

$$\partial_t^2 u - \Delta u = 0 \quad u(x, 0) = \varphi(x), \quad \partial_t u(x, 0) = \psi(x) \quad (3.1)$$

• 球坐标 $u(x, t) = u(r, t)$ $\partial_t^2 u - \Delta u = \partial_t^2 u - \left(\partial_r^2 u + \frac{2}{r} \partial_r u + \frac{1}{r^2} \Delta_{S^2} u \right) = 0$

两边同时在 S^2 上积分, 由于 $\int_{S^2} \Delta_{S^2} u \cdot d\sigma = 0$, 故

$$\partial_t^2 \int_{S^2} u d\sigma - \left(\partial_r^2 \int_{S^2} u d\sigma + \frac{2}{r} \partial_r \int_{S^2} u d\sigma \right) = 0$$

令 $\bar{u}(r, t)$, 则 $\begin{cases} \partial_t^2 \bar{u} - \left(\partial_r^2 \bar{u} + \frac{2}{r} \partial_r \bar{u} \right) = 0 \\ \bar{u}(r, 0) = \bar{\varphi}(r), \quad \partial_t \bar{u}(r, 0) = \bar{\psi}(r). \end{cases}$

将 $\bar{u}(r, t)$ 关于 r 作换元, 令 $v = r\bar{u}$, 则 $\begin{cases} \partial_t^2 v - \partial_r^2 v = 0 \\ v(r, 0) = r\bar{\varphi}(r), \quad \partial_t v(r, 0) = r\bar{\psi}(r). \end{cases}$

于是, $v(r, t) = \frac{1}{2}[(r+t)\bar{\varphi}(r+t) + (r-t)\bar{\varphi}(r-t)] + \frac{1}{2} \int_{r-t}^{r+t} s \bar{\psi}(s) ds$

由此可以计算出 $\bar{u}(r, t)$. 如何求得 $u(x, t)$?

Step 1. $u|_{0, t} = \bar{u}|_{0, t} = \partial_r \left(\frac{v}{r} \right) \Big|_{r=0}$

$$= \frac{1}{2} (\bar{\varphi}(t) + t\bar{\psi}'(t) + \bar{\varphi}'(t) - t\bar{\varphi}'(t)) + \frac{1}{2} [(t)\bar{\varphi}'(t) - (t)\bar{\varphi}'(t)]$$

$$= \bar{\varphi}(t) + t\bar{\psi}'(t) + t\bar{\varphi}'(t)$$

$$= \frac{d}{dt} (t\bar{\varphi}(t)) + t\bar{\psi}(t)$$

$$= \frac{d}{dt} \left(\frac{t}{4\pi} \int_{S^2} \varphi(t\omega) d\sigma \right) + \frac{t}{4\pi} \int_{S^2} \psi(t\omega) d\sigma$$

Step 2. 波方程是平移不变的. 即若 $u(x, t)$ 是 (W) 的解. 则 $\forall x_0 \in \mathbb{R}^3, u(x+x_0, t)$ 也是 (W) 的解. 初值为 $\varphi(x+x_0), \psi(x+x_0)$.

对 $u(x+x_0, t)$ 应用 Step 1, 可得

$$u(x_0, t) = \frac{d}{dt} \left(\frac{t}{4\pi} \int_{S^2} \varphi(x_0+t\omega) d\sigma \right) + \frac{t}{4\pi} \int_{S^2} \psi(x_0+t\omega) d\sigma$$

由于 $x_0 \in \mathbb{R}^3$ 是任意的, 故

$$u(x, t) = \frac{d}{dt} \left(\frac{t}{4\pi} \int_{S^2} \varphi(x+t\omega) d\sigma \right) + \frac{t}{4\pi} \int_{S^2} \psi(x+t\omega) d\sigma$$

$$= \frac{d}{dt} \left(\frac{1}{4\pi t} \int_{|x-y|=t} \varphi(y) dS(y) \right) + \frac{1}{4\pi t} \int_{|x-y|=t} \psi(y) dS(y)$$

Kirchhoff 公式



其中 $dS(y)$ 是 $B(x, t)$ 上的面积元, $dS(y) = t^2 dy$.

$n=2$ 降维法.

考虑二维波动方程 $\Delta^2 u - \Delta(\Delta^2 u + \Delta^2 u) = 0$
 $u(x, 0) = \varphi(x, x_2), \quad \Delta u(x, 0) = \psi(x, x_2).$

将 $u(t, x_1, x_2)$ 看成三维空间中的函数 $\tilde{u}(t, x_1, x_2, x_3) = u(t, x_1, x_2).$

$\tilde{\varphi}(t, x_1, x_2, x_3) = \varphi(x_1, x_2), \quad \tilde{\psi}(t, x_1, x_2, x_3) = \psi(x_1, x_2) \cdot \delta(x_3)$

$\begin{cases} \Delta^2 \tilde{u} - \Delta(\Delta^2 \tilde{u} + \Delta^2 \tilde{u}) = 0 \\ \tilde{u}(x, 0) = \tilde{\varphi}, \quad \Delta \tilde{u}(0) = \tilde{\psi}. \end{cases}$

由 Kirchhoff 公式, $\tilde{u}(x_1, x_2, x_3, t) = \frac{d}{dt} \left(\frac{1}{4\pi t} \int_{|x-y|=t} \tilde{\varphi}(y) dS(y) \right) + \frac{1}{4\pi t} \int_{|x-y|=t} \tilde{\psi}(y) dS(y).$

由于 \tilde{u} 与 x_3 无关, 不妨设 $x_3 = 0$. 由平移不变性, 先求 $\tilde{u}(0, 0, 0, t)$.

$\tilde{u}(0, 0, 0, t) = \frac{d}{dt} \left(\frac{1}{4\pi t} \int_{|y|=t} \varphi(y_1, y_2) dS(y) \right) + \frac{1}{4\pi t} \int_{|y|=t} \psi(y_1, y_2) dS(y).$

直接计算 $\int_{y_3 = \sqrt{t^2 - y_1^2 - y_2^2}} \varphi(y_1, y_2) dS(y) = 2 \int_{y_3 = \sqrt{t^2 - y_1^2 - y_2^2}} \varphi(y_1, y_2) dS(y)$

$= 2 \int_{y_1^2 + y_2^2 \leq t^2} \varphi(y_1, y_2) \sqrt{1 + \left(\frac{\partial y_3}{\partial y_1}\right)^2 + \left(\frac{\partial y_3}{\partial y_2}\right)^2} dy_1 dy_2$

$= 2t \int_{y_1^2 + y_2^2 \leq t^2} \varphi(y_1, y_2) \frac{1}{\sqrt{t^2 - y_1^2 - y_2^2}} dy_1 dy_2$

$= 2t \int_{B(0, t)} \frac{\varphi(y_1, y_2)}{\sqrt{t^2 - y_1^2 - y_2^2}} dy_1 dy_2.$

即 $u(0, 0, t) = \frac{d}{dt} \left(\frac{1}{2\pi} \int_{B(0, t)} \frac{\varphi(y)}{\sqrt{t^2 - |y|^2}} dy_1 dy_2 \right) + \frac{1}{2\pi} \int_{B(0, t)} \frac{\psi(y)}{\sqrt{t^2 - |y|^2}} dy_1 dy_2$

对 $u(x, x_0, t)$ 应用上式, 可得 $u(x, x_0, t) = \frac{d}{dt} \left(\frac{1}{2\pi} \int_{B(x_0, t)} \frac{\varphi(x_0 + y)}{\sqrt{t^2 - |y|^2}} dy_1 dy_2 \right) + \dots$

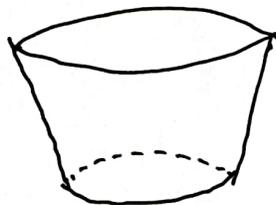
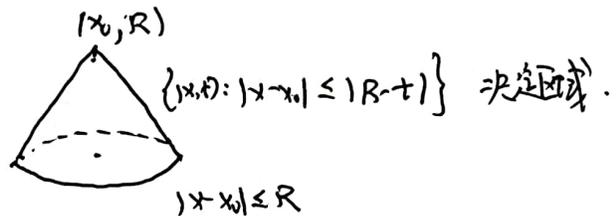
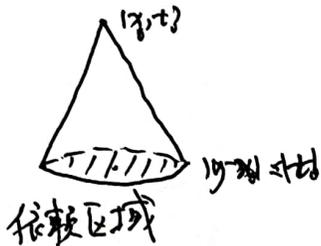
故 $u(x, t) = \frac{d}{dt} \left(\frac{1}{2\pi} \int_{|x-y| \leq t} \frac{\varphi(y)}{\sqrt{t^2 - |x-y|^2}} dy_1 dy_2 \right) + \frac{1}{2\pi} \int_{|x-y| \leq t} \frac{\psi(y)}{\sqrt{t^2 - |x-y|^2}} dy_1 dy_2.$



$$\partial_t^2 u - \Delta u = 0 \quad u(x, 0) = \varphi(x), \quad \partial_t u(x, 0) = \psi(x)$$

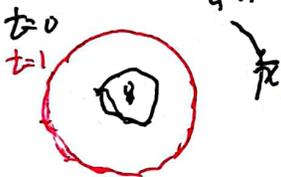
$$d=3 \quad u(x, t) = \frac{d}{dt} \left(\frac{1}{4\pi t} \int_{|x-y|=t} \varphi(y) dS(y) \right) + \frac{1}{4\pi t} \int_{|x-y|=t} \psi(y) dy$$

$$d=2 \quad u(x, t) = \frac{d}{dt} \left(\frac{1}{2\pi} \int_{|x-y| \leq t} \frac{\varphi(y)}{\sqrt{t^2 - |x-y|^2}} dy \right) + \frac{1}{2\pi} \int_{|x-y| \leq t} \frac{\psi(y)}{\sqrt{t^2 - |x-y|^2}} dy$$



$|x-x_0| \leq |H-z| + R$ 影响区域.

$d=3$



Huygens principle.

$d=2$ 不成立.

