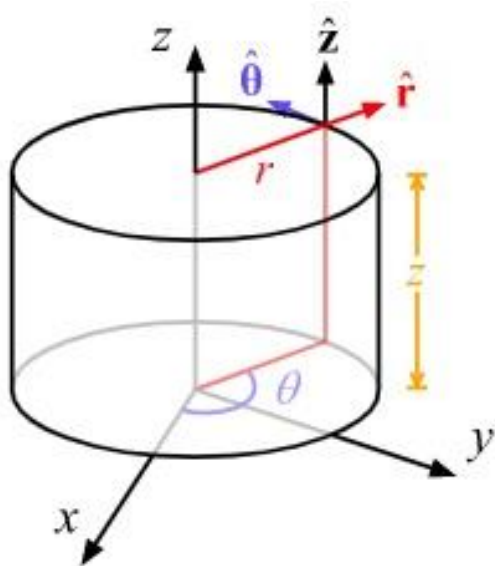
$$\begin{aligned} \nabla \cdot \vec{E} &\stackrel{\text{def}}{=} \frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} + \frac{\partial E_z}{\partial z} \\ &\stackrel{\text{def}}{=} \lim_{V \rightarrow 0} \frac{1}{V} \oint_{\partial V} \vec{E} \cdot d\vec{S} = \lim_{V \rightarrow 0} \frac{1}{V} \oint_{\partial V} E_i \cdot dS_i \\ &= \frac{1}{h_1 h_2 h_3} \left[\frac{\partial(h_2 h_3 E_1)}{\partial q_1} + \frac{\partial(h_3 h_1 E_2)}{\partial q_2} + \frac{\partial(h_1 h_2 E_3)}{\partial q_3} \right] \end{aligned}$$

c)旋度

$$\begin{aligned} \nabla \times \vec{E} &\stackrel{\text{def}}{=} \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x & E_y & E_z \end{vmatrix} \\ &\stackrel{\text{def}}{=} \lim_{S \rightarrow 0} \frac{1}{S} \oint_{\partial S} \vec{E} \cdot d\vec{l} = \lim_{S \rightarrow 0} \frac{1}{S} \oint_{\partial S} E_i \cdot dl_i \\ &= \frac{1}{h_2 h_3} \frac{\partial(h_1 E_1)}{\partial q_1} + \frac{1}{h_3 h_1} \frac{\partial(h_2 E_2)}{\partial q_2} + \frac{1}{h_1 h_2} \frac{\partial(h_3 E_3)}{\partial q_3} \end{aligned}$$

②特殊正交曲线坐标系：

(1)柱坐标系：



$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases}$$

Lamé 系数

$$\begin{cases} h_r = 1 \\ h_\theta = r \\ h_z = 1 \end{cases}$$

柱面上的积分：

$$\iint_S \sigma dS_r = \int_0^{2\pi} \int_0^z \sigma r d\theta dz$$

圆盘上的积分：

$$\iint_S \sigma dS_z = \int_0^{2\pi} \int_0^r \sigma r dr d\theta$$

体积分：

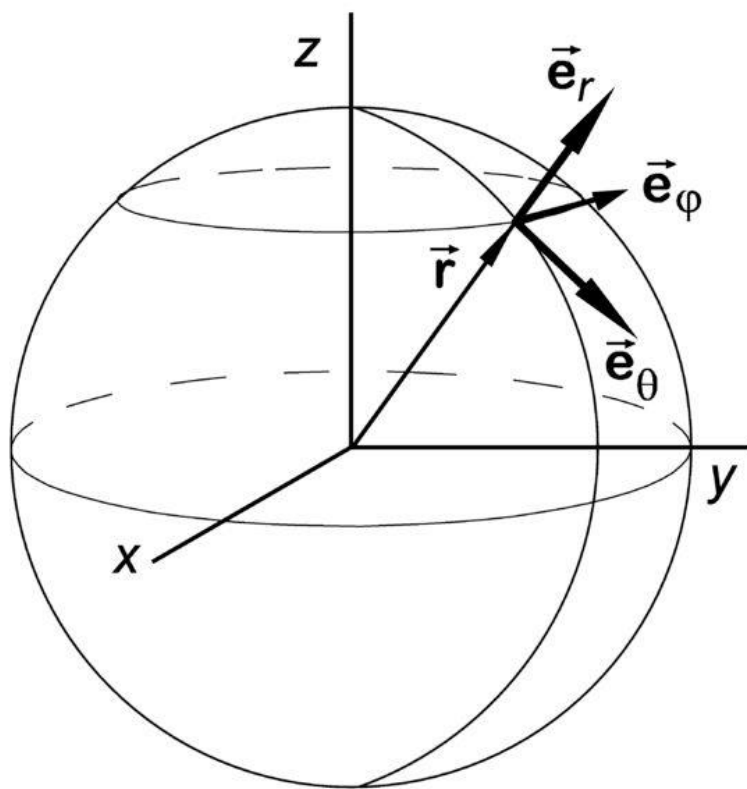
$$\iiint_V \rho dV = \int_0^r \int_0^{2\pi} \int_0^z \sigma r dr d\theta dz$$

∇ 算符

$$-\nabla U = -\frac{\partial U}{\partial r} \hat{r} - \frac{1}{r} \frac{\partial U}{\partial \theta} \hat{\theta} - \frac{\partial U}{\partial z} \hat{z}$$

$$\nabla \cdot \vec{P} = \frac{1}{r} \left[\frac{\partial(rP_r)}{\partial r} + \frac{\partial P_\theta}{\partial \theta} + \frac{\partial(rP_z)}{\partial z} \right] = \frac{1}{r} \frac{\partial(rP_r)}{\partial r} + \frac{1}{r} \frac{\partial P_\theta}{\partial \theta} + \frac{\partial P_z}{\partial z}$$

(1)球坐标系：注意 θ 为纬度，与柱坐标有区别



$$\begin{cases} x = r \cos \theta \cos \phi \\ y = r \cos \theta \sin \phi \\ z = r \sin \theta \end{cases}$$

Lamé 系数

$$\begin{cases} h_r = 1 \\ h_\theta = r \\ h_z = r \sin \theta \end{cases}$$

球面上的积分:

$$\oiint_S \sigma dS_r = \int_0^\pi \int_0^{2\pi} \sigma r^2 \sin \theta \, d\theta d\varphi$$

体积分:

$$\iiint_V \rho dV = \int_0^r \int_0^\pi \int_0^{2\pi} \sigma r^2 \sin \theta \, dr d\theta d\varphi$$

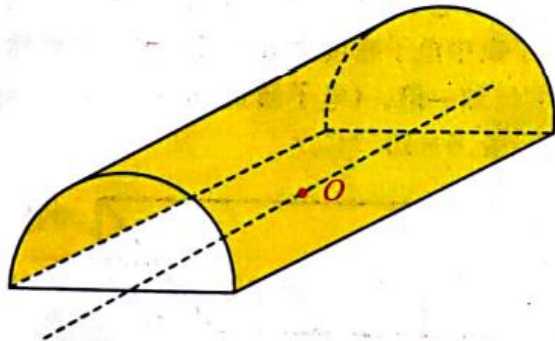
∇ 算符

$$-\nabla U = -\frac{\partial U}{\partial r} \hat{\mathbf{r}} - \frac{1}{r} \frac{\partial U}{\partial \theta} \hat{\boldsymbol{\theta}} - \frac{1}{r \sin \theta} \frac{\partial U}{\partial \varphi} \hat{\boldsymbol{\varphi}}$$

$$\begin{aligned} \nabla \cdot \vec{\mathbf{P}} &= \frac{1}{r^2 \sin \theta} \left[\frac{\partial(r^2 \sin \theta P_r)}{\partial r} + \frac{\partial(r \sin \theta P_\theta)}{\partial \theta} + \frac{\partial(r^2 P_\varphi)}{\partial \varphi} \right] \\ &= \frac{1}{r^2} \frac{\partial(r^2 P_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\sin \theta P_\theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial P_\varphi}{\partial \varphi} \end{aligned}$$

1.13 (柱面积分和换元)

半径为 R 的无限长半圆柱薄筒, 均匀带电, 单位面积的电量为 σ , 求半圆柱轴线上一点 O 的场强.



以 O 为原点, 建立适当的柱坐标系。由对称性, 点 O 处的电场强度方向竖直向下, 大小为

$$E = \frac{1}{4\pi\epsilon_0} \int_{-\infty}^{+\infty} dz \int_0^\pi \frac{\sigma}{R^2 + z^2} \frac{R \sin \theta}{\sqrt{R^2 + z^2}} R d\theta = \frac{\sigma R^2}{2\pi\epsilon_0} \int_{-\infty}^{+\infty} \frac{dz}{(R^2 + z^2)^{\frac{3}{2}}}$$

换元积分: $z \in (-\infty, +\infty)$, 记 $z = R \tan \varphi$, $\varphi \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$, 则 $\frac{1}{R^2 + z^2} =$

$$\frac{\cos^2 \varphi}{R^2}, \quad dz = \frac{R d\varphi}{\cos^2 \varphi}$$

$$E = \frac{\sigma R^2}{2\pi\epsilon_0} \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \frac{\cos \varphi d\varphi}{R^2} = \frac{\sigma}{\pi\epsilon_0}$$

例题 1: (球面积分) 某导体球壳面电荷分布满足 $\sigma_e = 3\epsilon_0 E_0 \cos \theta$

(球坐标系)。求 z 方向上各点的电场强度、电势

记导体球半径为 R 。先求电势:

$$U = \frac{1}{4\pi\epsilon_0} \oint \frac{\sigma_e}{(r^2 + R^2 - 2Rr \cos \theta)^{\frac{1}{2}}} dS$$

$$\begin{aligned}
&= \frac{1}{4\pi\epsilon_0} \int_0^{2\pi} d\varphi \int_0^\pi \frac{3\epsilon_0 E_0 \cos \theta}{(r^2 + R^2 - 2Rr \cos \theta)^{\frac{1}{2}}} R^2 \sin \theta d\theta \\
&= \frac{3E_0 R^2}{2} \int_0^\pi \frac{\cos \theta}{(r^2 + R^2 - 2Rr \cos \theta)^{\frac{1}{2}}} - d \cos \theta \\
&= \frac{3E_0 R^2}{2b^2} \int_1^{-1} \frac{(a - bt) - a}{(a - bt)^{\frac{1}{2}}} d(bt) \\
&= \frac{3E_0 R^2}{2b^2} \left[-\frac{2}{3} (a - bt)^{\frac{3}{2}} \right]_1^{-1} + 2a(a - bt)^{\frac{1}{2}} \Big|_1^{-1} \\
&= \frac{E_0 R^2}{4R^2 r^2} \{ -[(r + R)^3 - (r - R)^3] + 3(r^2 + R^2)[r + R - (r - R)] \} \\
&= \frac{E_0}{4r^2} \{ -[6Rr^2 + 2R^3] + 3(2Rr^2 + 2R^3) \} \\
&= \frac{E_0 R^3}{r^2}
\end{aligned}$$

$$\begin{aligned}
E &= \frac{1}{4\pi\epsilon_0} \oint \frac{\sigma_e}{r^2 + R^2 - 2Rr \cos \theta} \frac{r - R \cos \theta}{(r^2 + R^2 - 2Rr \cos \theta)^{\frac{1}{2}}} dS \\
&= \left(1 + \frac{2r_0^3}{r^3} \right) E_0
\end{aligned}$$

作为参考，空间任一点的电势：

$$\begin{aligned}
U &= \frac{1}{4\pi\epsilon_0} \oint \frac{3\epsilon_0 E_0 \cos \theta'}{(r^2 + R^2 - 2Rr[\cos \theta \cos \theta' \cos(\varphi - \varphi') + \sin \theta \sin \theta'])^{\frac{1}{2}}} dS' \\
&= \frac{E_0 R^3}{r^2} \cos \theta
\end{aligned}$$

例题 2：（球面积分）库伦定律 $\delta \neq 0$ 时，均匀带电球壳的电场强度和电势分布。

点电荷的电场强度和电势分布易得：

$$E = \frac{Q}{4\pi\varepsilon_0 r'^{2+\delta}}$$

$$U = \frac{Q}{4\pi\varepsilon_0(1+\delta)r'^{1+\delta}}$$

球壳 $r > R$ 时:

$$\begin{aligned} U &= \oiint_{\partial V} \frac{\sigma_e}{4\pi\varepsilon_0(1+\delta)r'^{1+\delta}} dS \\ &= \frac{Q}{8\pi\varepsilon_0(1+\delta)} \int_0^\pi \frac{1}{(r^2 + R^2 - 2Rr \cos \theta)^{\frac{1+\delta}{2}}} \sin \theta d\theta \\ &= \frac{Q}{8\pi\varepsilon_0(1+\delta)} \frac{1}{Rr} \left[\frac{1}{1-\delta} (r^2 + R^2 - 2Rr \cos \theta)^{\frac{1-\delta}{2}} \right]_0^\pi \\ &= \frac{Q}{8\pi\varepsilon_0} \frac{(r+R)^{1-\delta} - (r-R)^{1-\delta}}{(1-\delta^2)Rr} \\ &\approx \frac{Q}{4\pi\varepsilon_0} \frac{1 - \frac{(r+R) \ln\left(1 + \frac{R}{r}\right) - (r-R) \ln\left(1 - \frac{R}{r}\right)}{2R}}{r^{1+\delta}} \delta \end{aligned}$$

$$\begin{aligned} E &= \oiint_{\partial V} \frac{\sigma_e}{4\pi\varepsilon_0 r'^{2+\delta}} \cdot \frac{r - R \cos \theta}{r'} dS \\ &= \frac{Q}{8\pi R^2 \varepsilon_0} \int_0^\pi \frac{r - R \cos \theta}{(r^2 + R^2 - 2Rr \cos \theta)^{\frac{3+\delta}{2}}} R^2 \sin \theta d\theta \end{aligned}$$

2.简谐振动

若物体受力

$$\vec{F} = -kx\hat{x}$$

k 为常数。则物体运动形式为一维简谐振动，振动周期

$$T = 2\pi\sqrt{\frac{m}{k}}$$

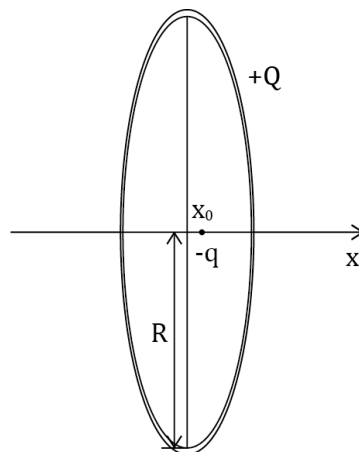
位移满足

$$x = A \cos\left(\sqrt{\frac{k}{m}}t + \delta\right)$$

A 、 δ 由初始条件 $\begin{cases} x|_{t=0} = x_0 \\ \left.\frac{dx}{dt}\right|_{t=0} = v_0 \end{cases}$ 求得

1.7（柱面积分，简谐振动）

半径为 R 的细金属环带电量为 $+Q$ ，小球质量为 m ，电量为 $-q$ ，它可以沿着穿过环中心的一根细轨道无摩擦地运动，如果把小球放置在与环中心距离为 $x_0 \ll R$ 处无初速地释放，求小球的运动规律。



细金属环的电荷线密度为：

$$\lambda = \frac{Q}{2\pi R}$$

建立适当的柱坐标系。由对称性， $\vec{F} \parallel \hat{x}$ ，且应当与小球的位置矢量 $\vec{x}$ 方向相反。

$$\begin{aligned}\vec{F} &= \frac{1}{4\pi\epsilon_0} \oint_{\partial S} \frac{-q\lambda}{R^2 + x^2} \frac{x}{\sqrt{R^2 + x^2}} \hat{x} dl = -\frac{1}{8\pi^2\epsilon_0 R} \hat{x} \int_0^{2\pi} \frac{qQx}{(R^2 + x^2)^{\frac{3}{2}}} R d\theta \\ &= -\frac{1}{4\pi\epsilon_0} \frac{qQx}{(R^2 + x^2)^{\frac{3}{2}}} \hat{x} \approx -\frac{qQx}{4\pi\epsilon_0 m R^3} \hat{x}\end{aligned}$$

因此小球的运动形式为一维简谐振动：

$$x = A \cos(\omega t + \delta)$$

初始条件 $x|_{t=0} = x_0$, $\left.\frac{dx}{dt}\right|_{t=0} = 0$ 得到

$$x = x_0 \cos\left(\sqrt{\frac{qQ}{4\pi\epsilon_0 m R^3}} t\right)$$

3.泰勒展开

$$(1+x)^\alpha = 1 + \alpha x + \frac{\alpha(\alpha-1)}{2} x^2 + o(x^2)$$

二、一些物理结论（黑字部分适当说明可以直接使用）

1. 电场、电势（除电偶极子需说明使用高斯定理；揣摩出题人意图，特定情形电偶极子结论可以直接使用）

(1) 点：

$$\text{点电荷: } \vec{E} = \frac{q}{4\pi\epsilon_0 r^2} \hat{r}, \quad U = \frac{q}{4\pi\epsilon_0 r}$$

$$\text{电偶极子: } \vec{E} = -\frac{\vec{p}}{4\pi\epsilon_0 r^3} + \frac{3(\vec{p} \cdot \hat{r})\hat{r}}{4\pi\epsilon_0 r^3}, \quad U = \frac{\vec{p} \cdot \hat{r}}{4\pi\epsilon_0 r^2}$$

$$(2) \text{直线: } \vec{E} = \frac{\lambda_e}{2\pi\epsilon_0 r} \hat{r}, \quad U = \frac{\lambda_e}{2\pi\epsilon_0} \ln r \quad (\text{以距直线单位长度位置为参考点})$$

(3) 面：

无穷大平面、不考虑边缘效应的平板、面电荷元在邻域上产生的电场（ z_+

$$\text{平面): } \vec{E} = \frac{\sigma_e}{2\epsilon_0} \hat{z}, \quad U = \frac{\sigma_e}{2\epsilon_0} (x - x_0)$$

$$\text{无穷长柱面: } \vec{E} = \frac{\sigma_e R}{\epsilon_0 r} \hat{r}, \quad U = \frac{\sigma_e R}{\epsilon_0} \ln \frac{r}{R} \quad (\text{以 } r = R \text{ 位置为参考点})$$

$$\text{球面: } \vec{E} = \begin{cases} \frac{\sigma_e R^2}{\epsilon_0 r^2} \hat{r}, & r > R \\ 0, & r \leq R \end{cases}, \quad U = \begin{cases} \frac{\sigma_e R^2}{\epsilon_0 r}, & r > R \\ \frac{\sigma_e R}{\epsilon_0}, & r \leq R \end{cases}$$

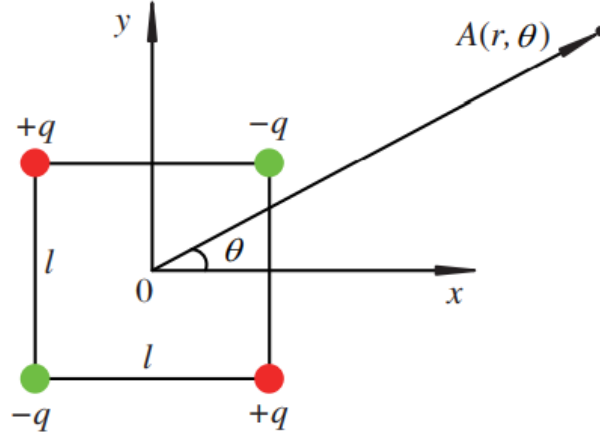
(4) 体：

$$\text{无穷长柱体: } \vec{E} = \frac{\rho_e R^2}{2\epsilon_0 r} \hat{r}, \quad U = \frac{\rho_e R^2}{2\epsilon_0 r} \ln \frac{r}{R} \quad (\text{以 } r = R \text{ 位置为参考点})$$

$$\text{球体: } \vec{E} = \begin{cases} \frac{\rho_e R^3}{3\epsilon_0 r^2} \hat{r}, & r > R \\ \frac{\rho_e r}{3\epsilon_0} \hat{r}, & r \leq R \end{cases}, \quad U = \begin{cases} \frac{\rho_e R^3}{3\epsilon_0 r}, & r > R \\ \frac{\rho_e (3R^2 - r^2)}{6\epsilon_0}, & r \leq R \end{cases}$$

1.15（电偶极子，泰勒展开，球坐标劈形算符，无明显对称性考虑电势）（拓展：空间内任意一点）

面电四极子如习题 1.17 图所示, 点 $A(r, \theta)$ 与电四极子共面, 极轴 ($\theta = 0$) 通过正方形中心并与两边平行。设 $r \gg l$, 求面电四极子在点 A 处产生的电场强度。



习题 1.17 图

视为两个相反方向的电偶极子。球坐标系 (r, θ, φ) 中

$$U_1 = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \vec{r}}{r_1^2} = \frac{pr \sin \theta \cos \varphi}{4\pi\epsilon_0} \frac{1}{r_1^3}$$

$$U_2 = -\frac{pr \sin \theta \cos \varphi}{4\pi\epsilon_0} \frac{1}{r_2^3}$$

$$\begin{aligned} U = U_1 + U_2 &= -\frac{pr \sin \theta \cos \varphi}{4\pi\epsilon_0} \left(\frac{1}{r_2^3} - \frac{1}{r_1^3} \right) \approx -\frac{pr \sin \theta \cos \varphi}{4\pi\epsilon_0 r^3} \frac{3l}{r} \sin \varphi \\ &= -\frac{3ql^2 \sin \theta \sin 2\varphi}{8\pi\epsilon_0 r^3} \end{aligned}$$

其中

$$\begin{aligned} \frac{1}{r_2^3} - \frac{1}{r_1^3} &= \frac{1}{\left(r^2 + \frac{l^2}{4} - lr \sin \theta\right)^{\frac{3}{2}}} + \frac{1}{\left(r^2 + \frac{l^2}{4} + lr \sin \theta\right)^{\frac{3}{2}}} \\ &= \frac{1}{r^3} \left[\frac{1}{\left(1 + \frac{l^2}{4r^2} - \frac{l}{r} \sin \theta\right)^{\frac{3}{2}}} + \frac{1}{\left(1 + \frac{l^2}{4r^2} + \frac{l}{r} \sin \theta\right)^{\frac{3}{2}}} \right] \end{aligned}$$

$$\begin{aligned}
&= \frac{1}{r^3} \left\{ \left[1 - \frac{3}{2} \left(\frac{l^2}{4r^2} - \frac{l}{r} \sin \theta \right) + o\left(\frac{l}{r}\right) \right] - \left[1 - \frac{3}{2} \left(\frac{l^2}{4r^2} + \frac{l}{r} \sin \theta \right) + o\left(\frac{l}{r}\right) \right] \right\} \\
&= \frac{1}{r^3} \left\{ \frac{3l}{r} \sin \theta + o\left(\frac{l}{r}\right) \right\} \approx \frac{1}{r^3} \left\{ \frac{3l}{r} \sin \theta \right\}
\end{aligned}$$

$$\begin{aligned}
\therefore \vec{E} &= -\nabla U = -\frac{\partial U}{\partial r} \hat{r} - \frac{1}{r} \frac{\partial U}{\partial \theta} \hat{\theta} - \frac{1}{r \sin \theta} \frac{\partial U}{\partial \varphi} \hat{\varphi} \\
&= -\frac{9ql^2 \sin \theta \sin 2\varphi}{8\pi\epsilon_0 r^4} \hat{r} + \frac{3ql^2 \cos \theta \sin 2\varphi}{8\pi\epsilon_0 r^4} \hat{\theta} + \frac{3ql^2 \cos 2\varphi}{4\pi\epsilon_0 r^4} \hat{\varphi}
\end{aligned}$$

本题讨论 xOy 平面，令 $\theta = \frac{\pi}{2}$ 得到

$$\vec{E} = -\frac{9ql^2 \sin 2\varphi}{8\pi\epsilon_0 r^4} \hat{r} + \frac{3ql^2 \cos 2\varphi}{4\pi\epsilon_0 r^4} \hat{\varphi}$$

2. 电容器

平行板电容器： $C = \frac{\epsilon_0 S}{d}$

柱形电容器： $C = \frac{2\pi\epsilon_0 L}{\ln\left(\frac{R_2}{R_1}\right)}$

球形电容器： $C = \frac{4\pi\epsilon_0 R_1 R_2}{R_2 - R_1}$

3. 回路电压定律（第3章）

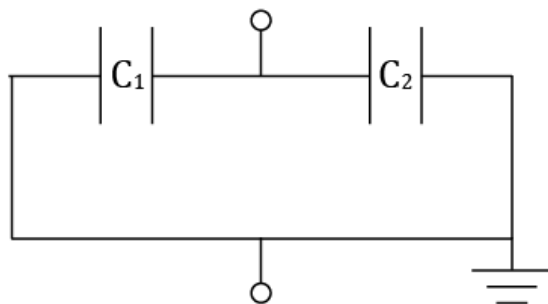
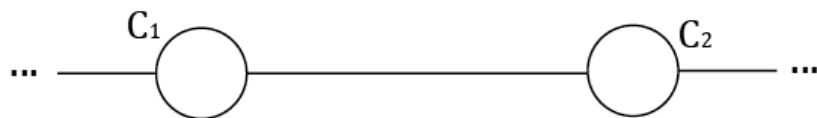
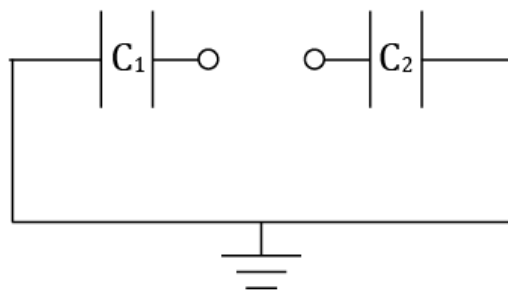
回路逆（顺）时针电压降之和为0。2.11、2.12 用到