非齐次方程
$$\begin{cases} \partial_t^2 u - \Delta u = f \\ u(x, 0) = \varphi(x), \quad \partial_t u(x, 0) = \psi(x) \end{cases}$$

叠加原理
$$\begin{cases} \partial_t^2 u - \Delta u = 0 & (I) \\ u(x, 0) = \varphi(x), \quad \partial_t u(x, 0) = \psi(x) \end{cases}$$

$$\begin{cases} \partial_t^2 u - \Delta u = f(x, t) & (II) \\ u(x, 0) = \varphi(x), \quad \partial_t u(x, 0) = \psi(x) \end{cases}$$

Claim: 令 $W(x, t; \tau)$ 是
$$\begin{cases} \partial_t^2 u - \Delta u = 0 \\ u(x, \tau) = 0, \quad \partial_t u(x, \tau) = f(x, \tau) \end{cases}$$

则 $u(x, t) = \int_0^t W(x, t; \tau) d\tau$ 是 (II) 的解.



$$\partial_t u = W(x, t; t) + \int_0^t \partial_t W(x, t; \tau) d\tau = \int_0^t \partial_t^2 W(x, t; \tau) d\tau$$

$$\partial_t^2 u = \partial_t W(x, t; t) + \int_0^t \partial_t^2 W(x, t; \tau) d\tau$$

$$\Delta u = \int_0^t \Delta W(x, t; \tau) d\tau$$

$$\Rightarrow \begin{cases} \partial_t^2 u - \Delta u = \int_0^t (\partial_t^2 W - \Delta W)(x, t; \tau) d\tau + f(x, t) = f(x, t) \\ u(x, 0) = 0, \partial_t u(x, 0) = 0 \end{cases}$$

~~Kindhoff~~ $W(x, t) =$

$$\hat{=} \text{令 } s = t - \tau, \quad \square \quad u(x, t) = u(x, s + \tau) \triangleq v(x, s), \quad \partial_s^2 v - \Delta v = 0$$

$$\text{且 } v(x, 0) = 0, \quad \partial_s v(x, 0) = f(x, \tau)$$

$$\Rightarrow v(x, s) = \frac{1}{4\pi s} \int_{|x-y|=s} f(y, \tau) dS(y)$$

$$\Rightarrow W(x, t) = \frac{1}{4\pi(t-\tau)} \int_{|x-y|=t-\tau} f(y, \tau) dS(y)$$

$$\Rightarrow u(x, t) = \int_0^t \frac{1}{4\pi(t-\tau)} \int_{|x-y|=t-\tau} f(y, \tau) dS(y) d\tau$$

$$= \frac{1}{4\pi} \int_0^t \frac{1}{4s} \int_{|x-y|=s} f(y, t-s) dS(y) ds$$

$$= \frac{1}{4\pi} \int_{|x-y| \leq t} \frac{f(y, t-|x-y|)}{|x-y|^2} dy$$



§3.5 能量法. 解的唯一性与稳定性.

若 $u(x,t)$ 是 $\partial_t^2 u - \Delta u = 0$ 的解 (即 $u(x, t+t_0)$, $u(x+t_0, t)$ 也是解).

$$\begin{aligned} \partial_t u (\partial_t^2 u - \Delta u) &= \frac{1}{2} \partial_t (\partial_t u)^2 - \operatorname{div}(\partial_t u \nabla u) + \partial_t \nabla u \cdot \nabla u \\ &= \frac{1}{2} \partial_t (\partial_t u)^2 + \frac{1}{2} \partial_t |\nabla u|^2 - \operatorname{div}(\partial_t u \nabla u) \end{aligned}$$

令 $e(u) = \frac{1}{2} (\partial_t u)^2 + \frac{1}{2} |\nabla u|^2$, 则 $\partial_t e(u) = \operatorname{div}(\partial_t u \nabla u)$

(I) 波动方程
$$\begin{cases} \partial_t^2 u - \Delta_{\mathbb{R}^n} u = 0 & \Omega \times \{t \geq 0\} \\ (\frac{\partial u}{\partial \nu} + \sigma u)|_{\partial \Omega} = 0 & t \geq 0 \end{cases} \quad (3.5.2)$$

$$\begin{aligned} \text{则} \quad \partial_t \int_{\Omega} e(u) dx &= \int_{\Omega} \operatorname{div}(\partial_t u \nabla u) dx = \int_{\partial \Omega} \partial_t u \frac{\partial u}{\partial \nu} dS \\ &= -\sigma \int_{\partial \Omega} \partial_t u u dS = -\frac{\sigma}{2} \partial_t \int_{\partial \Omega} u^2 dS \end{aligned}$$

即 $\partial_t \left[\int_{\Omega} e(u) dx + \frac{\sigma}{2} \int_{\partial \Omega} u^2 dS \right] = 0$.

令 $E(u) = \int_{\Omega} e(u) dx + \frac{\sigma}{2} \int_{\partial \Omega} u^2 dS$, 则 $E(u(t)) = E(u(0))$.

定理 3.1. 问题
$$\begin{cases} \partial_t^2 u - \Delta u = f & \text{in } \Omega, t \geq 0 & \text{最多有一解.} \\ u(x,0) = \varphi(x), \partial_t u(x,0) = \psi(x) \\ (\frac{\partial u}{\partial \nu} + \sigma u)|_{\partial \Omega} = p(x,t) & t \geq 0 \end{cases}$$

证: 设 u_1, u_2 是两解. 令 $V = u_1 - u_2$, 则 V 满足
$$\begin{cases} \partial_t^2 V - \Delta V = 0 \\ V(x,0) = 0, \partial_t V(x,0) = 0 \\ (\frac{\partial V}{\partial \nu} + \sigma V)|_{\partial \Omega} = 0 \end{cases}$$

由能量估计,

$$E(V(t)) = \frac{1}{2} \int_{\Omega} (\partial_t V)^2 + |\nabla V|^2 dx + \frac{\sigma}{2} \int_{\partial \Omega} V^2 dS = E(V(0)) = 0.$$

故 $\partial_t V \equiv 0, \nabla V \equiv 0 \Rightarrow V = \text{const}$ in $\bar{\Omega} \times \{t \geq 0\}$

又 $\int_{\partial \Omega} V^2 dS = 0 \Rightarrow V \equiv 0$ on $\partial \Omega \times \{t \geq 0\}$ 故 $V \equiv 0$ in $\bar{\Omega} \times \{t \geq 0\}$.

(II) 波动方程
$$\begin{cases} \partial_t^2 u - \Delta u = 0 & \text{in } \mathbb{R}^n \times \{t \geq 0\} \\ u(x,0) = \varphi(x), \partial_t u(x,0) = \psi(x) & x \in \mathbb{R}^n \end{cases}$$

若 $u \in C^2$ 且 $|u(x)| \rightarrow 0, \text{ as } |x| \rightarrow \infty$. 则

$$\partial_t \int_{\mathbb{R}^n} \underbrace{\left(\frac{1}{2} (\partial_t u)^2 + \frac{1}{2} |\nabla u|^2 \right)}_{E(u)} dx = \int_{\mathbb{R}^n} \operatorname{div}(\partial_t u \nabla u) dx = 0 \Rightarrow E(u(t)) = E(u(0)).$$



$$\begin{cases} \partial_t^2 u - \Delta u = f(x,t) & x \in \Omega \\ u(x,0) = \varphi(x), \partial_t u(x,0) = \psi(x) & x \in \Omega \\ \left(\frac{\partial u}{\partial \nu} + \sigma u\right)|_{\partial \Omega} = 0 & t \geq 0 \end{cases} \quad (3.5.10)$$

定理 (3.5.10) 的解 $u(x,t)$ 在下述意义下关于初值和右端项是稳定的:

$$\forall \varepsilon > 0, \exists \eta = \eta(\varepsilon, T) > 0, \text{ 若 } \|\varphi_1 - \varphi_2\|_{L^2(\Omega)} \leq \eta, \|\nabla \varphi_1 - \nabla \varphi_2\|_{L^2} \leq \eta, \|\psi_1 - \psi_2\|_{L^2} \leq \eta, \|\varphi_1 - \varphi_2\|_{L^2(\partial \Omega)} \leq \eta, \|f_1 - f_2\|_{L^2([0,T] \times \Omega)} \leq \eta, \text{ 则以 } (\varphi_1, \psi_1) \text{ 为初值, 右端项为 } f_1 \text{ 的解 } u_1 \text{ 与以 } (\varphi_2, \psi_2) \text{ 为初值, } f_2 \text{ 为右端项的解 } u_2 \text{ 的差在 } 0 \leq t \leq T \text{ 上满足}$$

$$\|u_1 - u_2\|_{L^2(\Omega)} + \|\nabla u_1 - \nabla u_2\|_{L^2(\Omega)} \leq \varepsilon, \|\partial_t u_1 - \partial_t u_2\|_{L^2} \leq \varepsilon.$$

证明: 令 $u = u_1 - u_2, f = f_1 - f_2, \varphi = \varphi_1 - \varphi_2, \psi = \psi_1 - \psi_2$. 则

$$\begin{cases} \partial_t^2 u - \Delta u = f \\ u(x,0) = \varphi, \partial_t u(x,0) = \psi \\ \left(\frac{\partial u}{\partial \nu} + \sigma u\right)|_{\partial \Omega} = 0 \end{cases}$$

且 $\|\varphi\|_{L^2(\Omega)} \leq \eta, \|\nabla \varphi\|_{L^2(\Omega)} \leq \eta, \|\psi\|_{L^2(\Omega)} \leq \eta, \|\psi\|_{L^2} \leq \eta$.