4. 电容的串联、并联

充当正极板的导体板与充当正极板的导体板连接，属于并联。

2.8（串并联，无穷远点）

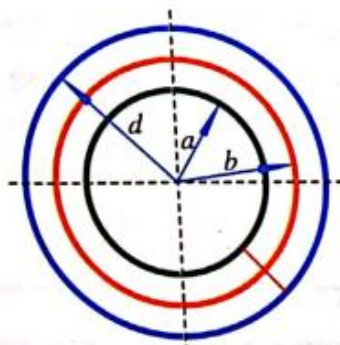
把地球和月球均当作导体球，地球半径为 a ，月球半径为 b ，它们之间的距离远大于它们各自的半径（即可视为孤立导体球），则地球与月球之间的电容值为多少？如果地球与月球之间用一根细导线接通，则此时地球与月球之间的电容为多少？



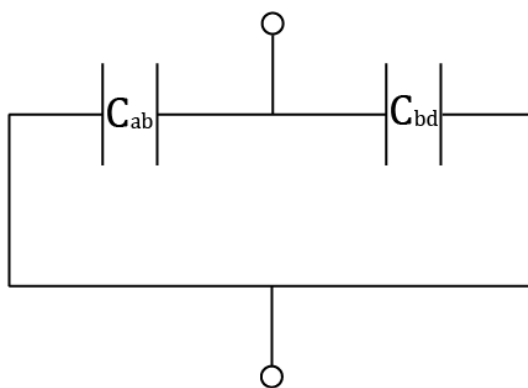
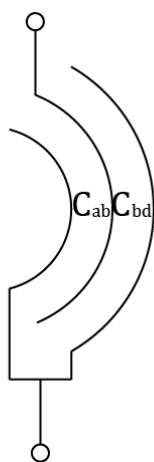
2.8 (串并联)

一个球形电容器由三个很薄的同心导体壳组成,它们的半径分别为 a, b, d 。一根绝缘细导线通过中间壳层的一个小孔把内外球壳连接起来。忽略小孔的边缘效应。

(1) 求此系统的电容;(2) 若在中问球壳上放置任意电量 Q ,确定中间球壳内外表面上的电荷分布。



(1) 若中间球壳带正电,则内球壳外表面和外球壳内表面均带负电。只考虑作为电容的部分,内球壳和外球壳均为负极板。可见导线连接在相同的极板上,因此为并联。



$$C = C_{ab} + C_{bc} = 4\pi\epsilon_0 b \left(\frac{a}{b-a} + \frac{c}{c-b} \right)$$

5.边界(高斯定理、环路定理)

$$\text{边界处法向分量关系(高斯定理):} \begin{cases} \hat{n} \cdot (\vec{E}_2 - \vec{E}_1) = \frac{\sigma_e}{\epsilon_0} \\ \hat{n} \cdot (\vec{P}_2 - \vec{P}_1) = \sigma'_e \\ \hat{n} \cdot (\vec{D}_2 - \vec{D}_1) = \sigma_{e0} \end{cases}$$

边界处切向分量关系（环路定理）：

$$\left\{ \begin{array}{l} \hat{\boldsymbol{n}} \times (\vec{\boldsymbol{E}}_2 - \vec{\boldsymbol{E}}_1) = \vec{\boldsymbol{0}} \\ \frac{\hat{\boldsymbol{n}} \cdot \vec{\boldsymbol{P}}_2}{\hat{\boldsymbol{n}} \cdot \vec{\boldsymbol{P}}_1} = \frac{\varepsilon_2}{\varepsilon_1} \\ \frac{\hat{\boldsymbol{n}} \cdot \vec{\boldsymbol{D}}_2}{\hat{\boldsymbol{n}} \cdot \vec{\boldsymbol{D}}_1} = \frac{\varepsilon_2}{\varepsilon_1} \end{array} \right.$$

作业题

1.8 (特别的积分)

真空中有两个点电荷 q_1 和 q_2 , 它们的质量为 m_1 和 m_2 , 位置为 r_1 和 r_2 , 相距为 r_0 , 只考虑库仑相互作用, 求两个电荷相遇的时间。

易知两点电荷异号, 令 q_1 、 q_2 表示电荷量的绝对值。记点电荷 q_1 到 q_2 的距离为 $\vec{r}$ 。

$$\vec{F}_{21} = m_1 \frac{d^2 \vec{r}_1}{dt^2} = \frac{kq_1 q_2}{r^2} \hat{r}$$

$$\vec{F}_{12} = m_2 \frac{d^2 \vec{r}_2}{dt^2} = -\frac{kq_1 q_2}{r^2} \hat{r}$$

$$\therefore \frac{d^2 \vec{r}}{dt^2} = \frac{d^2 (\vec{r}_2 - \vec{r}_1)}{dt^2} = -\frac{kq_1 q_2}{r^2} \left(\frac{1}{m_1} + \frac{1}{m_2} \right) \hat{r}$$

方法一: 可降阶的二阶微分方程 ($y'' = f(y, y')$)

$$\frac{d^2 r}{dt^2} = -\frac{kq_1 q_2}{r^2} \left(\frac{1}{m_1} + \frac{1}{m_2} \right) \triangleq -\frac{\lambda^2}{r^2}$$

$$\ddot{r} = \frac{d\dot{r}}{dt} = \frac{d\dot{r}}{dr} \frac{dr}{dt} = \dot{r} \frac{d\dot{r}}{dr}$$

$$\dot{r} \frac{d\dot{r}}{dr} = -\frac{\lambda^2}{r^2}$$

边界条件 $\dot{r}|_{t=0} = 0$, $r|_{t=0} = r_0$ 。积分得

$$\dot{r}^2 = 2\lambda^2 \left(\frac{1}{r} - \frac{1}{r_0} \right)$$

$\dot{r}$ 应当为负值, 因此

$$\frac{dr}{dt} = -\sqrt{2\lambda^2 \left(\frac{1}{r} - \frac{1}{r_0} \right)}$$

$$dt = -\frac{dr}{\sqrt{\frac{2\lambda^2 \left(1 - \frac{r}{r_0} \right)}{r}}} = -\sqrt{\frac{r_0^3}{2\lambda^2}} \frac{2x^2 dx}{\sqrt{1-x^2}}$$

积分得

$$t = -\sqrt{\frac{r_0^3}{2\lambda^2}} \left(-\frac{r}{r_0} \sqrt{1 - \left(\frac{r}{r_0} \right)^2} + \arcsin \frac{r}{r_0} \right) \Bigg|_{r_0}^0 = \frac{\pi}{2} \sqrt{\frac{r_0^3}{2\lambda^2}} = \frac{\pi}{2} \sqrt{\frac{2\pi\epsilon_0 r_0^3}{q_1 q_2 \left(\frac{1}{m_1} + \frac{1}{m_2} \right)}}$$

方法二：退化椭圆

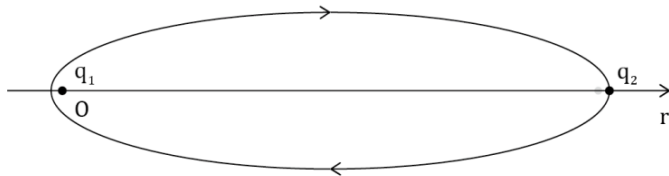
该方程不易求解。可以考虑以点电荷 q_1 为圆心做非惯性参考系。则点电荷 q_2 有惯性加速度

$$\vec{a}_t = -\frac{\vec{F}_{21}}{m_1} = -\frac{kq_1 q_2}{m_1 r^2} \hat{r}$$

因此非惯性系中 q_2 的受力情况为

$$\vec{F}'_{12} = m_2 \vec{a}_t + \vec{F}_{12} = -\frac{kq_1 q_2 m_2}{r^2} \left(\frac{1}{m_1} + \frac{1}{m_2} \right) \hat{r}$$

类比引力情形，点电荷的运动相当于引力为 $-\frac{GMm_2}{r^2} = -\frac{kq_1 q_2 m_2}{r^2} \left(\frac{1}{m_1} + \frac{1}{m_2} \right)$ ，半长轴 $a = \frac{r_0}{2}$ ，半短轴 $b = 0$ ，半焦距 $a = \frac{r_0}{2}$ 的行星运动（如图）。



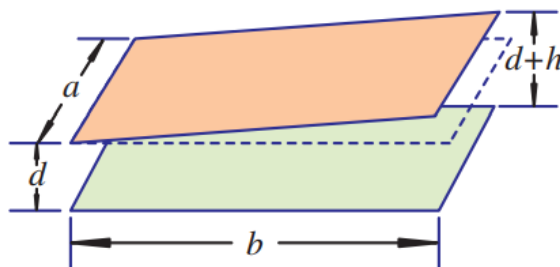
由开普勒第三定律：

$$T = 2\pi \sqrt{\frac{a^3}{GM}} = 2\pi \sqrt{\frac{\left(\frac{r_0}{2}\right)^3}{kq_1q_2\left(\frac{1}{m_1} + \frac{1}{m_2}\right)}} = \pi r_0 \sqrt{\frac{2\pi\epsilon_0 r_0^3}{q_1q_2\left(\frac{1}{m_1} + \frac{1}{m_2}\right)}}$$

$$\text{因此从静止到相遇时间为 } t = \frac{T}{2} = \frac{\pi r_0}{2} \sqrt{\frac{2\pi\epsilon_0 r_0}{q_1q_2\left(\frac{1}{m_1} + \frac{1}{m_2}\right)}}$$

2.9（并联，题目有瑕疵）

两块长与宽均为 a 和 b 的导体平板在制成平行板电容器时稍有偏斜,使两板间距一端为 d ,另一端为 $d+h$,且 $h \ll d$,求该电容器的电容。



方法一*：平行导体板的叠加

将稍有倾斜的导体板电容器视为无数长 a 宽 dx 相距 $d + \frac{x}{b}h$ 的平行导体板电容器的并联。注意无法视为导线的叠加，否则计算中引入无穷大，而这要求 $h \ll b$ 。由此：

$$C = \int dC = \int_0^b \frac{\epsilon_0 a dx}{d + \frac{x}{b}h} = \frac{\epsilon_0 ab}{h} \ln\left(1 + \frac{h}{d}\right)$$

宽相对极板距离过窄的情况下，电容器一般无法忽略边缘效应。因此要求 $h \ll d \ll dx \ll b$

方法二*：计算电荷量

导体板的面电荷未必是均匀分布的，但电势一定是定值。可以给定两极板的电势差值，计算导体板的总电荷，从而得到电容。

两极板延长线的交点 O 为原点，建立柱坐标系。下极板上表面的位置为 $\theta = 0$ 。简单计算可得下极板左边缘位置为 $r_e = \frac{bd}{h}$

假定下极板电势为 0 ，上极板电势为 U 。利用高斯定理配合电势进行计算，由对称性（忽略边缘效应）， $U = U(r, \theta)$ 。

$$\nabla \cdot \vec{E} = -\nabla^2 U = 0$$

边界条件为：

$$U|_{\theta=0} = 0$$

$$U|_{\theta=\arctan \frac{h}{b}} = U$$

得到 Laplace 方程边值问题

$$\begin{cases} \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial U}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 U}{\partial \theta^2} = 0 \\ U|_{\theta=0} = 0 \\ U|_{\theta=\arctan \frac{h}{b}} = U \end{cases}$$

分离变量 $U = R(r)\theta(\theta)$ ，分离得常微分方程组：

$$\begin{cases} \theta'' + \mu\theta = 0 \\ r(rR')' - \mu R = 0 \end{cases}$$

θ 的常微分方程解得

$$\mu_n = n^2, \quad n = 0, 1, 2, \dots$$

$$\theta_m(\theta) = \begin{cases} A_n + B_n \theta, & n = 0 \\ A_n \cos n\theta + B_n \sin n\theta, & n = 1, 2, 3, \dots \end{cases}$$

对于 R 的常微分方程，设 $r = e^t$ 。则

$$\frac{d^2 R}{dt^2} - n^2 R = 0$$

解得

$$R_n(\theta) = \begin{cases} C_n + D_n \ln r, & n = 0 \\ C_n r^n + D_n r^{-n}, & n = 1, 2, 3, \dots \end{cases}$$

$$\begin{aligned} \therefore U(r, \theta) = & A'_0 + B_0 \theta + (C'_0 + D'_0 \theta) \ln r \\ & + \sum_{n=1}^{\infty} [(A'_n \cos n\theta + B'_n \sin n\theta) r^n + (C'_n \cos n\theta + D'_n \sin n\theta) r^{-n}] \end{aligned}$$