$$\text{令 } E(t) = \int_{\Omega} \frac{1}{2} (\partial_t u)^2 + \frac{1}{2} |\nabla u|^2 dx + \int_{\partial \Omega} \frac{1}{2} |u|^2 dS, \text{ 则}$$

$$\frac{d}{dt} E(t) = \int_{\Omega} u_t f dx \leq \int_{\Omega} \frac{|f|^2 + |u_t|^2}{2} dx = \frac{1}{2} \int_{\Omega} |f|^2 dx + \frac{1}{2} \int_{\Omega} |u_t|^2 dx \leq \frac{1}{2} \|f\|^2 dx + E(t)$$

$$\Rightarrow \frac{d}{dt} (e^{-t} E(t)) \leq \frac{1}{2} e^{-t} \int_{\Omega} |f|^2 dx$$

$$\Rightarrow e^{-t} E(t) - E(0) \leq \frac{1}{2} \int_0^t e^{-s} \int_{\Omega} |f|^2 dx ds \Rightarrow E(t) \leq G_1(E(0) + \int_0^T \int_{\Omega} |f|^2 dx ds).$$

$$\text{令 } E_0(t) = \int_{\Omega} |u(x,t)|^2 dx, \text{ 则 } \frac{d}{dt} E_0(t) = 2 \int_{\Omega} u u_t dx \leq \int_{\Omega} |u|^2 dx + \int_{\Omega} |u_t|^2 dx$$

$$\leq \int_{\Omega} |u|^2 dx + 2E(t).$$

$$E(t) + \frac{d}{dt} E_0(t) \leq \int_{\Omega} |u|^2 dx + 2G_1(E(0) + \int_0^T \int_{\Omega} |f|^2 dx dt)$$

$$\Rightarrow E(t) \leq \int_{\Omega} |u|^2 dx + G_1(E(0) + \int_0^T \int_{\Omega} |f|^2 dx dt)$$

$$\leq C \left(\int_{\Omega} |\varphi|^2 dx + \int_{\Omega} (|\nabla \varphi|^2 + |\psi|^2) dx + \int_{\partial \Omega} |\psi|^2 dS + \int_0^T \int_{\Omega} |f|^2 dx dt \right)$$

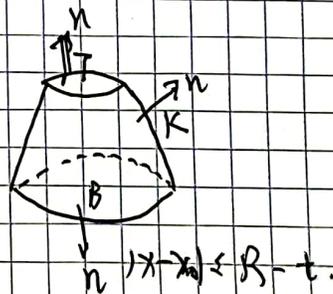
$$\leq C_2, \quad \forall t \in [0, T].$$

取 $\eta, \eta, G_1 < \varepsilon$, 即证.

能量估计与有限传播速度

$$\partial_t e(u) + \operatorname{div}(u_t \partial_x u) = 0.$$

$$\int_{\Delta} [\partial_t e(u) + \operatorname{div}(u_t \partial_x u)] dx dt = 0$$



在时轴 $|x-x_0|=|R-t|$ 上, $\phi(x,t) = |x-x_0| - |R-t|$. $\nabla\phi = (x-x_0, -2(R-t))$

$$n = -\frac{\nabla\phi}{|\nabla\phi|} = \frac{(x-x_0, -|R-t|)}{\sqrt{(x-x_0)^2 + |R-t|^2}} = \frac{-1}{\sqrt{2}} \left(\frac{x-x_0}{|x-x_0|}, \frac{-|R-t|}{|R-t|} \right)$$

$$\int_{\mathbb{R}^d} \int_{\Sigma} (\alpha \text{em}) + \text{div}(u_t \nabla u) dx dt$$

$$= \int_B \text{em} \cdot (u_t \nabla u, \text{em}) \cdot (0, -1) dx + \int_T (u_t \nabla u, \text{em}) \cdot (0, 1) dx$$

$$+ \int_K \frac{1}{\sqrt{2}} \left(u_t \nabla u \cdot \frac{x-x_0}{|x-x_0|} + \frac{\text{em} \cdot (R-t)}{|R-t|} \right) dS$$

$$= -\int_B \text{em}(t) dx + \int_T \text{em}(T) dx + \text{Flux}[0, T],$$

$$\text{Flux}[0, T] = -\frac{1}{\sqrt{2}} \int_K \left(u_t \nabla u \cdot \frac{x-x_0}{|x-x_0|} + \frac{\text{em} \cdot (R-t)}{|R-t|} \right) dS$$

$$= \frac{1}{\sqrt{2}} \int_K \left(\text{em} - u_t \nabla u \cdot \frac{x-x_0}{|x-x_0|} \right) dS$$

$$= \frac{1}{2\sqrt{2}} \int_K \left(u_t - \frac{x-x_0}{|x-x_0|} \nabla u \right)^2 dS + \frac{1}{2\sqrt{2}} \int_K \left(|\nabla u| - \frac{x-x_0}{|x-x_0|} \nabla u \right)^2 dS \geq 0.$$

$$\int_{\mathbb{R}^d} \int_B \text{em}(t) dx = \int_T \text{em}(T) dx + \text{Flux}[0, T]$$

Remark: ① 时间反演不变.

② Minkowski 时空

③ Hamiltonian system.



第四章 热传导方程

考虑方程 $\partial_t u - \Delta u = 0$ $\Omega \times \{t \geq 0\}$

初值条件: $u(x, 0) = \varphi(x)$ $\Omega \times \{t=0\}$

边值条件: Dirichlet $u|_{\partial\Omega} = g(x, t)$ $t \geq 0$.

Neumann $\frac{\partial u}{\partial n}|_{\partial\Omega} = g(x, t)$ $t \geq 0$

Robin $(\frac{\partial u}{\partial n} + \sigma u)|_{\partial\Omega} = g(x, t)$ $t \geq 0$.

解法: 1. 分离变量法 ($\Omega = [0, 1]^n$, $t \in \mathbb{R}^+$, $\Omega \cup \{0\}$ 域).

2. Fourier 变换方法.

$$\begin{cases} \partial_t u - \Delta u = f(x, t) & \text{in } \mathbb{R}^n \times [0, T) \\ u(x, 0) = g(x) & \text{on } \mathbb{R}^n \end{cases}$$

若 $f \in C^1(\mathbb{R}^n)$, 可定义 $\hat{f}(\xi) = \int_{\mathbb{R}^n} f(x) e^{-ix \cdot \xi} dx$. 性质: 若 $f \in \mathcal{S}(\mathbb{R}^n)$, 则有

(1) 令 $T_{x_0} f(x) = f(x-x_0)$, 则 $\widehat{T_{x_0} f}(\xi) = e^{-ix_0 \cdot \xi} \hat{f}(\xi)$

$$\widehat{T_{x_0} f}(\xi) = \int f(x-x_0) e^{-ix \cdot \xi} dx \stackrel{y=x-x_0}{=} \int f(y) e^{-iy \cdot \xi} dy e^{-ix_0 \cdot \xi} = \hat{f}(\xi) e^{-ix_0 \cdot \xi}$$

(2) 令 $S_\lambda f(x) = f(\lambda x)$, 则 $\widehat{S_\lambda f}(\xi) = \lambda^{-n} \hat{f}(\lambda^{-1} \xi)$

$$\widehat{S_\lambda f}(\xi) = \int f(\lambda x) e^{-ix \cdot \xi} dx \stackrel{y=\lambda x}{=} \int f(y) e^{-iy \cdot \lambda^{-1} \xi} dy \lambda^{-n} = \lambda^{-n} \hat{f}(\lambda^{-1} \xi)$$

(3) 对于多重指标 $\alpha = (\alpha_1, \dots, \alpha_n)$, 记 $|\alpha| = |\alpha_1| + \dots + |\alpha_n|$, $x^\alpha = x_1^{\alpha_1} \dots x_n^{\alpha_n}$,

$\partial^\alpha = \partial_{x_1}^{\alpha_1} \dots \partial_{x_n}^{\alpha_n}$, 则 $\widehat{\partial^\alpha f}(\xi) = (i\xi)^\alpha \hat{f}(\xi)$

$$\widehat{\partial^\alpha f}(\xi) = \int_{\mathbb{R}^n} \partial^\alpha f(x) e^{-ix \cdot \xi} dx = (-i)^\alpha \int_{\mathbb{R}^n} f(x) \partial_x^\alpha (e^{-ix \cdot \xi}) dx$$

$$= (-i)^\alpha (-i)^\alpha \int_{\mathbb{R}^n} f(x) e^{-ix \cdot \xi} dx = (i\xi)^\alpha \hat{f}(\xi)$$

$$(4) \widehat{(-ix)^\alpha f(x)} = \alpha^\alpha \widehat{f(x)}$$

$$\widehat{(-ix)^\alpha f(x)} = \int (-ix)^\alpha f(x) e^{-ix\zeta} dx = \int f(x) \alpha^\alpha (e^{-ix\zeta}) dx = \alpha^\alpha \int f(x) e^{-ix\zeta} dx = \alpha^\alpha \widehat{f(x)}$$

$$(5) \widehat{(f * g)(x)} = \int f(x-y) g(y) dy = \int f(y) g(x-y) dy, \quad \forall f, g \in \mathcal{S}(\mathbb{R}^n),$$

$$\widehat{f * g}(\zeta) = \widehat{f}(\zeta) \widehat{g}(\zeta)$$

$$\text{例: } \widehat{f(x)} = e^{-x^2}, x \in \mathbb{R}, \quad \widehat{f}(\zeta) = \frac{1}{\sqrt{\pi}} e^{-\frac{\zeta^2}{4}}$$

$$\widehat{f'}(\zeta) = \int e^{-x^2} e^{-ix\zeta} dx, \quad \widehat{f'}(\zeta) = \int e^{-x^2} (-ix) e^{-ix\zeta} dx$$

$$= \frac{i}{2} \int f'(x) e^{ix\zeta} dx = \frac{i}{2} \widehat{f'}(\zeta) = -\frac{\zeta}{2} \widehat{f}(\zeta) = -\frac{\zeta}{2} \widehat{f}(\zeta).$$

$$\text{且 } \widehat{f}(\zeta) = \int_{\mathbb{R}} e^{-x^2} dx = \sqrt{\pi} \quad \text{故} \quad \begin{cases} \widehat{f}(\zeta) + \frac{\zeta}{2} \widehat{f}(\zeta) = 0 \\ \widehat{f}(\zeta) = \frac{1}{\sqrt{\pi}} \end{cases}$$

$$\text{ODE, } \widehat{f}(\zeta) = \frac{1}{\sqrt{\pi}} e^{-\frac{\zeta^2}{4}}$$

$$\text{定义: } \widehat{f}(x) = \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} f(\zeta) e^{ix\zeta} d\zeta$$

$$\text{若 } f \in \mathcal{S}(\mathbb{R}^n), \quad \widehat{\widehat{f}} = f.$$

$$\text{claim: } (e^{-|\zeta|^2 t})_{\zeta, t}^{\vee} = \frac{1}{(4\pi t)^{\frac{n}{2}}} e^{-\frac{|x|^2}{4t}}$$