代入边值条件 $U|_{\theta=0} = 0$:

$$A'_0 + (C'_0 + D'_0 \theta) \ln r + \sum_{n=1}^{\infty} [A'_n r^n + C'_n r^{-n}] = 0$$

得到 $A'_n = 0$; $C'_n = 0$; $D'_0 = 0$ 。代入边值条件 $U|_{\theta=\arctan \frac{h}{b}} = U$:

$$B_0 \arctan \frac{h}{b} + \sum_{n=1}^{\infty} \left[B'_n \sin n \arctan \frac{h}{b} r^n + D'_n \sin n \arctan \frac{h}{b} r^{-n} \right] = U$$

得到 $B_0 = \frac{U}{\arctan \frac{h}{b}}$, $B'_n = 0$ ($n \neq 1$); $D'_n = 0$ ($n \neq 1$)。因此:

$$U(r, \theta) = U(\theta) = \frac{U \theta}{\arctan \frac{h}{b}}$$

$$\vec{E} = -\nabla U = -\frac{1}{r} \frac{\partial U}{\partial \theta} \hat{\theta} = -\frac{U}{r \arctan \frac{h}{b}} \hat{\theta}$$

下极板上表面 $(r_0, 0, z)$ 处取一微小柱形高斯面，高平行 $\hat{\theta}$ 方向，上下底面面积为 dS 。可得

$$-\frac{U}{r \arctan \frac{h}{b}} dS = \frac{\sigma_e(r) dS}{\epsilon_0}$$

$$\therefore \sigma_e(r) = -\frac{\epsilon_0 U}{r \arctan \frac{h}{b}}$$

$$\therefore Q = \iint_S \sigma_e(r) dS = \int_0^a dz \int_{r_e}^{r_e+b} -\frac{\epsilon_0 U}{r \arctan \frac{h}{b}} dr = -\frac{\epsilon_0 U a \ln \left(1 + \frac{h}{d}\right)}{\arctan \frac{h}{b}}$$

$$\therefore C = \frac{Q}{0 - U} = \frac{\epsilon_0 a \ln \left(1 + \frac{h}{d}\right)}{\arctan \frac{h}{b}} \approx \frac{\epsilon_0 ab}{h} \ln \left(1 + \frac{h}{d}\right)$$

2.15 (球面电荷的等效电偶极矩。题目有瑕疵)

水分子是有极分子，一个水分子的电偶极矩为 $0.61 \times 10^{-30} \text{ C} \cdot \text{m}$ ，若所有的水分子电矩都朝同一方向，(1) 试估算水的极化强度；(2) 直径为 1 mm 的水滴的电偶极矩有多大？距水 10 cm 处的电场强度有多大？

(1) 水的摩尔质量 $M = 18.0152 \text{ g}$ ，密度 $\rho \approx 1.00 \times 10^3 \text{ g/m}^3$

$$P = np = \frac{\rho N_A}{M} p = 2.04 \times 10^{-2} \text{ C/m}^2$$

(2) 该处电场为所有电偶极子产生电场的叠加（同方向可直接叠加，相反方向可能为多极子）。总电偶极矩 p_d 为：

$$p_d = VP = \frac{\pi d^3}{6} P = 1.07 \times 10^{-11} \text{ C} \cdot \text{m}$$

题目未给出电偶极矩与位置矢量的方向，而电偶极子产生的电场与方向有

关。若10 cm位置垂直电偶极矩方向，则

$$E = \frac{p_d}{4\pi\epsilon_0 r^3} = 9.62 \times 10 \text{ C/m}^2$$

若10 cm位置平行电偶极矩方向，则

$$E = \frac{p_d}{2\pi\epsilon_0 r^3} = 1.92 \times 10^2 \text{ C/m}^2$$

计算总电偶极矩 p_d 时，也可用球面电荷计算等效电偶极矩，但这只会徒增计算量：

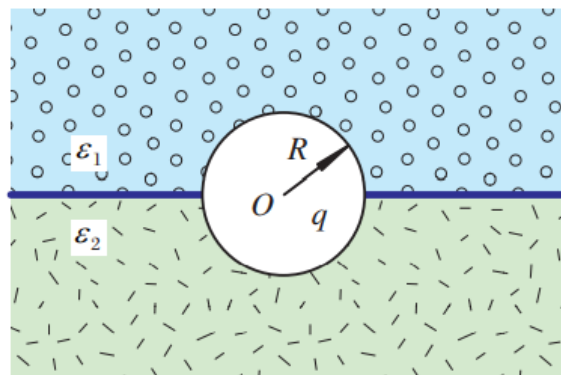
$$\sigma_e = \hat{r} \cdot (\vec{0} - \vec{P}) = -P \cos \theta$$

$$\begin{aligned} \vec{p}_d &= \oint_{\partial V} \sigma_e 2R \cos \theta dS (-\hat{z}) = - \int_0^{2\pi} d\varphi \int_0^\pi \sigma_e 2R \cos \theta R^2 \sin \theta d\theta \hat{z} \\ &= 2\pi R^3 \vec{P} \int_0^\pi \cos^2 \theta \sin \theta d\theta = \frac{4\pi R^3}{3} \vec{P} \\ &= 1.07 \times 10^{-11} \text{ C} \cdot \text{m} \end{aligned}$$

(

2.22 (介质面平行电场线)

2.36 如图所示，一导体球外充满两半无限电介质，介电常量分别为 ϵ_1 和 ϵ_2 ，介质界面为通过球心的无限平面。设导体球半径为 R ，总电荷为 q ，求空间电场分布和导体球表面的自由面电荷分布。



习题 2.36 图

杨国桢《电磁学与电动力学（上）》P57）介质界面与（无介质时的）电场线重合，极化电荷只可能分布在介质与导体的边界面上。从结果上说，介质与导体的边界面的总电荷分布与无介质时导体边界面上的电荷分布相同

介质界面与（无介质时的）电场线垂直，从结果上来说，有

$$\vec{E}_i = \frac{\epsilon_0 \vec{E}_0}{\epsilon_i}$$

$\vec{E}_0$ 是无介质情形的电场。但没必要使用该结论，直接先计算 $\vec{D}$ 再计算 $\vec{E}_i$ 即可（2.16）

介质界面处，电场强度的切向分量相等。而电场平行于介质界面，因此界面两侧电场强度相等。可见电场强度应当仍然满足一维对称分布，边界面总电荷均匀分布。由电位移矢量的高斯定理：

$$2\pi r^2 D_1 + 2\pi r^2 D_2 = 2\pi r^2 \epsilon_1 E + 2\pi r^2 \epsilon_2 E = q$$

$$\therefore \vec{E} = \frac{q}{2\pi(\epsilon_1 + \epsilon_2)r^2} \hat{r}$$

[2.1] 第一章习题 (1)

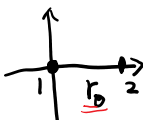
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△ 第一章: [公式分为同类量与非同类量]

1.2. SI: 量: $F = k \frac{q_1 q_2}{r^2}$ $[kg \cdot m/s^2] = 9 \times 10^9 \frac{[C^2]}{[m^2]}$
 $\therefore [C] = \frac{[kg \cdot m^3]}{9 \times 10^9 [s^2]}$ 设 $[C] = X \text{esu}$ ✓
 $\frac{1}{X^2} = \frac{10^{-9}}{9 \times 10^9}$ $\textcircled{1} C \rightarrow X \text{esu} \rightarrow \frac{1}{X} [esu]$
 $\therefore X = 3 \times 10^9$

数+基 [同类量]: $1kg = 1000g$ 代换 (全) $1kg \rightarrow 1000g$
 数 [不同类量]: $1[m] = 5[h]$ 代换 (仅数) $1[h] \rightarrow 10^{-5}[g]$

1.8 两体问题: $\frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r^2} = \mu \frac{d^2 r}{dt^2}$ G, m_1, m_2
 $r(0) = r_0, v(0) = 0$



$\therefore \ddot{r} + \beta \cdot \frac{1}{r^2} = 0$, 其中 $\beta = \frac{q_1 q_2}{4\pi\epsilon_0 \mu}$

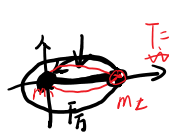
由 $\frac{dr}{dt} = \frac{dr}{dr} \cdot \dot{r}$, $\frac{dr}{dt} \cdot \dot{r} = \dot{r}^2$

$\therefore \dot{r} dr = \beta \frac{dr}{r^2} \Rightarrow \frac{1}{2} \dot{r}^2 = \beta \frac{1}{r} + C$

$\therefore 0 = \beta \frac{1}{r_0} + C \Rightarrow C = -\beta \frac{1}{r_0}$

$\therefore \dot{r} = -\sqrt{2\beta \left(\frac{1}{r} - \frac{1}{r_0} \right)}$ $r(t)?$

$\therefore dt = -\frac{dr}{\left[2\beta \left(\frac{1}{r} - \frac{1}{r_0} \right) \right]^{1/2}} \quad (0 < r < r_0) \Rightarrow t = \frac{1}{\sqrt{2\beta}} \cdot \frac{\pi}{2} r_0^{3/2}$



$T = 2\pi \sqrt{\frac{a^3 m_1}{G M m_1}}$

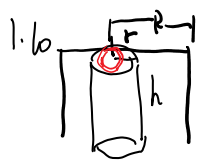
$T = 2\pi \sqrt{\frac{a^3 m_2}{G M m_2}}$

$a = \frac{r_0}{2}$
 $\therefore t = \frac{T}{2}$ ✓

类比退化椭圆: $-\frac{GMm}{r^2} = m\ddot{r} \Rightarrow \ddot{r} + GM \frac{1}{r^2} = 0$ $T = 2\pi \sqrt{\frac{a^3}{GM}}$ ✓

则此题中, $GM \rightarrow \beta$, $a \rightarrow \frac{r_0}{2}$

$\therefore t = \frac{T}{2} = \pi \sqrt{\frac{4\pi\epsilon_0 k_0^3 \mu}{8 q_1 q_2}} = \pi \sqrt{\frac{\pi\epsilon_0 r_0^3 \mu}{2 q_1 q_2}}$ ✓

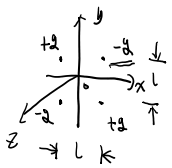


$r < R, E \cdot 2\pi r h = \frac{\iiint \rho dv}{\epsilon_0} = \frac{1}{\epsilon_0} \int_0^r \int_0^{2\pi} \int_0^h (a r^2 - b r^4) r dr d\theta dz$
 $= \frac{2\pi h}{\epsilon_0} \int_0^r (a r^2 - b r^4) dr$
 $= \frac{2\pi h}{\epsilon_0} \cdot \left(\frac{a}{3} r^3 - \frac{b}{5} r^5 \right)$

$\therefore E = -\frac{b}{5\epsilon_0} r^4 + \frac{a}{3\epsilon_0} r^2$

$$\therefore E = -\frac{b}{5\epsilon_0} r^4 + \frac{a}{3\epsilon_0} r^2$$

$$r > R: E = \left(-\frac{b}{5\epsilon_0} R^5 + \frac{a}{3\epsilon_0} R^3 \right) \frac{1}{r}.$$

1.15. 法: $Q=0$ 

$$\vec{P} = \sum_{i=1}^4 q_i \vec{r}_i = -q \left(\frac{l}{2} \hat{x} \right) + q \left(-\frac{l}{2} \hat{x} \right) - q \left(\frac{l}{2} \hat{y} \right) + q \left(-\frac{l}{2} \hat{y} \right) + q \left(\frac{l}{2} \hat{z} \right) + q \left(-\frac{l}{2} \hat{z} \right) = 0 \text{ V}$$

$$\begin{aligned} D &= \sum_{i=1}^4 q_i (3\vec{r}_i \vec{r}_i - r_i^2 \hat{I}) = -q \left[\frac{3l^2}{4} (\hat{x}\hat{x} + \hat{y}\hat{y} + \hat{z}\hat{z}) - \frac{l^2}{4} \hat{I} \right] \\ &\quad + q \left[\frac{3l^2}{4} (\hat{x}\hat{x} - \hat{x}\hat{y} - \hat{y}\hat{x} + \hat{y}\hat{y}) - \frac{l^2}{4} \hat{I} \right] \\ &\quad - q \left[\frac{3l^2}{4} (\hat{x}\hat{x} + \hat{x}\hat{y} + \hat{y}\hat{x} + \hat{y}\hat{y}) - \frac{l^2}{4} \hat{I} \right] \\ &\quad + q \left[\frac{3l^2}{4} (\hat{x}\hat{x} - \hat{x}\hat{y} - \hat{y}\hat{x} + \hat{y}\hat{y}) - \frac{l^2}{4} \hat{I} \right] \\ &= \frac{3ql^2}{4} (-4\hat{x}\hat{y} - 4\hat{y}\hat{x}) \\ &= -3ql^2 (\hat{x}\hat{y} + \hat{y}\hat{x}) \quad \star \end{aligned}$$

$$\begin{aligned} \therefore \varphi &= \frac{1}{4\pi\epsilon_0 r^3} D: \hat{r}\hat{r} = -\frac{3ql^2}{8\pi\epsilon_0} \cdot \frac{1}{r^3} (\hat{x}\hat{y}: \hat{r}\hat{r} + \hat{y}\hat{x}: \hat{r}\hat{r}) \\ &= -\frac{3ql^2}{4\pi\epsilon_0} \cdot \frac{1}{r^3} \cdot \sin\theta \sin\varphi \cos\varphi \end{aligned}$$