$$n=1 \text{ 时, } \widehat{G(x,t)} = \frac{1}{(2\pi)} \int e^{-|\zeta|^2 t} e^{ix\zeta} d\zeta, \quad \frac{\partial}{\partial x} G = \frac{1}{(2\pi)} \int e^{-|\zeta|^2 t} i\zeta e^{ix\zeta} d\zeta$$

$$= -\frac{i}{2t} \frac{1}{(2\pi)} \int (e^{-|\zeta|^2 t})' e^{ix\zeta} d\zeta = -\frac{x}{2t} G(x,t).$$

$$\text{且 } G(0,t) = \frac{1}{(2\pi)} \int e^{-|\zeta|^2 t} d\zeta = \frac{1}{(2\pi)^{\frac{n}{2}}} \int e^{-\eta^2} d\eta = \frac{1}{(4\pi t)^{\frac{n}{2}}}$$

$$\text{于 } \mathbb{R}, \quad G(x,t) = \frac{1}{(4\pi t)^{\frac{1}{2}}} e^{-\frac{x^2}{4t}}$$

$$n \geq 2, \quad \frac{1}{(2\pi)^n} \int e^{-|\zeta|^2 t} e^{ix\zeta} d\zeta = \frac{1}{(2\pi)^n} \int_{\mathbb{R}} e^{-\zeta_1^2 t + ix_1 \zeta_1} d\zeta_1 \cdots \int_{\mathbb{R}} e^{-\zeta_n^2 t + ix_n \zeta_n} d\zeta_n$$

$$= \frac{1}{(4\pi t)^{\frac{n}{2}}} e^{-\frac{x_1^2}{4t}} \cdots e^{-\frac{x_n^2}{4t}} = \frac{1}{(4\pi t)^{\frac{n}{2}}} e^{-\frac{|x|^2}{4t}}.$$

对方程 $\begin{cases} \partial_t u - \Delta u = 0 \\ u(x, 0) = u_0(x) \end{cases}$ 两边作 Fourier 变换, 可得

$$\begin{cases} \partial_t \hat{u} + (\xi_1^2 + \dots + \xi_n^2) \hat{u} = 0 \\ \hat{u}(\xi, 0) = \hat{u}_0(\xi) \end{cases} \quad \text{即} \quad \begin{cases} \partial_t \hat{u} + |\xi|^2 \hat{u} = 0 \\ \hat{u}(\xi, 0) = \hat{u}_0(\xi) \end{cases} \quad \rightarrow \quad \hat{u}(\xi, t) = e^{-|\xi|^2 t} \hat{u}_0(\xi)$$

于是, 取 Fourier 逆变换, 可得
$$u(x, t) = \frac{1}{(4\pi t)^{\frac{n}{2}}} e^{-\frac{|x|^2}{4t}} * u_0$$

$$= \frac{1}{(4\pi t)^{\frac{n}{2}}} \int e^{-\frac{|x-y|^2}{4t}} u_0(y) dy.$$

令 $K(x) = \frac{1}{(4\pi)^{\frac{n}{2}}} e^{-\frac{|x|^2}{4}}$ (Heat kernel), $K_t(x) = t^{-\frac{n}{2}} K(\frac{x}{\sqrt{t}})$

则 $u(x, t) = K_t * u_0.$

对于 $\{K_t\}_{t>0}$, 有 (i) $\int_{\mathbb{R}^n} K_t(x) dx = \int_{\mathbb{R}^n} K(x) dx = 1$

(ii) $\int_{\mathbb{R}^n} |K_t(x)| dx = 1$ (bdd).

(iii) $\forall \eta > 0, \int_{|x|>\eta} |K_t(x)| dx = \int_{|y|>\frac{\eta}{\sqrt{t}}} |K(y)| dy \xrightarrow{t \rightarrow 0^+} 0.$

事实上, 称 $\{K_t\}_{t>0}$ 是一族逼近恒等算子 (approximation to the identity).

Claim: $\lim_{t \rightarrow 0^+} u(x, t) = u_0(x)$, if u_0 continuous, bounded ($\exists M > 0, |u_0(x)| \leq M$).

$$u(x, t) - u_0(x) = \frac{1}{(4\pi t)^{\frac{n}{2}}} \int e^{-\frac{|y|^2}{4t}} u_0(x-y) dy - u_0(x)$$

$$= \frac{1}{(4\pi t)^{\frac{n}{2}}} \int e^{-\frac{|y|^2}{4t}} (u_0(x-y) - u_0(x)) dy$$

$$\stackrel{y = \sqrt{4t}z}{=} \frac{1}{(4\pi)^{\frac{n}{2}}} \int e^{-|z|^2} (u_0(x - \sqrt{4t}z) - u_0(x)) dz$$

$$\Rightarrow |u(x, t) - u_0(x)| \leq \frac{1}{(4\pi)^{\frac{n}{2}}} \int_{|z|>R} e^{-|z|^2} |u_0(x - \sqrt{4t}z) - u_0(x)| dz \quad (1)$$

$$+ \frac{1}{(4\pi)^{\frac{n}{2}}} \int_{|z|<R} e^{-|z|^2} |u_0(x - \sqrt{4t}z) - u_0(x)| dz \quad (2)$$

$$\textcircled{1} \leq \frac{M}{(4\pi)^{\frac{n}{2}}} \int_{|z|>R} e^{-|z|^2} dz < \varepsilon, \text{ 只要 } R \text{ 充分大.}$$

$$\textcircled{2}: \text{ 当 } t \rightarrow 0^+ \text{ 充分小时, } |u_0(x-2\sqrt{t}z) - u_0(x)| < \varepsilon, \forall |z| < R.$$

$$\text{于是, } \textcircled{2} \leq \varepsilon \frac{1}{(4\pi)^{\frac{n}{2}}} \int_{|z|<R} e^{-|z|^2} dz \leq C\varepsilon. \text{ 证毕.}$$

因此, $\lim_{t \rightarrow 0^+} u(x, t) = u_0(x).$

Rmk: (1) $u(x, t) \in C^\infty, \forall t > 0$

$$(2) \sup_{x \in \mathbb{R}^n} |u(x, t)| \leq \sup_{x \in \mathbb{R}^n} |u_0(x)|.$$

(3) 沿时间不能反向演化

(4) 无限传播速度.

非齐次方程
$$\begin{cases} \partial_t u - \Delta u = f(x, t) \\ u(x, 0) = u_0(x) \end{cases}$$

两边同时关于 x 取 Fourier 变换, 得
$$\begin{cases} \partial_t \hat{u} + |\xi|^2 \hat{u} = \hat{f}(\xi, t) \\ \hat{u}(\xi, 0) = \hat{u}_0(\xi). \end{cases}$$

$$\Rightarrow \hat{u}(\xi, t) = e^{-|\xi|^2 t} \hat{u}_0(\xi) + \int_0^t e^{-|\xi|^2(t-s)} \hat{f}(\xi, s) ds$$

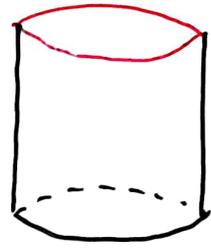
$$\Rightarrow u(x, t) = \frac{1}{(4\pi t)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|x-y|^2}{4t}} u_0(y) dy + \int_0^t \frac{1}{(4\pi(t-s))^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|x-y|^2}{4(t-s)}} f(y, s) dy ds$$

极大值原理.

考虑热传导方程
$$\begin{cases} \partial_t u - \Delta u = 0 & \text{in } \Omega \times \{t > 0\} \\ u(x, 0) = u_0(x) & \text{on } \Omega \times \{t = 0\} \\ u(x, t)|_{\partial\Omega} = h(x, t) \neq 0. \end{cases}$$

令 $Q_T = \Omega \times]0, T]$, 定义抛物边界 $\Gamma_T = \overline{Q_T} \setminus Q_T$.

定理 4.2.1. (极值原理) 令 $u(x,t)$ 在矩形 Γ_T 侧面上及底面



$R_T = \{ \alpha \leq x \leq \beta, 0 \leq t \leq T \}$ 上连续并且在矩形内部满足热传导方程 $u_t - \Delta_x u = 0$. 则它在抛物边界达到其最大值和最小值.

证明: 考虑最大值的情形. 令 $M = \max_{Q_T} u$, $m = \min_{\Gamma_T} u$. 若结论不成立,

则 $M > m$. 于是存在 $(x^*, t^*) \in \overset{\circ}{R}_T$ 且 $u(x^*, t^*) = M$. 于是, $u_t(x^*, t^*) \geq 0$

$\Delta_x u(x^*, t^*) \leq 0$. 故 $(u_t - \Delta_x u)(x^*, t^*) \geq 0$

构造主函数 $v(x,t) = u(x,t) + \frac{M-m}{4l^2} |x-x^*|^2$, 其中 $l = \beta - \alpha$. 则

$$\max_{\Gamma_T} v(x,t) \leq \max_{\Gamma_T} u(x,t) + \frac{M-m}{4} = m + \frac{M-m}{4} \leq M$$

$$\max_{R_T} v(x,t) \geq \max_{Q_T} u(x,t) = M$$

故 v 在内部达到最大值. (未必是 x^*, t^*). 设 v 在 $(x,t) \in \overset{\circ}{R}_T$ 取最大值.

则 $v_t(x,t) \geq 0$, $\Delta_x v(x,t) \leq 0$ 于是 $(v_t - \Delta_x v)(x,t) \geq 0$.

但是, $v_t = u_t$, $\Delta_x v = \Delta_x u + \frac{M-m}{2l^2}$. 于是,

$$(u_t - \Delta_x u - \frac{M-m}{2l^2})(x,t) \geq 0. \text{ 即 } (u_t - \Delta_x u)(x,t) \geq \frac{M-m}{2l^2} > 0. \text{ 矛盾!}$$

Remark: 若 $u_t - \Delta_x u \leq 0$, 则它在抛物边界达到最大值.

定理 4.2.2 (唯一性和稳定性) 热传导方程的边值问题

$$\begin{cases} u_t - \Delta_{xx} u = f & R_T^* \\ u(x,0) = \phi(x) \\ u(\alpha,t) = u_1(t), u(\beta,t) = u_2(t) \end{cases}$$

在 R_T 上的解是唯一的. 而且连续地依赖于边界 Γ_T 上

给定的初始条件和边界条件.