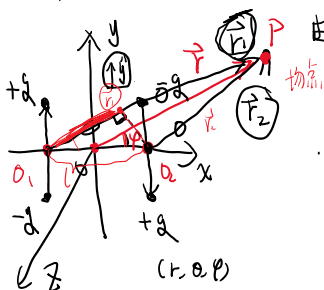
$$\begin{aligned} \therefore \vec{E} &= -\nabla\varphi = \frac{3ql^2}{4\pi\epsilon_0} \left(\frac{\partial}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial}{\partial \theta} \hat{\theta} + \frac{1}{r \sin\theta} \frac{\partial}{\partial \varphi} \hat{\varphi} \right) \left(-\frac{1}{r^3} \sin\theta \sin\varphi \cos\varphi \right) \\ &= \frac{3ql^2}{4\pi\epsilon_0} \left[-\frac{3}{r^4} \sin^2\theta \sin\varphi \cos\varphi \hat{r} + \frac{1}{r^4} \sin\varphi \cos\varphi \sin\theta \cos\theta \hat{\theta} + \frac{1}{r^4} \sin\theta \cos\varphi \hat{\varphi} \right] \\ &= \frac{3ql^2}{4\pi\epsilon_0} \cdot \frac{1}{r^4} \left[-\frac{3}{2} \sin^2\theta \sin 2\varphi \hat{r} + \frac{1}{2} \sin 2\theta \sin 2\varphi \hat{\theta} + \sin\theta \cos\varphi \hat{\varphi} \right] \end{aligned}$$

★ 取 $\theta = \frac{\pi}{2}$, 则 XOY 平面

$$\varphi_{xy} = -\frac{3ql^2}{8\pi\epsilon_0} \cdot \frac{1}{r^2} \sin 2\varphi$$

$$\vec{E}_{xy} = \frac{3ql^2}{4\pi\epsilon_0} \cdot \frac{1}{r^4} \left[-\frac{3}{2} \sin 2\varphi \hat{\theta} + \cos\varphi \hat{\varphi} \right]$$

法: 看作两个电偶极子.



由图, $\vec{r}_1 = \vec{r} + \frac{l}{2} \hat{x}$, $\vec{r}_2 = \vec{r} - \frac{l}{2} \hat{x}$

$$\begin{aligned} \varphi_1(\vec{r}_1) &= \frac{1}{4\pi\epsilon_0} \frac{\vec{p}_1 \cdot \vec{r}_1}{r_1^3} \\ \varphi_2(\vec{r}_2) &= \frac{1}{4\pi\epsilon_0} \frac{\vec{p}_2 \cdot \vec{r}_2}{r_2^3} \end{aligned}$$

$$\therefore \varphi(\vec{r}) = \varphi_1(\vec{r}_1) + \varphi_2(\vec{r}_2)$$

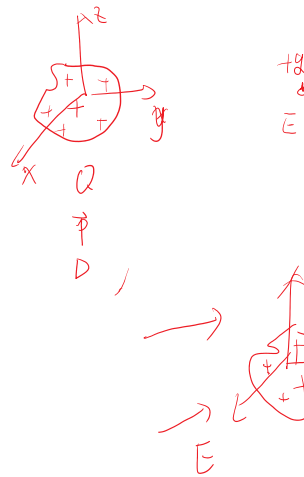
$$= \frac{ql}{4\pi\epsilon_0} \left(\frac{\hat{y} \cdot \vec{r}_1}{r_1^3} - \frac{\hat{y} \cdot \vec{r}_2}{r_2^3} \right)$$

$$= \frac{ql}{4\pi\epsilon_0} \left(\frac{1}{r_1^3} - \frac{1}{r_2^3} \right)$$

$$= \frac{ql}{4\pi\epsilon_0} \cdot \frac{r_2^3 - r_1^3}{r_1^3 r_2^3} \quad \rightarrow (r_2 - r_1)(r_2^2 + r_2 r_1 + r_1^2)$$

$$\approx \frac{ql}{4\pi\epsilon_0} \frac{3r^2(r_2 - r_1)}{r^6} = \frac{3ql}{4\pi\epsilon_0} \cdot \frac{y}{r^4} (r_2 - r_1) = \frac{3ql}{4\pi\epsilon_0} \cdot \frac{1}{r^5} \cdot \frac{y}{r} \cdot (r_2 - r_1)$$

$$= \frac{y}{r^5} \sin\theta \sin\varphi$$



注: 直接.

$$\approx \frac{qL}{4\pi\epsilon_0} \frac{3r^2(r_2-r_1)}{r^6} = \frac{3qL}{4\pi\epsilon_0} \cdot \frac{y}{r^4} (r_2-r_1) = \frac{3qL}{4\pi\epsilon_0} \cdot \frac{1}{r^3} \cdot \underline{\underline{y}} \cdot (r_2-r_1)$$

$$= -\frac{3qL}{4\pi\epsilon_0} \cdot \frac{1}{r^3} \sin\theta \sin\varphi \cos\varphi \quad (x\text{-轴: } \theta = \frac{\pi}{2})$$

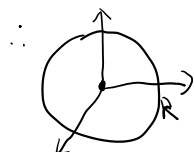
$\vec{E} = -\nabla\varphi$

$$y = r \sin\theta \sin\varphi$$

$$= \frac{y}{r} = \sin\theta \sin\varphi \quad \checkmark$$

$$r_2 - r_1 = -l \cos\varphi$$

1.2 | $\rho = \rho_0 \frac{e^{-kr}}{r}$



$$\oint \vec{E} \cdot d\vec{r} = \frac{1}{\epsilon_0} \int \rho dV = \frac{\rho_0}{\epsilon_0} \int_0^R \int_0^\pi \int_0^{2\pi} \frac{e^{-kr}}{r} \cdot r^2 \sin\theta dr d\theta d\varphi$$

$$= \frac{4\pi\rho_0}{\epsilon_0} \int_0^R r e^{-kr} dr$$

$$= \frac{4\pi\rho_0}{\epsilon_0} \left[-\frac{1}{k} r e^{-kr} + \frac{1}{k} \int_0^R e^{-kr} dr \right]$$

$$= \frac{4\pi\rho_0}{k\epsilon_0} \left[-R e^{-kR} - \frac{1}{k} (e^{-kR} - 1) \right]$$

$$\therefore \vec{E}(\vec{r}) = \frac{\rho_0}{k\epsilon_0} \left[-\frac{e^{-kr}}{R} - \frac{1}{k} \cdot \frac{e^{-kr} - 1}{R^2} \right] \hat{r}$$

1.24. 无旋场有势.

$$\vec{E} = \frac{kq}{r^3} \hat{r}$$

$$\nabla \times \vec{E} = \frac{1}{r^2 \sin\theta} \begin{vmatrix} \hat{r} & r\hat{\theta} & r\sin\theta\hat{\varphi} \\ \partial_r & \partial_\theta & \partial_\varphi \\ \frac{kq}{4\pi\epsilon_0} \frac{1}{r^3} & 0 & 0 \end{vmatrix}$$

$$= 0$$

$\therefore$ 有势. 设 $\vec{E} = -\nabla\varphi$ $\varphi - \varphi_0 = \int_{r_0}^r \vec{E} \cdot d\vec{r}$

$$\therefore \varphi(r) = \int_{\infty}^r \vec{E} \cdot d\vec{r} = \int_{\infty}^r \frac{kq}{4\pi\epsilon_0 r^3} dr = \frac{kq}{2\pi\epsilon_0 r^2} \quad (\text{设 } \varphi(\infty) = 0)$$

此时 Gauss 定理不适用. $\left[\nabla \cdot \frac{1}{r^2} = 4\pi\delta(\vec{r}) \right]$

$$\therefore \varphi(r) = \iint \frac{kq(\vec{r}-\vec{r}') \cdot d\vec{s}'}{|\vec{r}-\vec{r}'|^3} \quad (-\text{包围})$$

$$= \frac{k}{4\pi\epsilon_0} \int_0^{2\pi} \int_0^\pi \frac{r^2 \sin\theta}{(r^2+z^2)^{3/2}} d\theta d\varphi$$

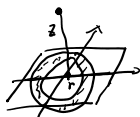
$$= \frac{k\pi}{2\epsilon_0} \int_0^{2\pi} \frac{d\varphi}{1+z^2/r^2}$$

$$= \frac{k\pi}{2\epsilon_0} \ln(r^2+z^2) \Big|_0^{2\pi}$$

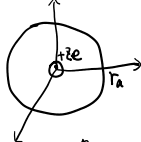
$$= \frac{k\pi}{2\epsilon_0} (\ln 2\pi - \ln z^2)$$

$$= \frac{k\pi}{2\epsilon_0} \ln 2\pi + \frac{k\pi}{2\epsilon_0} \ln(z^2)$$

(不影响 $\vec{E}$)



1.30. 带电密度 $\rho = \frac{Ze}{4\pi r^3}$



$$\therefore r < a \text{ 时, } \varphi = \frac{1}{4\pi\epsilon_0} \frac{Ze}{r} + \frac{1}{4\pi\epsilon_0} \frac{\rho_0 r^2}{r} + \frac{1}{4\pi\epsilon_0} \iint \frac{\rho(r')}{|\vec{r}-\vec{r}'|} dV' \quad (-\text{包围})$$

$$= \frac{1}{4\pi\epsilon_0} \left(\frac{Ze}{r} - \frac{Ze r'}{r^3} + \frac{Ze}{8\pi\epsilon_0} \cdot \int_0^a \int_0^\pi \int_0^{2\pi} \frac{r' \sin\theta}{[r^2+r'^2-2rr'(\cos\theta\cos\theta' + \sin\theta\sin\theta'\cos(\varphi-\varphi'))]^{3/2}} d\theta d\varphi d\varphi' \right)$$

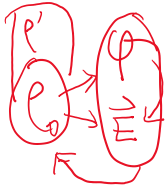
$$= \frac{Ze}{4\pi\epsilon_0} \left(\frac{1}{r} - \frac{r'}{r^3} + \frac{3}{2r^2} \right) \quad \therefore \vec{E}$$

$$\therefore \vec{E} = -\nabla\varphi = \frac{Ze}{4\pi\epsilon_0} \left(\frac{1}{r^2} - \frac{r'}{r^3} \right) \vec{e}_r$$

☆ PPT, 例 1-2-5, 电偶极子. (题目有问题?)

☆ PPT, 例 1-2-4, 导体给出 ρ_0 后, 不管它了.

★ PP7, 例 1-2-4, 导体给出 ρ_0 后, 不管它了.



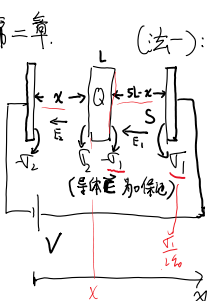
★ 带电体:

(1) 静电场: $\varphi(r) = \frac{1}{4\pi\epsilon_0} \left(\frac{Q}{r} + \frac{\vec{p} \cdot \hat{r}}{r^2} + \frac{D \cdot \hat{r} \hat{r}}{2r^3} + \dots \right)$

(2) 外电场中: $\vec{E}_p = Q\varphi(\vec{r}_0) - \vec{p} \cdot \vec{E} - \frac{1}{6} D \cdot \nabla \vec{E} + \dots$

△ 第=章

2.2



(法一):

$$Q = \frac{\epsilon_0 S}{L} V$$

$$(\sigma_1 - \sigma_2)S = Q \quad (1)$$

$$\frac{\sigma_1}{\epsilon_0} (5L - x) + \frac{\sigma_2}{\epsilon_0} x = V \quad (2)$$

$$\sigma_1 = -\frac{\epsilon_0 V}{5L} x + \frac{\epsilon_0 V}{5L}$$

$$\sigma_2 = -\frac{\epsilon_0 V}{5L} x + \frac{11\epsilon_0 V}{30L}$$

(净电荷在左板上)

$$F_Q = -\frac{\sigma_1}{2\epsilon_0} \cdot (-\sigma_1 S) - \frac{\sigma_2}{2\epsilon_0} \cdot \sigma_2 S \quad (\text{自身的电荷对自身无作用})$$

$$= \frac{\epsilon_0 S V^2}{180L^3} x - \frac{11\epsilon_0 S V^2}{360L^2}$$

$$\therefore W_{F_Q} = -W_Q = -\int_L^{5L} F_Q dx = \frac{13\epsilon_0 S V^2}{180L}$$

(法二): $dW_{\text{外}} + dW_{\text{电源}} = dE_p$ (不可行, 因电荷移动)

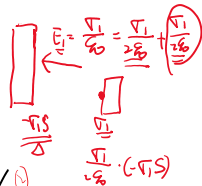
$$E_p = \frac{1}{2} \cdot \frac{5L-x}{\epsilon_0 S} \cdot (\sigma_1 S)^2 + \frac{1}{2} \cdot \frac{x}{\epsilon_0 S} \cdot (\sigma_2 S)^2$$

$$= \frac{\epsilon_0 S V^2}{180L^2} \left[(5L-x) \left(-\frac{x}{L} + 6\right)^2 + x \left(-\frac{x}{L} + 11\right)^2 \right]$$

$$= \frac{\epsilon_0 S V^2}{180L^2} \left(-\frac{5}{L} x^2 + 25x + 180L \right)$$

$$= -\frac{\epsilon_0 S V^2}{360L^2} (x^2 - 5Lx - 36L^2)$$

$$\therefore F_Q' = -\frac{\partial E_p}{\partial x} = \frac{\epsilon_0 S V^2}{360L^2} (2x - 5L) \neq F_Q$$



$$\left[(5L-x) \frac{\epsilon_0 V^2}{90L^2} \left(-\frac{x}{L} + 6\right)^2 + x \cdot \frac{\epsilon_0 V^2}{90L^2} \left(-\frac{x}{L} + 11\right)^2 \right]$$

$$\frac{S}{2\epsilon_0} \cdot \frac{\epsilon_0^2 V^2}{90L^2}$$

$$\frac{\epsilon_0 S V^2}{180L^2}$$

$$F_p(L)$$

$$= -\frac{\epsilon_0 S V^2}{360L^2}$$

$$(L^2 - 5L^2 - 36L^2)$$

$$= -\frac{\epsilon_0 S V^2}{9L}$$

$$F_p(3L)$$

$$= -\frac{\epsilon_0 S V^2}{360L^2}$$

$$(9L^2 - 15L^2 - 36L^2)$$

$$= -\frac{74\epsilon_0 S V^2}{360L}$$

$$\frac{10+21}{180}$$

$$\frac{10+21}{180}$$

$$\frac{S}{2\epsilon_0} \left[(5L-x) \sigma_1^2 + x \sigma_2^2 \right]$$

$$= \frac{S}{2\epsilon_0} \left[\right]$$

$$(5L-x) \left(\frac{x^2}{L^2} - \frac{12x}{L} + 36 \right)$$

$$= -\frac{1}{L^2} x^3 + \frac{12}{L} x^2 - 36x + \frac{5}{L} x^2 - 60x + 180L$$

$$= -\frac{1}{L^2} x^3 + \frac{17}{L} x^2 - 96x + 180L$$

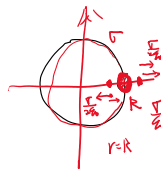
$$x \left(\frac{1}{L^2} x^2 - \frac{2}{L} x + 14 \right)$$

$$= \frac{1}{L^2} x^3 - \frac{2}{L} x^2 + 14x$$

$$\therefore -\frac{5}{L} x^2 + 25x + 180L$$



$$E = \frac{V}{2\epsilon_0}$$



$$E = \begin{cases} 0, & r < R \\ \frac{Q}{2\epsilon_0 L}, & r > R \end{cases}$$

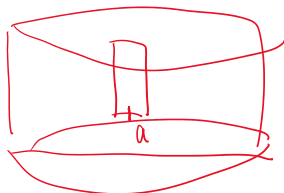
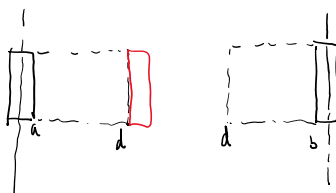
$$r = R, E = \frac{V}{2\epsilon_0} \quad (\text{因为 } r=R \text{ 很薄})$$

$$\begin{cases} F \\ E_p \end{cases}$$

$$E = \begin{cases} \frac{V}{2\epsilon_0}, & r > R \\ 0, & r < R \end{cases}$$

2.5. 看做两个电容器并联:

$$C_1 = \frac{2\pi\epsilon_0}{\ln \frac{a}{b}}, \quad C_2 = \frac{2\pi\epsilon_0}{\ln \frac{a}{b}}$$

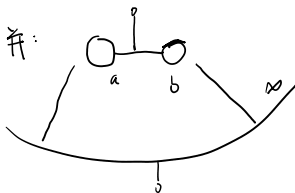


$$\therefore C = [C_1^{-1} + C_2^{-1}]^{-1} = \frac{2\pi\epsilon_0}{\ln \frac{a}{b}}$$

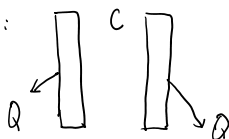
$$2.6 \quad C_1 = 4\pi\epsilon_0 a, \quad C_2 = 4\pi\epsilon_0 b$$

(1) 串: $\circ - \bigcirc_a - \bigcirc_b - \circ$
地 月

$$C = \left[\frac{1}{4\pi\epsilon_0 a} + \frac{1}{4\pi\epsilon_0 b} \right]^{-1} = 4\pi\epsilon_0 \frac{ab}{a+b}$$

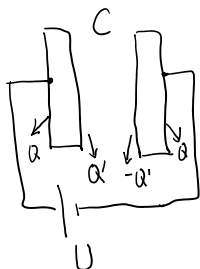
(2) 并:  $C = 4\pi\epsilon_0 (a+b)$

2.7 充电前:



内极板上无电荷, 内无电场.

充电后:

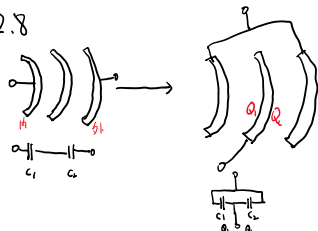


$$Q' = CU$$

$\therefore$ 总电量: 左 $Q + CU$

右 $Q - CU$

2.8



$$\therefore C = C_1 + C_2 = 4\pi\epsilon_0 \left[\frac{ab}{b-a} + \frac{bd}{d-b} \right]$$

当 $Q_1 + Q_2 = Q$ 时,

有 $\frac{Q_1}{C_1} = \frac{Q_2}{C_2}$

$$\therefore Q_1 = \frac{a(d-b)}{d(b-a) + a(d-b)} Q \quad (a)$$

$$Q_2 = \frac{d(b-a)}{d(b-a) + a(d-b)} Q \quad (b)$$

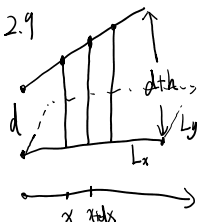
$$Q_2 = Q - Q_1$$

$$\frac{Q_1}{Q - Q_1} = \frac{a(d-b)}{b-a} \cdot \frac{d-b}{bd} = \frac{a(d-b)}{d(b-a)}$$

$$\therefore d(b-a)Q_1 = a(d-b)(Q - Q_1)$$

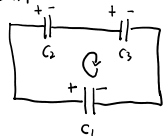
$$\therefore Q_1 = \frac{a(d-b)}{d(b-a) + a(d-b)} Q$$

2.9



$$\begin{aligned} C &= \int_0^{L_x} dC = \int_0^{L_x} \frac{\epsilon_0 L_y}{d + \frac{h}{L_x} x} dx \\ &= \frac{\epsilon_0 L_x L_y}{h} \ln \left(d + \frac{h}{L_x} x \right) \Big|_0^{L_x} \\ &= \frac{\epsilon_0 L_x L_y}{h} \ln \frac{d+h}{d} \end{aligned}$$

2.11 "电路"



$$\therefore \begin{cases} Q_1 + Q_2 = C_1 V_0 \\ -Q_1 - Q_3 = -C_1 V_0 \\ -\frac{Q_1}{C_1} + \frac{Q_2}{C_2} + \frac{Q_3}{C_3} = 0 \end{cases}$$

$$\therefore Q_1 = \frac{2C_1 V_0}{2C_1 + C_2}$$

$$Q_2 = Q_3 = \frac{C_2 C_3 V_0}{2C_1 + C_2}$$

$$Q_1 = Q_3$$

$$\frac{Q_1}{C_1} = \frac{2Q_2}{C_2}$$

$$Q_1 = \frac{2C_1}{C_2} Q_2$$

$$\left(1 + \frac{2C_1}{C_2} \right) Q_2 = C_1 V_0$$

$$Q_2 = \frac{C_1 C_2 V_0}{2C_1 + C_2}$$

$$\therefore U_1 = \frac{C_1 V_0}{2C_1 + C_2}$$

$$Q_2 = Q_1 = \frac{C_1 C_2 V_0}{2C_1 + C_2}$$

$$\left(1 + \frac{C_1}{C_2}\right) U_2 = C_2 V_0$$

$$U_2 = \frac{C_1 C_2 V_0}{2C_1 + C_2}$$

$$Q_1 = \frac{2C_1^2 V_0}{2C_1 + C_2}$$

$$2.14. \begin{cases} \frac{Q_1}{\epsilon_1} \phi_1' + C \phi_2 = Q_1 \\ \frac{Q_2}{\epsilon_2} \phi_2' - C \phi_1 = Q_2 \end{cases} \Rightarrow \phi_1' - \phi_2' = \frac{Q_2 (Q_1 - Q_2)}{Q_1 Q_2 + C Q_1 Q_2 + C^2 Q_1 Q_2}$$

2.16, 2.20, 2.21, 2.22 分区均匀介质:

1 // 分界面: 用 $\vec{E}$ (判断 E 连续性) $[E \text{ (总场)} = E_0 + E']$
 2 分界面: 用 $\vec{D}$

(1)  求 $\vec{D}, \vec{E}$ ($R_1 < r < R_2$)

由对称性, E 均匀, D 均匀

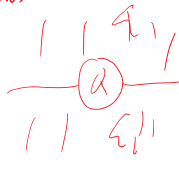
$\therefore E \cdot 2\pi r = \frac{Q_0}{\epsilon_1}$ $E = \frac{Q_0}{2\pi \epsilon_1 r}$ $D = \epsilon_1 E = \frac{Q_0}{2\pi r}$

$\therefore (E_1 + E_2) \cdot 2\pi r = Q_0$ $E_1 E = \frac{Q_0}{2\pi r}$ $\Rightarrow D \cdot 2\pi r = Q_0$

$\therefore \vec{E} = \frac{Q_0}{2\pi \epsilon_1 \epsilon_2 r} \frac{1}{r} \hat{r}$ ($R_1 < r < R_2$)

$\therefore \vec{D} = \epsilon_1 \vec{E} = \frac{Q_0}{2\pi r} \frac{1}{r} \hat{r}$

$\vec{E}_2 = \epsilon_2 \vec{E} = \frac{Q_0}{2\pi \epsilon_2 r} \frac{1}{r} \hat{r}$



(2)  求 $\vec{D}, \vec{E}$?

由对称性, E 均匀, D 均匀

$\therefore D \cdot 4\pi r^2 = Q_0$

$\therefore D = \frac{Q_0}{4\pi r^2}$

$\therefore E = \frac{D}{\epsilon_1} = \frac{Q_0}{4\pi \epsilon_1 r^2}$

$\vec{E}_2 = \frac{D}{\epsilon_2} = \frac{Q_0}{4\pi \epsilon_2 r^2}$

2.28. a) ϵ_1 时
 ϵ_2 时
导体球

2.41 (1) $Q = C V_{AB}$

随穿前后, 能量减小.