证明: 设 u_1, u_2 是两个解. 令 $\tilde{u} = u_1 - u_2$. 则 \tilde{u} 满足
$$\begin{cases} \partial_t \tilde{u} - \partial_x^2 \tilde{u} = 0 & \text{in } R_T \\ \tilde{u}(0, t) = 0, \tilde{u}(l, t) = 0 \\ \tilde{u}(x, 0) = 0 \end{cases} \quad (2)$$

由初值原理, \tilde{u} 在 R_T 上的最大值、最小值都在边界取到. 故 \tilde{u} 的最大值、最小值都是 0. 故 $\tilde{u} \equiv 0$ in R_T . 唯一性得证.

下面证明稳定性. 令 u_1, u_2 满足
$$\begin{cases} \partial_t u_1 - \partial_x^2 u_1 = f \\ u_1(0, t) = \mu_1^1, u_1(l, t) = \mu_1^2 \\ u_1(x, 0) = \varphi_1 \end{cases} \quad u_2 \text{ 满足 } \begin{cases} \partial_t u_2 - \partial_x^2 u_2 = f \\ u_2(0, t) = \mu_2^1, u_2(l, t) = \mu_2^2 \\ u_2(x, 0) = \varphi_2 \end{cases} \quad \mu_1^2, \mu_2^2$$

令 $u = u_1 - u_2$. 则 u 满足
$$\begin{cases} \partial_t u - \partial_x^2 u = 0 \\ u(0, t) = \mu_1^1 - \mu_2^1, u(l, t) = \mu_1^2 - \mu_2^2 \\ u(x, 0) = \varphi_1 - \varphi_2 \end{cases}$$

由初值原理, $\max_{R_T} u \leq \max_{\bar{I}_T} u \leq \max_{0 \leq t \leq T} (\mu_1^1 - \mu_2^1 + |\mu_1^2 - \mu_2^2|) + \max_{\alpha \leq x \leq \beta} |\varphi_1 - \varphi_2|$

且 $\min_{R_T} u \geq \min_{\alpha \leq x \leq \beta} \{ \min_{0 \leq t \leq T} (\mu_1^1 - \mu_2^1 + \mu_1^2 - \mu_2^2), \min_{\alpha \leq x \leq \beta} |\varphi_1 - \varphi_2| \}$

$\geq \min_{\alpha \leq x \leq \beta} (|\mu_1^1 - \mu_2^1| - |\mu_1^2 - \mu_2^2|) + \min_{\alpha \leq x \leq \beta} |\varphi_1 - \varphi_2|$

于是 $|u(x, t)| \leq \max_{\alpha \leq x \leq \beta} (|\mu_1^1 - \mu_2^1| + |\mu_1^2 - \mu_2^2|) + \max_{\alpha \leq x \leq \beta} |\varphi_1 - \varphi_2|$

第三类边值问题
$$\begin{cases} \partial_t u - \partial_x^2 u = 0 \\ u(0, t) = \mu_1(h), u(l, t) = \mu_2(h) \quad (u_x + hu)(l, t) = \mu_2(h) \quad h > 0 \\ u(x, 0) = \varphi(h) \end{cases}$$

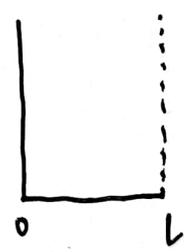
要证明唯一性, 只需证明
$$(*) \quad \begin{cases} \partial_t u - \partial_x^2 u = 0 \\ u(0, t) = 0, u(l, t) = 0 \quad (u_x + hu)(l, t) = 0 \\ u(x, 0) = 0 \end{cases} \quad \text{只有零解.}$$

否则, (*) 有非零解. 则此非零解 u 在 R_T 上有正的最大值或负的最小值.

由初值原理, 正的最大值只能在边界取到. 由于 $u(0, t) = 0$,

$u(x, 0) = 0$. 故正的最大值只能在 $x=l$ 上取到. 此时,

$u_x(l, t^+) > 0$, 且 $u(l, t^+) = M > 0$. 故 $(u_x + hu)(l, t^+) > 0$. 矛盾!



类似可证 w 在 R_T 上没有负的最小值. 因此 (1) 只有空解.

(3)

作业: 证明稳定性: $\forall (x,t) \in R_T,$

$$|u_1(x,t) - u_2(x,t)| \leq \max \left(\max_{0 \leq t \leq T} |u_1'(t) - u_2'(t)|, \max_{0 \leq x \leq l} |\varphi_1(x) - \varphi_2(x)|, \max_{0 \leq t \leq T} |u_1(l,t) - u_2(l,t)| \right).$$

再考虑第二类边值问题

$$\begin{cases} u_t - u_{xx} = 0 \\ u(0,t) = u_1(t), \quad u(l,t) = u_2(t) \\ u(x,0) = \varphi(x) \end{cases}$$

需证明唯一性. 只要证明

$$\begin{cases} u_t - u_{xx} = 0 \\ u(0,t) = 0, \quad u_x(l,t) = 0 \\ u(x,0) = 0 \end{cases}$$

只有空解. 仿照第二类边值问题的证明得不到矛盾.

令 $\tilde{u} = w(x)u$, 则 $u = \frac{\tilde{u}}{w(x)}$, 故 $u_x = \frac{\tilde{u}_x}{w(x)}$, $u_{xx} = -\frac{w_{xx}}{w^2} \tilde{u} + \frac{1}{w} \tilde{u}_{xx}$

$u_t - u_{xx} = \left(-\frac{w_{xx}}{w^2} + 2\frac{w_x^2}{w^3} \right) \tilde{u} - 2\frac{w_x}{w^2} \tilde{u}_x + \frac{1}{w} \tilde{u}_{xx}$. 于是,

$$0 = u_t - u_{xx} = \frac{1}{w} (\tilde{u}_t - \tilde{u}_{xx}) + 2\frac{w_x}{w^2} \tilde{u}_x + \left(\frac{w_{xx}}{w^2} - 2\frac{w_x^2}{w^3} \right) \tilde{u}$$

$$\Rightarrow \begin{cases} \tilde{u}_t - \tilde{u}_{xx} = - \left(\frac{w_{xx}}{w^2} - 2\frac{w_x^2}{w^3} \right) \tilde{u} - 2\frac{w_x}{w^2} \tilde{u}_x \\ \tilde{u}(0,t) = 0, \quad \tilde{u}_x(l,t) = w'_x(l)u(l,t) \\ \tilde{u}(x,0) = 0 \end{cases}$$

取 $w(x) = -x+l+1$, 则 $w'_x = -1$. 且 $w(x) > 0, \forall x \in [0,l]$. 于是,

$$\begin{cases} \tilde{u}_t - \tilde{u}_{xx} = 2\frac{1}{(x-l+1)^2} \tilde{u} + \frac{2}{-x+l+1} \tilde{u}_x \\ \tilde{u}(0,t) = 0, \quad (\tilde{u}_x + \tilde{u})(l,t) = 0 \\ \tilde{u}(x,0) = 0 \end{cases}$$

令 $v(x,t) = e^{-\lambda t} \tilde{u}(x,t)$, 则 $\tilde{u}(x,t) = e^{\lambda t} v(x,t)$. 故 $v(x,t)$ 满足

$$\begin{cases} v_t - v_{xx} + \left(\lambda - \frac{2}{(x-l+1)^2} \right) v + \frac{2}{x-l+1} v_x = 0 \\ v(0,t) = 0, \quad (v_x + v)(l,t) = 0 \\ v(x,0) = 0 \end{cases}$$



取 $\lambda \gg 2$, 则 $\lambda - \frac{2}{(x-t)^2} > 0, \forall x \in [0, 1]$.

Claim: 若 v 在 $(x_*, t_*) \in R_T$ 达到正的最大值, 则 $(x_*, t_*) \in \Gamma_T$.

否则, 若 $(x_*, t_*) \in R_T^o$ 则 $v_x(x_*, t_*) = 0, v_t(x_*, t_*) \geq 0, \lambda_x^2 v(x_*, t_*) \leq 0$.

于是, $(v_t - v_{xx} + \underbrace{\lambda - \frac{2}{(x-t)^2}}_{\text{严格正}})v + \frac{2}{x-t-1} v_x(x_*, t_*) > 0$. 矛盾!

由于 $v(0, t) = 0, v(x, 0) = 0$ 故 v 只能在右边界的某处 (\bar{x}, \bar{t}) 取到.

此时, $v_x(\bar{x}, \bar{t}) \geq 0$. 于是, $(v + v_x)(\bar{x}, \bar{t}) \geq v(\bar{x}, \bar{t}) > 0$. 矛盾!

定理. 设 $u \in C_1^2(\mathbb{R}^n \times [0, T]) \cap C(\mathbb{R}^n \times [0, T])$ 满足 $\begin{cases} \Delta u - u = 0 \\ u(x, 0) = \varphi(x) \end{cases}$ 且 $|u(x, t)| \leq A e^{a|x|^2}$,

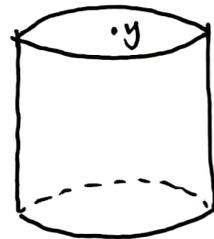
$\forall x \in \mathbb{R}^n, 0 \leq t \leq T, A, a > 0$. 则有 $\sup_{x, t \in \mathbb{R}^n \times [0, T]} u(x, t) \leq \max_{x \in \mathbb{R}^n} \varphi(x)$.

证明: 只要证明 $u(y, t) \leq \max_{x \in \mathbb{R}^n} \varphi(x)$.

Step 1. 先设 T 充分小: ($4aT < 1$)

~~$\forall r > 0$, 在 $B(y, r) \times [0, T]$ 上应用极值原理,~~

~~可得 $u(y, T) \leq \max_{\Gamma_T} u$.~~



令 $|x-y|=r, 0 \leq t \leq T$. ~~要估计 $u(x, t)$.~~

令 $v(x, t) = u(x, t) - \frac{u}{(T+t-t)^2} e^{\frac{|x-y|^2}{4(T+t-t)}}$, 则 v 也是抛物方程的解.

~~且 $v(x, 0) \leq u(x, 0) \leq \max_x \varphi(x)$~~ 故 $\max_{\bar{Q}_T} v = \max_{\Gamma_T} v$.