① $e^-: B \rightarrow A$

$$\Delta W = \frac{1}{2C} (Q-e)^2 - \frac{1}{2C} Q^2 < 0$$

$$\therefore 2Q - e > 0$$

$$\text{即 } Q > \frac{e}{2}$$

$$\therefore V_{AB} > \frac{e}{2C}$$

$$\text{② } e^-: A \rightarrow B$$

$$\Delta W = \frac{1}{2C} (Q+e)^2 - \frac{1}{2C} Q^2 < 0$$

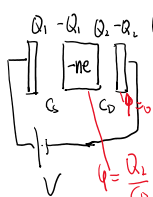
$$\therefore Q < -\frac{e}{2}$$

$$\text{即 } V_{AB} < -\frac{e}{2C}$$

由①、②, $V_{AB} > \frac{e}{2C}$ 或 $V_{AB} < -\frac{e}{2C}$ 时可随穿.故当 $-\frac{e}{2C} \leq V_{AB} \leq \frac{e}{2C}$ 时, 发生库仑阻塞 (Coulomb blockade)

$$(2) \therefore \frac{e}{2C} = 10 \text{ mV}$$

$$\therefore C = 8 \times 10^{-18} \text{ F}$$



$$(3) \begin{cases} \frac{Q_1}{C_1} + \frac{Q_2}{C_2} = V \\ -Q_1 + Q_2 = -ne \end{cases}$$

$$\therefore Q_1 = \frac{C_2 C_0}{C_1 + C_2} V + \frac{C_2 ne}{C_1 + C_2}$$

$$Q_2 = Q_1 - ne = \frac{C_2 C_0}{C_1 + C_2} V - \frac{C_2 ne}{C_1 + C_2}$$

$$(注:) W = \frac{1}{2} (-ne) \cdot \frac{Q_2}{C_2} = \frac{ne (ne - C_2 V)}{2 (C_1 + C_2)} \quad (\text{与 } V \text{ 有关})$$

$\Rightarrow \int \text{电势: } W = \frac{1}{2} Q U$

$W = \frac{1}{2} \int_V \rho \phi dV$

$W = \frac{1}{2} \int_V \epsilon \vec{E} \cdot d\vec{V}$

$$Q_2 = Q_1 - ne$$

$$\frac{1}{C_1} Q_1 + \frac{1}{C_2} (Q_1 - ne) = V$$

$$Q_1 = \left(V + \frac{ne}{C_2} \right) \frac{C_1 C_2}{C_1 + C_2}$$

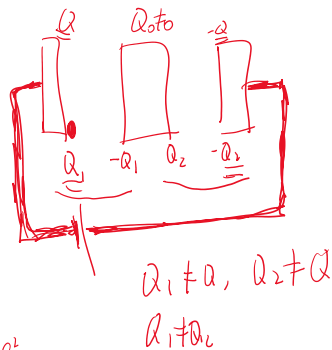
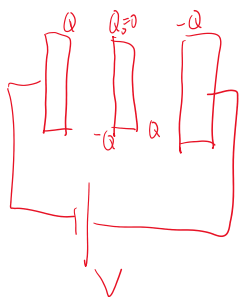
$$(法一): \quad W = \frac{1}{2}(-ne) \cdot \frac{Q_2}{C_D} = \frac{neC_D V - C_D V^2}{2(C_S + C_D)} \quad (\text{与 } V \text{ 有关})$$

$$W_{\text{总}} = W + \frac{1}{2} Q_1 V = \frac{ne^2 + C_S C_D V^2}{2(C_S + C_D)}$$

$$(法二): \quad V_S = \frac{Q_1}{C_S} = \frac{Q_1 V + ne}{C_S + C_D}, \quad V_D = \frac{Q_2}{C_D} = \frac{Q_1 V - ne}{C_S + C_D}$$

$$W_{\text{总}} = \frac{1}{2} C_S V_S^2 + \frac{1}{2} C_D V_D^2$$

$$= \frac{ne^2 + C_S C_D V^2}{2(C_S + C_D)}$$



★ 若定义 $W = W_{\text{总}} - W_C = \frac{ne^2}{2(C_S + C_D)}$

$$\frac{C_S}{2} \frac{(C_D V + ne)^2 + C_D (C_S V - ne)^2}{(C_S + C_D)^2}$$

$$= \frac{C_S (C_D^2 V^2 + ne^2 + 2C_D V ne) + C_D (C_S^2 V^2 + ne^2 - 2ne C_S V)}{2(C_S + C_D)^2}$$

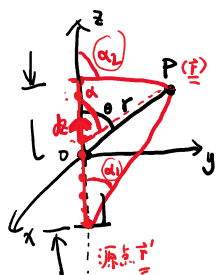
$$= \frac{C_S C_D V^2 (C_D + C_S) + (C_S + C_D) ne^2}{2(C_S + C_D)^2}$$

$$= \frac{C_S C_D V^2 + ne^2}{2(C_S + C_D)}$$

[2.4] 第四章习题 (1)

2020年4月9日 19:30

4.1 (PPT)



$$\vec{B}(P) = \frac{\mu_0}{4\pi} \int \frac{I d\vec{l} \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dz$$

$$= \frac{\mu_0 I R}{4\pi} \int_{-\pi}^{\pi} \frac{dz}{[z^2 - 2R \cos\theta z + R^2]^{\frac{3}{2}}}$$

积分:

$$\therefore \vec{B}(P) = \frac{\mu_0 I}{4\pi R \sin\theta} (\cos\theta_1 - \cos\theta_2) \hat{\theta}$$

当 $r \ll R$ 时, $\theta_1 \approx 0, \theta_2 \approx \pi$.

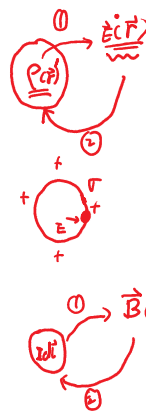
$$\therefore \vec{B}(P) = \frac{\mu_0 I}{2\pi R \sin\theta}$$

$$z = \frac{1}{2} - r \cos\alpha$$

亦可这样解: (将 $z \rightarrow \alpha$)

$$\Rightarrow \frac{\mu_0 I R}{4\pi} \int_{\alpha_1}^{\alpha_2} \frac{(r \sin\theta / \sin\alpha) d\alpha}{(r \sin\theta / \sin\alpha)^3}$$

$$= \frac{\mu_0 I}{4\pi R \sin\theta} (\cos\alpha_1 - \cos\alpha_2)$$



4.4 (1) 求 $\vec{B}$ 在 r, θ 处

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{I d\vec{l} \times \vec{r}}{r^3}$$

$$= \frac{\mu_0 N I}{4\pi (b-a)} \int_a^b \int_0^{2\pi} \frac{r' dr' d\theta}{r^3}$$

$$= \frac{\mu_0 N I}{2(b-a)} \ln \frac{b}{a}$$



密度	线: $\frac{I dl}{L}$	面: $\frac{I ds}{S}$	体: $\frac{I dV}{V}$
----	---------------------	---------------------	---------------------

你可一圈圈算: 每个 r 外面电流环: $d\vec{B} = \frac{\mu_0 i_0 dr}{2r} \Rightarrow \vec{B} = \int d\vec{B}$

$$(2) \vec{B}(0,0,z) = \frac{\mu_0}{4\pi} \int \frac{I d\vec{l} \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$

$$(a, b, z) = \frac{\mu_0 N I}{4\pi (b-a)} \int_a^b \int_0^{2\pi} \frac{r' dr' d\theta}{r^3}$$

$$= \frac{\mu_0 N I}{2(b-a)} \left[\ln \frac{\sqrt{a^2+z^2}+b}{\sqrt{a^2+z^2}+a} + \frac{a}{\sqrt{a^2+z^2}} - \frac{b}{\sqrt{b^2+z^2}} \right]$$

[亦可一圈圈算]

4.8.



$$I = \frac{dq}{dt} = \frac{e}{T} = \frac{e v}{2\pi r}$$

$$B = \frac{\mu_0 I}{2r} = \frac{\mu_0 e v}{4\pi r^2} = 12.5 T$$

4.16.

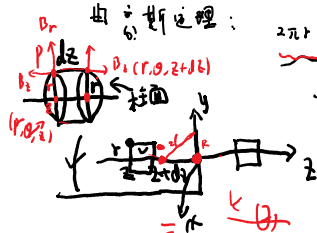
由 PPT

$$B_z(0,0,z) = \frac{\mu_0 N I}{2} (0 \cos\theta_1 - \cos\theta_2) \approx \frac{\mu_0 N I}{2} \left(1 - \frac{z}{R} \right)$$

由安培定理:

$$2\pi r dB_z(r,0,z) + \pi r^2 dB_z(r,0,z) = 0$$

$$\therefore B_z(r,0,z) = -\frac{r}{2} \frac{dB_z(0,0,z)}{dz} = \frac{r}{2} \frac{dB_z(0,0,z)}{dz} = \frac{\mu_0 N I r}{4R}$$



[由 B_z 与 $\nabla \cdot \vec{B} = 0$ 推出]

4.17

$$F = I l B, \text{ at 内跳起.}$$



$$\therefore I l B \cdot \Delta t = m v$$

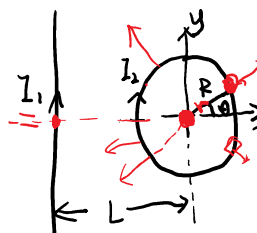
$$\text{且 } mgh = \frac{1}{2} m v^2$$

$$\therefore \Gamma = \frac{m \sqrt{2gh}}{I l B}$$

$$mgh = \frac{1}{2} m v^2$$

$$\therefore v = \sqrt{2gh}, q = I \Delta t = \frac{m \sqrt{2gh}}{Bl}$$

4.18.



(1) I_1 对 I_2 的力 $\vec{F}_{12} = -\vec{F}_{21}$.

$$\therefore d\vec{F}_{12} = \frac{\mu_0 I_1 I_2}{2\pi(L^2 + R^2 - 2LR\cos\theta)} R d\theta \hat{r}$$

(可用对称性简化: $F_{12y} = 0$.)

$$dF_{12x} = |d\vec{F}_{12}| \cos\theta$$

$$\therefore \vec{F}_{12} = \hat{x} \int_0^{2\pi} dF_{12x} dx = \hat{x} \mu_0 I_1 I_2 \left(\frac{L}{\sqrt{L^2 + R^2}} - 1 \right)$$

$$\vec{F}_{21} = -\vec{F}_{12}$$

(2) $\vec{M}_{12}$: 以 O 为心, 由于 $d\vec{F}_{12} \propto \hat{r}$

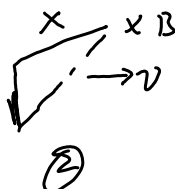
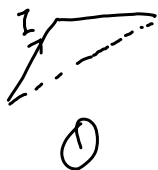
$$\therefore d\vec{M}_{12} = \hat{r} \times d\vec{F}_{12} = 0$$

$$\therefore \vec{M}_{12} = 0.$$

第四章习题 (2)

2020年4月29日 12:45

4.23



4.32. $\vec{B} = B \hat{x}$

$q\vec{v} \times \vec{B} = m\vec{a}$

$\therefore \begin{cases} \dot{x} = 0 \checkmark \\ \dot{y} = \frac{qB}{m} \dot{z} \\ \dot{z} = -\frac{qB}{m} \dot{y} \end{cases}, \text{ 且 } \begin{cases} x(0) = 0 \\ y(0) = 0 \\ z(0) = \frac{mv_0 \sin \beta}{qB} \end{cases} \quad \begin{cases} \dot{x}(0) = v_0 \cos \beta \\ \dot{y}(0) = v_0 \sin \beta \\ \dot{z}(0) = 0 \end{cases}$

此外可用通解法、代入法、猜解法。

$\therefore \begin{cases} x = v_0 t \cos \beta \\ y = \frac{qB \sin \beta}{2B} \sin \frac{2B}{m} t \\ z = \frac{mv_0 \sin \beta}{qB} \cos \frac{2B}{m} t \end{cases}$

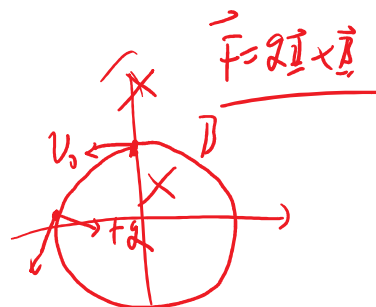
$\dot{z} = \frac{m}{qB} \ddot{y}$

$\ddot{z} = \frac{m}{qB} \ddot{y}$

$\frac{m}{qB} \ddot{y} = -\frac{qB}{m} \dot{y}$

$v = \dot{y}(t)$

$\dot{v} = -\Omega^2 v$



[2.5] 第五章习题

2020年4月9日 19:31

$$5.4 \quad (1) N = \frac{m}{M} \cdot N_A = \frac{2N_A \rho V}{M} = 1.58 \times 10^{24}$$

(2) 电子磁矩为 $\mu_e = \frac{1}{2} \mu_B$ (物理常量)

$$\therefore \mu = N \mu_e = 8.33 \times 10^{11} \text{ A} \cdot \text{m}^2$$

(3) 由线圈的磁矩: $\mu = IS = i \cdot L \cdot S$

$$\therefore i = \frac{\mu}{SL} = 8.84 \times 10^{-6} \text{ A} \cdot \text{m}^{-1}$$



(4) 看做无限长螺线管:

$$B = \mu_0 i = 1.11 \times 10^{-11} \text{ T}$$

$$5.6 \quad Q = CU = 4\pi\epsilon_0 R U$$

[也可以看做各个线圈磁矩]

$$\therefore \vec{j}(\vec{r}) = \nabla \vec{v}(\vec{r}) = \frac{4\pi\epsilon_0 R U}{4\pi R^2} \cdot \omega R \hat{z} \times \hat{r}$$

$$= \epsilon_0 U \omega (\sin\theta \cos\phi \hat{y} - \sin\theta \sin\phi \hat{x})$$

$$\therefore \vec{m} = \frac{1}{2} \iint_S \vec{r} \times \vec{j}(\vec{r}) d\vec{S} \quad d\vec{m} = \frac{1}{2} \vec{r} \times (i d\vec{l})$$

$$= \epsilon_0 U \omega \int_0^{2\pi} \int_0^\pi \vec{r} \hat{r} \times (\sin\theta \cos\phi \hat{y} - \sin\theta \sin\phi \hat{x}) R^2 \sin\theta d\theta d\phi$$

$$= \epsilon_0 U R^2 \omega \int_0^{2\pi} \int_0^\pi \sin^2\theta (\cos\phi \hat{y} - \sin\phi \hat{x}) d\theta d\phi$$

$$= \epsilon_0 U R^2 \omega \int_0^{2\pi} \int_0^\pi \sin^2\theta [\cos\phi (\sin\theta \cos\phi \hat{z} - \cos\theta \hat{x}) - \sin\phi (-\sin\theta \sin\phi \hat{z} + \cos\theta \hat{y})] d\theta d\phi$$

$$= \epsilon_0 U R^2 \omega \int_0^{2\pi} \int_0^\pi \sin^2\theta (\sin\theta \hat{z} - \cos\theta \cos\phi \hat{x} - \cos\theta \sin\phi \hat{y}) d\theta d\phi$$

$$= 2\pi \epsilon_0 U R^2 \omega \int_0^\pi \sin^3\theta d\theta \hat{z}$$

$$= \frac{4\pi}{3} \epsilon_0 U R^3 \omega \hat{z}$$

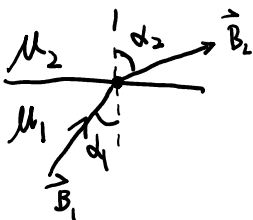
5.10

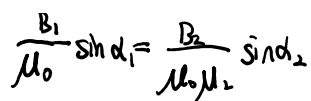
$$\therefore \vec{n} \cdot (\vec{B}_2 - \vec{B}_1) = 0$$

$$\vec{n} \times (\vec{H}_2 - \vec{H}_1) = 0$$

$$\therefore B_1 \cos\alpha_1 = B_2 \cos\alpha_2$$

$$\frac{B_1}{\mu_0} \sin\alpha_1 = \frac{B_2}{\mu_0 \mu_2} \sin\alpha_2$$

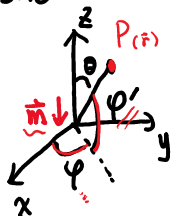




$$\therefore \tan d_1 = \frac{\tan d_2}{\mu_2}$$

$$\therefore \alpha_2 \approx 0.09^\circ$$

5.13



磁偶极子在球坐标下: $\vec{m} = -m\hat{e}_z$

$$\underline{\underline{\vec{B}(\vec{r})}} = \frac{\mu_0}{4\pi r^3} [-\vec{m} + 3(\vec{m} \cdot \hat{r})\hat{r}]$$

$$= \frac{16}{4\pi^3} [m\hat{z} - 3m \cos\theta \hat{r}]$$

$$= \frac{\mu_0 m}{4\pi r^3} (\sin\theta \hat{\theta} - 2\cos\theta \hat{r})$$

$$= \frac{\mu_0 m}{4\pi r^3} (\cos\phi' \hat{\phi}' - 2\cos\theta \hat{r}) \quad \therefore \tan\phi = \frac{B_y}{B_{z0}}$$

$$\therefore \tan \beta = \frac{2 \sin \phi'}{\cos \phi'} = 2 \tan \phi'$$

5.14. 5.16. 判断 $\bar{x}$ 均还是 $\bar{y}$ 均

(根据对称性, 均为均匀)

① $\frac{+P_0}{D}$ $\frac{+e}{\epsilon_1 | \epsilon_2}$

[分区均匀介质]

② $\frac{i_1}{i}$ $\frac{i_2}{i}$

$\frac{1}{n_1} \left| \frac{1}{n_2} \right.$ $\frac{-i_0}{i}$

5.20. 磁路图:

$$R_1 = \frac{L}{\mu S} = 5411.3 \text{ H}^{-1}$$

$$R_3 = 5411.3 \text{ Ft}^{-1}$$

$$\Sigma_m = NI$$

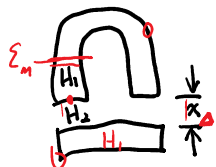
$$\therefore \Phi = \frac{\Sigma m}{R_{\text{eq}}}$$

$$\therefore \underline{\underline{\varepsilon_m = NI = BS\left(\frac{R_1}{2} + R_2\right) = 94583 \text{ A}}}$$

5.21.

$$\underline{H_1 L} + \underline{2H_2 x} = \underline{2N I}$$

$$\text{B} \quad L = 2l + \pi \cdot (a + \frac{a}{2}) + 2a + d = 3l + (\frac{3}{2}\pi + 2)a = 0,64 \text{ m.}$$



且 $\vec{n} \cdot (\vec{B}_2 - \vec{B}_1) = 0$

$$\therefore \mu_{H_2} = \mu_{H_1}$$

$$\therefore B_1 = \frac{2\mu\mu_0 NI}{\mu_0 l + 2\mu\pi}$$

$$\therefore \underline{W_m} = \frac{1}{2} I \Phi_m = \frac{2\mu\mu_0 I^2 N^2 a^2}{\mu_0 L + 2\mu x}$$

$$= \frac{1}{2} (2) W_m = \frac{1}{2} (2^2 N^2 T^2 a^4)$$

$$= \frac{\mu_0 L T 2 \mu x}{\mu_0 L^2} = -99.5 \text{ N.}$$

☆ 小磁体在远处:

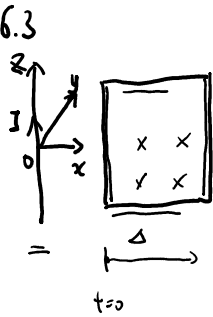
$$(1) \text{ 产生磁场: } \vec{B}(r) = \frac{\mu}{4\pi} \left[-\frac{\vec{m}}{r^3} + \frac{3(\vec{m} \cdot \hat{r}) \hat{r}}{r^3} \right] + \dots$$

$$(2) \text{ 外场中: } E_p = \vec{m} \cdot \vec{B}_{\text{外}} + \dots$$

[2.6] 第六章习题

2020年4月29日 12:45

6.3



(1) $\vec{B} = \frac{\mu_0 I}{2\pi r} \hat{\phi}$

$$\Phi = \iint_S \vec{B} \cdot d\vec{s} = \frac{\mu_0 I b \sin \omega t}{2\pi} \int_b^b \frac{1}{r} dr$$

$$= \frac{\mu_0 I b \sin \omega t}{2\pi} \ln \frac{b}{a}$$

$$\therefore \mathcal{E} = - \frac{d\Phi}{dt} = - \frac{\mu_0 I b \omega \cos \omega t}{2\pi} \ln \frac{b}{a}$$

(2) $\Phi = \frac{\mu_0 I b \sin \omega t}{2\pi} \int_{a+\omega t}^{b+\omega t} \frac{1}{r} dr$

$$= \frac{\mu_0 I b \sin \omega t}{2\pi} \cdot \ln \frac{b+\omega t}{a+\omega t}$$

$$\therefore \mathcal{E} = - \frac{d\Phi}{dt} \Leftrightarrow \text{动生} + \text{感生}$$

(3) $I = \frac{\mathcal{E}}{R}$

① 源 $\rightarrow$ 场
(q, IdL) (E, B)
($\mathcal{E}, \sim$)

② 场 $\rightarrow$ 源

$$F = B_1 L - B_2 L$$

6.4. $\mathcal{E} = \int_L \vec{v} \times \vec{B} \cdot d\vec{l} = \int_L \vec{B} \cdot \vec{v}$

$$= - \frac{\mu_0 \mu \omega}{4\pi R} (L \dot{\theta})$$



$$\vec{m} = -m\hat{z}; \quad \vec{B} = \frac{\mu_0}{4\pi} \left[\frac{\vec{m}}{R^3} + \frac{3(\vec{m} \cdot \hat{R})\hat{R}}{R^5} \right] = \frac{\mu_0}{4\pi} \left[\frac{m}{R^3} \hat{z} - \frac{3m \cos \theta}{R^3} \hat{R} \right] = \frac{\mu_0 m}{4\pi R^3} [\hat{z} - 3 \cos \theta \hat{R}]$$

$$\vec{v} = R\omega \sin \theta \hat{\phi}, \quad d\vec{l} = R d\theta \hat{\theta}$$

$$\therefore \mathcal{E} = \int_L \vec{v} \times \vec{B} \cdot d\vec{l}$$

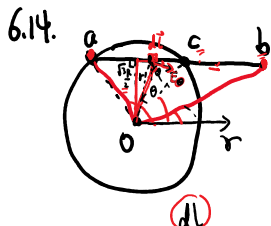
$$= \int [R\omega \sin \theta \hat{\phi} \times \frac{\mu_0 m}{4\pi R^3} [\sin \theta \hat{\theta} + 2 \cos \theta \hat{R}]] \cdot R d\theta \hat{\theta}$$

$$= - \frac{\mu_0 m \omega}{4\pi R} \int [-\hat{R} + \hat{\theta}] \sin \theta \cdot d\theta$$

$$= - \frac{\mu_0 m \omega}{4\pi R} \int_0^\pi \sin \theta d\theta$$

$$= - \frac{\mu_0 m \omega}{2\pi R}$$

$$\hat{R} \cos \theta - \hat{\theta} \sin \theta$$



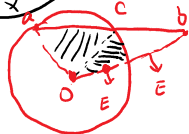
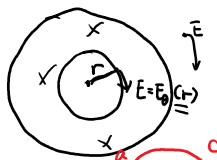
(法-) 求 E_z . $\therefore \vec{E} = E_z(r) \hat{z}$

$$\therefore \mathcal{E} = \int_C \vec{E} \cdot d\vec{l} = E_z(r) \cdot 2\pi r$$

$$\therefore \mathcal{E} = - \frac{d\Phi}{dt} = -k \cdot \pi r^2, \quad r \leq R$$

$$= -k \cdot \pi R^2, \quad r > R$$

$$\therefore E_z(r) = - \frac{k}{2} r, \quad r \leq R$$



$$= \frac{1}{2} \left[-\frac{1}{k} \pi R^2, r > R \right]$$

$$\therefore E_0(r) = \begin{cases} -\frac{k}{2} r, & r \leq R \\ -\frac{kR^2}{2} \frac{1}{r}, & r > R. \end{cases}$$

$$\therefore U_{ab} = \int_a^b \vec{E} \cdot d\vec{r} = \int_a^b \frac{k}{2} r \sin \theta \cdot r d\theta + \int_b^R \frac{kR^2}{2} \frac{1}{r} \sin \theta \cdot r d\theta$$

$$\text{且 } r = \frac{\sqrt{3}R}{2 \sin \theta}$$

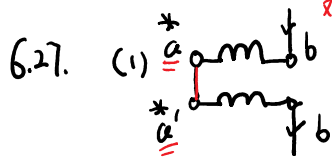
$$\therefore U_{ab} = \frac{k}{2} \int_{\frac{\pi}{3}}^{\frac{\pi}{2}} \frac{3R^2}{4 \sin^2 \theta} d\theta + \frac{kR^2}{2} \theta \Big|_{\frac{\pi}{3}}^{\frac{\pi}{2}} = \left(\frac{\sqrt{3}}{4} + \frac{\pi}{12} \right) kR^2$$

$$(\therefore \Sigma) : \Sigma = \Sigma_{ab0}$$

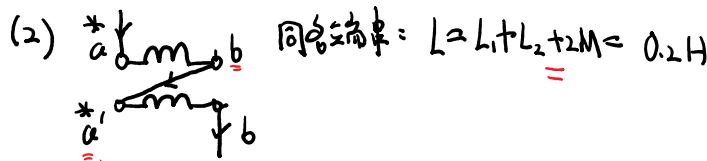
$$= \left(\frac{\sqrt{3}}{4} + \frac{\pi}{12} \right) kR^2$$

$$\Sigma = -\frac{d\Phi}{dt} = \dot{\Sigma} \cdot k$$

$$\text{又: } \Sigma = \Sigma_{ab} + \Sigma_{b0} + \Sigma_{0a} = \Sigma_{ab}$$



异名端: $L = L_1 + L_2 - 2M = L_1 + L_2 - 2\sqrt{L_1 L_2} = 0$



同名端: $L = L_1 + L_2 + 2M = 0.2H$

6.31. 代入公式证明.