于是: $v(x, 0) \leq u(x, 0) \leq \max_{x \in \mathbb{R}^n} \varphi(x)$.



⑤

例证: $v(x,t) \leq A e^{a|x|^2} - \frac{\mu}{(T+t)^{\frac{1}{2}}} e^{\frac{r^2}{4(T+t)}} \quad \forall T > 0, s.t. \frac{1}{4(T+t)} = a+r, r > 0.$

$$\leq A a^{(1+r)^2} - \mu (4(1+r))^{\frac{n}{2}} e^{(a+r)r^2} \xrightarrow{r \rightarrow +\infty} -\infty$$

故当 r 充分大时, $v(x,t) \leq \max_{x \in \mathbb{R}^n} \varphi(x).$

令 $\mu \rightarrow 0$, 则 $u(x,t) \leq \max_{x \in \mathbb{R}^n} \varphi(x).$

Step 2. 若 $4aT \geq 1$. 选 $\tau T_1, s.t. 4aT_1 < 1$. 在 $[0, T_1], [T_1, 2T_1], \dots, [kT_1, (k+1)T_1]$ 上不断重复上述过程, 直到 $(k+1)T_1 > T$. 即可.

能量估计: 初值问题 $\begin{cases} u_t - \Delta u = f & \text{in } \Omega \times [0, T] \\ u(x, 0) = \varphi(x) & \text{in } \Omega \\ u(x, t)|_{\partial\Omega \times [0, T]} = g(x, t) \end{cases}$ 只有一个解 $u \in C_1(\bar{Q}_T).$

证明: 只需证明 $f \equiv 0, \varphi \equiv 0, g \equiv 0$ 时只有零解.

$$\int_{\Omega} u(u_t - \Delta u) = 0 \Rightarrow \frac{1}{2} \frac{d}{dt} \int_{\Omega} u^2 dx - \int_{\Omega} \nabla \cdot (u \nabla u) dx + \int_{\Omega} |\nabla u|^2 dx = 0$$

$$\Rightarrow \frac{d}{dt} \int_{\Omega} |u|^2 dx - \int_{\partial\Omega} u \frac{\partial u}{\partial n} dS + \int_{\Omega} |\nabla u|^2 dx = 0$$

$$\Rightarrow \frac{d}{dt} \int_{\Omega} |u|^2 dx = - \int_{\Omega} |\nabla u|^2 dx \leq 0$$

$$\Rightarrow \int_{\Omega} |u(x, t)|^2 dx \leq \int_{\Omega} |u(x, 0)|^2 dx = 0,$$

故 $u(x, t) \equiv 0.$



第五章 位势方程

§5.1. 基本解与 Green 函数.

$$\Delta u = f \quad \text{Poisson 方程}$$

当 $f=0$ 时, $\Delta u=0$ 调和方程. 称 u 是调和函数.

如果 $u \in C^2(\Omega)$, 并在 Ω 上 $-\Delta u \leq 0$, 称 u 是下调和的 (上)

若 $\Delta u = \delta$, 则称 u 是基本解. 特别地, $\Delta u=0, \forall x \neq 0$.

若 u 是径向函数. 即 $u(x) = u(|x|)$, 则 $(\partial_r^2 + \frac{n-1}{r} \partial_r)u = 0$.

$$\text{令 } v = \partial_r u. \text{ 则 } \partial_r v + \frac{n-1}{r} v = 0. \Rightarrow v(r) = C_1 r^{-(n-1)}$$

$$\text{即 } \partial_r u = C_1 r^{-(n-1)} \Rightarrow u = -\frac{C_1}{n-2} r^{-(n-2)} + C_2 \quad n \neq 2$$

$$u = C_1 \ln r + C_2 \quad n = 2.$$

$$\text{定义 } k(x) = \begin{cases} \frac{1}{2\pi} \ln|x| & n=2 \\ \frac{1}{n(n-2)\omega_n} |x|^{-(n-2)} & n \geq 3 \end{cases}$$

ω_n 是 \mathbb{R}^n 中单位球的体积.

$$(n=3. -\frac{1}{4\pi} |x|^{-1})$$

称 $k(x)$ 为调和方程的基本解.

Green 公式: 若 $u, v \in C^2(\Omega) \cap C^1(\bar{\Omega})$, 则

$$\int_{\Omega} u \Delta v dx = \int_{\Omega} \nabla \cdot (u \nabla v) dx = - \int_{\Omega} \nabla u \cdot \nabla v dx$$

$$= \int_{\partial \Omega} u \frac{\partial v}{\partial n} dS - \int_{\Omega} \nabla u \cdot \nabla v dx$$

$$\text{同样地, } \int_{\Omega} v \Delta u dx = \int_{\partial \Omega} v \frac{\partial u}{\partial n} dS - \int_{\Omega} \nabla v \cdot \nabla u dx$$

$$\Rightarrow \int_{\Omega} (u \Delta v - v \Delta u) dx = \int_{\partial \Omega} (u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n}) dS. \quad (\Delta \Delta)$$



Claim: $n=3$ 若 $u \in C^2(\Omega) \cap C^1(\bar{\Omega})$ 且 $\Delta u = 0$ 在 Ω . 则 $\forall x_0 \in \Omega$,

$$u(x_0) = \frac{1}{4\pi} \int_{\partial\Omega} \left[-u \frac{\partial}{\partial n} \left(\frac{1}{|x-x_0|} \right) + \frac{1}{|x-x_0|} \frac{\partial u}{\partial n} \right] dS \quad (**)$$

证明: 由 $\Delta u = 0$ 是调和不变性. 只需证明 $x_0 = 0$ 的情况. 即

$$u(0) = \frac{1}{4\pi} \int_{\partial\Omega} \left[-u \frac{\partial}{\partial n} \left(\frac{1}{|x|} \right) + \frac{1}{|x|} \frac{\partial u}{\partial n} \right] dS. \quad (*)$$

若 (*) 成立. 对 $u(\cdot + x_0)$ 应用 (*). 可得

$$\begin{aligned} u(x_0) &= \frac{1}{4\pi} \int_{\partial\Omega} \left[-u(y+x_0) \frac{\partial}{\partial n} \left(\frac{1}{|y|} \right) + \frac{1}{|y|} \frac{\partial u}{\partial n}(y+x_0) \right] dS \\ &\stackrel{y+x_0=x}{=} \frac{1}{4\pi} \int_{\partial\Omega} \left[-u(x) \frac{\partial}{\partial n} \left(\frac{1}{|x-x_0|} \right) + \frac{1}{|x-x_0|} \frac{\partial u}{\partial n}(x) \right] dS. \end{aligned}$$

现在证明 (*). 令 $\Omega_\varepsilon = \Omega \setminus \bar{B}_\varepsilon$. 则 $\partial\Omega_\varepsilon = \partial\Omega \cup \partial B_\varepsilon$.

且在 Ω_ε 上, $\Delta \left(\frac{1}{4\pi|x|} \right) = 0$, $\Delta u = 0$. 由 Green 第二公式

$$\begin{aligned} 0 &= \frac{1}{4\pi} \int_{\partial\Omega} \left(-u \frac{\partial}{\partial n} \left(\frac{1}{|x|} \right) + \frac{1}{|x|} \frac{\partial u}{\partial n} \right) dS \\ &\quad + \frac{1}{4\pi} \int_{\partial B_\varepsilon} \left(-u \frac{\partial}{\partial n} \left(\frac{1}{|x|} \right) + \frac{1}{|x|} \frac{\partial u}{\partial n} \right) dS \quad (1) \end{aligned}$$

$$(1) = \frac{1}{4\pi} \int_{\partial B_\varepsilon} u \frac{\partial}{\partial r} \left(\frac{1}{r} \right) + \frac{1}{r} \left(-\frac{\partial u}{\partial r} \right) dS = \underbrace{-\frac{1}{4\pi\varepsilon^2} \int_{\partial B_\varepsilon} u dS}_{(1a)} - \underbrace{\frac{1}{4\pi\varepsilon} \int_{\partial B_\varepsilon} \frac{\partial u}{\partial r} dS}_{(1b)}$$

$$(1a) = -\frac{1}{4\pi\varepsilon^2} \int_{\partial B_\varepsilon} (u(x) - u(0)) dS - u(0)$$

$$\begin{aligned} \left| \frac{1}{4\pi\varepsilon^2} \int_{\partial B_\varepsilon} (u(x) - u(0)) dS \right| &\leq \frac{1}{4\pi\varepsilon^2} \int_{\partial B_\varepsilon} |u(x) - u(0)| dS \leq \max_{\partial B_\varepsilon} |\nabla u| \frac{1}{4\pi\varepsilon^2} \int_{\partial B_\varepsilon} |x| dS \\ &\leq \varepsilon \max_{\bar{B}_\varepsilon} |\nabla u| \leq C\varepsilon \rightarrow 0, \text{ as } \varepsilon \rightarrow 0. \end{aligned}$$

$$(1b) = \frac{1}{4\pi\varepsilon} \int_{\partial B_\varepsilon} \vec{n} \cdot \nabla u dS = \frac{1}{4\pi\varepsilon} \int_{B_\varepsilon} \Delta u dx = 0, \quad \forall \varepsilon > 0.$$



于是 (1) $\rightarrow -u(x)$, as $\varepsilon \rightarrow 0$.

(3)

因此, $u(x) = \frac{1}{4\pi} \int_{\partial\Omega} \left[-u \frac{\partial u}{\partial n} \left(\frac{1}{|x|} \right) + \frac{1}{|x|} \frac{\partial u}{\partial n} \right] dS$.

Claim: $n=2$, $\forall x_0 \in \Omega$,

$$u(x) = \frac{1}{2\pi} \int_{\partial\Omega} \left[u \frac{\partial}{\partial n} (\log|x-x_0|) + \log|x-x_0| \frac{\partial u}{\partial n} \right] dS.$$

证明留作业.

以上公式中的问题在于未知哪种边值, 无法知道 $u, \frac{\partial u}{\partial n}$ 在边值的值!

解决办法: 若 $g(x)$ 在 Ω 上调和, 且 $g|_{\partial\Omega} = \frac{1}{4\pi|x-x_0|}|_{\partial\Omega}$. 则由 Green

第二公式, $\int_{\partial\Omega} \left(-u \frac{\partial g}{\partial n} + g \frac{\partial u}{\partial n} \right) dS = 0$.

由 (**), $u(x) = \int_{\partial\Omega} \left(-u \frac{\partial}{\partial n} \left(\frac{1}{4\pi|x-x_0|} - g \right) + \left(\frac{1}{4\pi|x-x_0|} - g \right) \frac{\partial u}{\partial n} \right) dS$

令 $G(x) = -\frac{1}{4\pi|x-x_0|} + g(x)$, 则 $G|_{\partial\Omega} = 0$. 故

$$u(x) = \int_{\partial\Omega} u \frac{\partial G}{\partial n} dS. \quad (\Delta)$$

定义 (Green 函数) Ω 上的单子- Δ 的 Green 函数, 满足

(1) $G(x) \in C^2(\Omega)$, 且 $\Delta G = 0$, 除了 $x = x_0$.

(2) $G(x) = 0, \forall x \in \partial\Omega$.

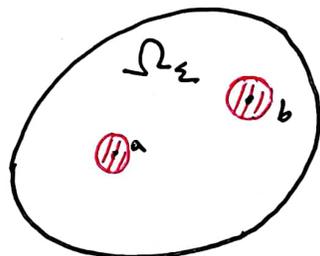
(3) $G(x) + \frac{1}{4\pi|x-x_0|}$ 在 x_0 有限, 处处二阶连续可导, 且在 x_0 调和.

性质: $G(x, x_0) = G(x_0, x), \forall x \neq x_0$. (对称原理)

对 $u(x) = G(x, a), v(x) = G(x, b)$ 在 Ω_ε 上应用

Green 第二公式, 可得

$$0 = \int_{\Omega_\varepsilon} (u \Delta v - v \Delta u) dx = \int_{\partial\Omega_\varepsilon} \left(u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \right) dS$$

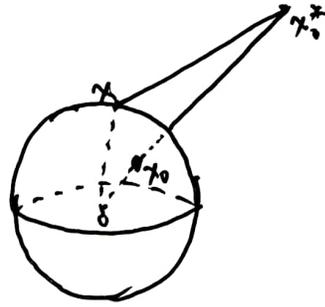


2. 球面. $\Omega = B_R(0) \subset \mathbb{R}^3$

(5)

若 $x_0 \in B_R(0)$, 取 $0-x_0$ 延长线上一点 x_0^*

$$\text{令 } G(x, x_0) = -\frac{1}{4\pi|x-x_0|} + \frac{C}{4\pi|x-x_0^*|}$$



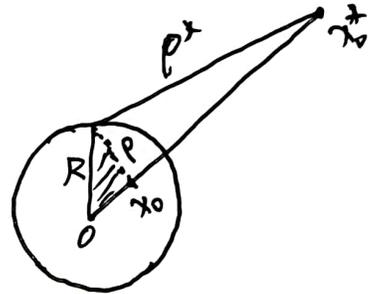
则 (i) G 在 $B_R(0) \setminus \{x_0\}$ 上二阶连续可微.

(ii) $G(x, x_0) + \frac{1}{4\pi|x-x_0^*|}$ 在 $B_R(0)$ 上二阶连续可微.

(iii). 选取 x_0^*, C , s.t. $G(x, x_0) = 0, \forall |x|=1$.

$$\text{令 } \rho = |x-x_0|, \rho^* = |x-x_0^*|. \text{ s.t. } \forall |x|=1, \frac{\rho^*}{\rho} = C.$$

若 $\frac{\rho^*}{\rho} = \Delta_1 \propto \Delta_2$ 则 $\frac{\rho^*}{\rho} = \frac{|x_0^*|}{R} (|x|=1)$.



$$\text{选取 } x_0^*, \text{ s.t. } \frac{|x_0^*|}{R} = \frac{R}{|x_0|} \text{ 即 } x_0^* = \frac{R^2}{|x_0|^2} x_0$$

$$\text{则 } \frac{\rho^*}{\rho} = \frac{R}{|x_0|} \text{ 故 } G(x, x_0) = -\frac{1}{4\pi|x-x_0|} + \frac{R}{|x_0|} \frac{1}{4\pi|x-x_0^*|}, x_0^* = \frac{R^2}{|x_0|^2} x_0.$$

$$\nabla G = \frac{x-x_0}{4\pi|x-x_0|^3} - \frac{R}{|x_0|} \frac{x-x_0^*}{4\pi|x-x_0^*|^3}$$

$$\text{当 } |x|=1, \rho^* = \frac{R}{|x_0|} \rho. \text{ 故 } \nabla G(x, x_0) = \frac{x-x_0}{4\pi|x-x_0|^3} - \frac{R}{|x_0|} \left(\frac{|x_0|}{R}\right)^3 \frac{x-x_0^*}{4\pi|x-x_0|^3}$$

$$\Rightarrow \nabla G(x_0, x_0) = \left(1 - \frac{|x_0|^2}{R^2}\right) \frac{x}{4\pi|x-x_0|^3} - \frac{1}{4\pi|x-x_0|^2} \left(x_0 - \frac{|x_0|^2}{R^2} x_0^*\right)$$

$$= \frac{R^2|x_0|^2}{R^2} \frac{x}{4\pi|x-x_0|^3}$$

$$\Rightarrow \frac{\partial G}{\partial n} = \frac{x \cdot \nabla G}{R} = \frac{R^2|x_0|^2}{R} \frac{1}{4\pi|x-x_0|^3}$$

$$\Rightarrow u(x) = \frac{R^2|x_0|^2}{4\pi R} \int_{|y|=R} \frac{\varphi(y)}{|x-y|^3} dS$$

$$\text{令 } K(x, y) = \frac{R^2|x_0|^2}{4\pi R|x-y|^3}, \text{ 则 } u(x) = \int_{|y|=R} K(x, y) \varphi(y) dS_{|y|=R}.$$



作业: 分别用 Green 函数法和分离变量法求解 = 维圆盘上的 Dirichlet

$$\text{问题 } \begin{cases} \Delta u = 0 & \text{in } B_{R^2(0)} \\ u = \varphi & \text{on } \partial B_{R^2(0)} \end{cases}$$

§2. 调和函数的性质

A. 平均值性质

极坐标公式: $\int_{R^n} f(x) dx = \int_0^\infty \left(\int_{\partial B_r(x)} f(y) dS(y) \right) dr$

$$\frac{1}{V(B_r(x))} \int_{B_r(x)} f dx = \int_{\partial B_r(x)} f(y) dS(y)$$

定义: 若 $u \in C^1(\Omega)$. (i) 称 u 满足平均值性质, 如果 $u(x) = \frac{1}{4\pi r^2} \int_{\partial B_r(x)} u(y) dS_y$,

$\forall B_r(x) \subset \Omega$. (ii) 称 u 满足球平均值性质, 如果

$$u(x) = \frac{3}{4\pi r^3} \int_{B_r(x)} u(y) dy, \quad \forall B_r(x) \subset \Omega.$$

注: 两个定义等价. 若 (i) 成立, 则 $\int_{B_r(x)} u(y) dy = \int_0^r \int_{\partial B_\rho(x)} u(y) dS_y d\rho$

$$= \int_0^r 4\pi \rho^2 u(x) d\rho = \frac{4\pi}{3} r^3 u(x). \quad \text{即 } u(x) = \frac{3}{4\pi r^3} \int_{B_r(x)} u(y) dy.$$

反之, 若 (ii) 成立. $\frac{4\pi}{3} r^3 u(x) = \int_0^r \int_{\partial B_\rho(x)} u(y) dS_y d\rho$

对 r 求导, 可得 $4\pi r^2 u(x) = \int_{\partial B_r(x)} u(y) dS_y$. 故 (i) 成立.

定理 2.1. 若 $u \in C^2(\Omega)$ 在 Ω 内调和, 则 u 满足平均值性质.

证明: 若 $u \in C^2(\Omega)$, 且 $\Delta u = 0$. 则 $\forall B_r(x) \subset \Omega$, $\forall \rho < r$. 由散度定理,

$$0 = \int_{B_\rho(x)} \Delta u dx = \int_{\partial B_\rho(x)} \frac{\partial u}{\partial n} dS_y = \int_{\partial B_\rho(x)} \frac{y-x}{\rho} \cdot (\nabla u)(y) dS_y$$

$$\stackrel{y-x=w}{=} \rho^2 \int_{|w|=1} w \cdot (\nabla u)(x+pw) dw = \rho^2 \int_{|w|=1} \frac{d}{dp} (u(x+pw)) dw$$

$$= \rho^2 \frac{d}{dp} \int_{|w|=1} u(x+pw) dw$$



作业: 分别用 Green 函数法和分离变量法求解二维圆盘上的 Dirichlet

$$\text{问题 } \begin{cases} \Delta u = 0 & \text{in } B_R(0) \\ u = \varphi & \text{on } \partial B_R(0) \end{cases}$$

§2. 调和函数的性质

A. 平均值性质

极坐标公式: $\int_{R^n} f(x) dx = \int_0^\infty \left(\int_{\partial B_r(x)} f(y) dS(y) \right) dr$

$$\frac{1}{r^n} \left(\int_{B_r(x)} f dx \right) = \int_{\partial B_r(x)} f(y) dS(y)$$

定义: 若 $u \in C^1(\Omega)$. (i) 称 u 满足平均值性质, 如果 $u(x) = \frac{1}{4\pi r^2} \int_{\partial B_r(x)} u(y) dS_y$,

$\forall B_r(x) \subset \Omega$. (ii) 称 u 满足第二平均值性质, 如果

$$u(x) = \frac{3}{4\pi r^3} \int_{B_r(x)} u(y) dy, \quad \forall B_r(x) \subset \Omega.$$

注: 两个定义等价. 若 (i) 成立, 则 $\int_{B_r(x)} u(y) dy = \int_0^r \int_{\partial B_\rho(x)} u(y) dS(y) d\rho$
 $= \int_0^r 4\pi \rho^2 u(x) d\rho = \frac{4\pi}{3} r^3 u(x)$. 即 $u(x) = \frac{3}{4\pi r^3} \int_{B_r(x)} u(y) dy$.

反之, 若 (ii) 成立. $\frac{4\pi}{3} r^3 u(x) = \int_0^r \int_{\partial B_\rho(x)} u(y) dS(y) d\rho$

对 r 求导, 可得 $4\pi r^2 u(x) = \int_{\partial B_r(x)} u(y) dS(y)$. 故 (i) 成立.

定理 2.1. 若 $u \in C^2(\Omega)$ 在 Ω 内调和, 则 u 满足平均值性质.

证明: 若 $u \in C^2(\Omega)$, 且 $\Delta u = 0$. 则 $\forall B_r(x) \subset \Omega$, $\forall 0 < \rho < r$. 由散度定理,

$$0 = \int_{B_\rho(x)} \Delta u dx = \int_{\partial B_\rho(x)} \frac{\partial u}{\partial n} dS(y) = \int_{\partial B_\rho(x)} \frac{y-x}{\rho} \cdot (\nabla u)(y) dS(y)$$

$$\stackrel{y-x=w}{=} \rho^2 \int_{|w|=1} w \cdot (\nabla u)(x+\rho w) dw = \rho^2 \int_{|w|=1} \frac{d}{d\rho} (u(x+\rho w)) dw$$



(7)

于是, $\frac{d}{dr} \int_{|w|=1} u(x+rw) dw = 0$. 因此,

$$4\pi u(x) = \int_{|w|=1} u(x) dw = \int_{|w|=1} u(x+rw) dw$$

$$\Rightarrow u(x) = \frac{1}{4\pi r^2} \int_{|y-x|=r} u(y) dS(y)$$

定理 2.2. 若 $u \in C(\Omega)$ 在 Ω 内具有平均值性质, 则 u 在 Ω 上光滑且调和.

证明: 令 $\varphi \in C_0^\infty(B_1(0))$, $\int \varphi = 1$ 且 φ radial 即 $\varphi(x) = \varphi(|x|)$. 于是, $\int \varphi(r) r^{n-1} dr = \frac{1}{|w_n|}$.

令 $\varphi_\varepsilon(x) = \frac{1}{\varepsilon^n} \varphi(\frac{x}{\varepsilon})$, $\varepsilon > 0$. 则 $\forall x \in \Omega$, $\exists \varepsilon < \text{dis}(x, \partial\Omega)$, 则

$$\text{claim: } u(x) = (u * \varphi_\varepsilon)(x),$$

$$\text{In fact, } \int u(y) \varphi_\varepsilon(x-y) dy \stackrel{\substack{x \in \Omega, |x-y| < \varepsilon \\ \text{则 } y \in \Omega}}{=} \int_{\Omega} u(y) \varphi_\varepsilon(x-y) dy \stackrel{\varphi \text{ radial}}{=} \int_{\Omega} u(y) \varphi_\varepsilon(y-x) dy$$

$$\stackrel{z=y-x}{=} \int_{\Omega-x} u(z+x) \varphi_\varepsilon(z) dz \stackrel{\text{supp } \varphi}{=} \int_{B_\varepsilon(0)} u(z+x) \varphi_\varepsilon(z) dz$$

$$\stackrel{z=zy}{=} \int_{B_\varepsilon(0)} u(zy+x) \varphi(y) dy$$

$$\stackrel{y=rw}{=} \int_0^1 \int_{S^{n-1}} \varphi(r) u(r\varepsilon w+x) r^{n-1} dr dw$$

$$= \int_0^1 \left(\int_{\partial B_\varepsilon(0)} u(r\varepsilon w+x) dw \right) \varphi(r) r^{n-1} dr$$

$$\stackrel{\text{平均值性质}}{=} \int_0^1 u(x) \varphi(r) r^{n-1} dr |w_n| = u(x).$$

故 $u \in C^\infty(\Omega)$. 且 $\forall r > 0, \forall x \in \Omega$

$$\int_{B_r(x)} \Delta u dy = \int_0^r \int_{\partial B_\rho(x)} r^{n-1} \frac{d}{dr} \int_{|w|=1} u(x+rw) dS(w) dr = 0.$$

故 $\Delta u = 0$ in Ω . (否则, $\exists x \in \Omega$, s.t. $\Delta u(x) > 0$. 则 $\exists r_0 > 0$, s.t. $\Delta u(x) > c$.

$\forall x \in B_{r_0}(x)$ 故 $\int_{B_{r_0}(x)} \Delta u(y) dy > 0$. 矛盾!)



命题 2.3. 若 $u \in C(\bar{\Omega})$ 满足平均值性质, 则 u 在 Ω 上达到极大值和极小值, 除非 u 是常数.

证: 只证明极大值的情况. 令 $\Sigma = \{x \in \Omega \mid u(x) = M = \max_{\bar{\Omega}} u\} \subset \Omega$.

(i) 若 $\{x_n\} \subset \Sigma$ 且 $x_n \rightarrow \bar{x}$. 则由 $u \in C(\bar{\Omega})$ 知 $u(\bar{x}) = \lim_{n \rightarrow \infty} u(x_n) = M$.

故 $\bar{x} \in \Sigma$. 即 Σ 是闭集.

(ii) 对 $\forall x_0 \in \Sigma$. 则 $\exists r_0 > 0$, 有 $B_{r_0}(x_0) \subset \Omega$. 由平均值性质,

$$M = u(x_0) = \frac{1}{|B_{r_0}(x_0)|} \int_{B_{r_0}(x_0)} u(y) dy \leq M. \text{ 故 } u(x_0) \equiv M \text{ 在 } B_{r_0}(x_0).$$

即 $B_{r_0}(x_0) \subset \Sigma$. 故 Σ 是开集.

于是, Σ 在 Ω 中既开又闭. 故 $\Sigma = \emptyset$ 或 Ω .

命题 2.4. (梯度估计) 设 $u \in C(\bar{B}_R)$ 是调和的, $(B_R = B_R(x_0))$, 则成立

$$|Du(x_0)| \leq \frac{n}{R} \max_{\bar{B}_R} |u|.$$

证明: 为简单起见, 设 $u \in C^1(\bar{B}_R)$. 则由定理 2.1, u 满足平均值性质.

则由定理 2.2, u 在 B_R 光滑. 因此 $\partial_{x_i} u$ 也是调和. 即 $\Delta \partial_{x_i} u = 0$. 再由定理 2.1,

$$\partial_{x_i} u \text{ 满足平均值性质, 即 } \partial_{x_i} u(x_0) = \frac{1}{|B_R(x_0)|} \int_{B_R(x_0)} \partial_{x_i} u(y) dy$$

$$\stackrel{\text{散度定理}}{=} \frac{1}{|B_R(x_0)|} \int_{\partial B_R(x_0)} u v_i ds$$

$$\Rightarrow |\partial_{x_i} u| \leq \max |u| \frac{|\partial B_R(x_0)|}{|B_R(x_0)|} \leq \frac{n}{R} \max_{x \in \bar{B}_R} |u|. \Rightarrow |Du(x_0)| = \left| \frac{1}{|B_R(x_0)|} \int_{\partial B_R(x_0)} u \vec{\nu} ds \right| \leq \frac{n}{R} \max_{x \in \bar{B}_R} |u|.$$

命题 设 $u \in C(\bar{B}_R)$ 是 $B_R = B_R(x_0)$ 上的非常调和不常数. 则成立

$$|\nabla u(x_0)| \leq \frac{n}{R} u(x_0).$$



(9)

证明: $|\alpha_x u(x_0)| \leq \frac{1}{|\partial B_R(x_0)|} \int_{\partial B_R(x_0)} |u(y)| dS = \frac{1}{|\partial B_R(x_0)|} \int_{\partial B_R(x_0)} u(y) dS \leq \frac{|\partial B_R(x_0)|}{|\partial B_R(x_0)|} u(x_0)$

故 $|\alpha_x u(x_0)| \leq \frac{n}{R} u(x_0)$.

推论: \mathbb{R}^n 上的上有界或下有界的调和函数是常数. (Liouville 定理)

证: 设 $u \leq M$ 是 \mathbb{R}^n 上的调和函数, 则 $M - u \equiv v \geq 0$ 仍是调和的.

$\forall x \in \mathbb{R}^n, \forall R > 0$. 应用上述命题, $|\nabla v(x_0)| \leq \frac{n}{R} v(x_0) \leq \frac{Kn}{R}$

令 $R \rightarrow +\infty$, 则 $|\nabla v(x_0)| = 0$. 故 v 是常数.

(不讲) 推论 (Poisson 公式) 令 $f \in C^2(\mathbb{R}^n)$ 则 $\Delta u = f$ 在 \mathbb{R}^n 的任意有界域具有以下形式:

$$u(x) = \frac{1}{4\pi} \int \frac{1}{|x-y|} f(y) dy + C.$$

令 $v(x) = \frac{1}{4\pi} \int \frac{1}{|x-y|} f(y) dy$, 则 $\Delta v = f$. 故 $\Delta(u-v) = 0$.

由于 u 有界, 故 $f \in C_c^2(\mathbb{R}^n)$, $|v(x)| \leq \frac{1}{4\pi} \int \frac{1}{|x-y|} |f(y)| dy \leq \frac{1}{4\pi} \int_{|y| \leq K} \frac{|f(y)|}{|x-y|} dy$

故 v 有界. 因此, $u-v$ 有上界. $\leq \frac{1}{4\pi} \|f\|_{\infty} \int_{|y| \leq K} \frac{1}{|x-y|} dy \leq C_K \|f\|_{\infty}$

因此, $u-v = C$.

命题 (高阶梯度估计) 设 $u \in C(\bar{B}_R)$ 在 $B_R = B_R(x_0)$ 内是调和的, 则对任意的多重指标 $\alpha, |\alpha| = m$, $|D^\alpha u(x_0)| \leq \frac{n^m e^{m-1} m!}{R^m} \max_{\bar{B}_R} |u|$.

证明: 对 m 用数学归纳法. 当 $m=1$ 时 $|D u(x_0)| \leq \frac{n}{R} \max_{\bar{B}_R} |u|$ 已证.

设 m 时结论成立, 则当 $|\alpha| = m+1$ 时, 对 $D^\alpha u$ 在 B_r 上应用梯度估计,

可得 $|D^{m+1} u(x_0)| \leq \frac{n}{r} \max_{\bar{B}_r} |D^m u| \leq \frac{n}{r} \frac{n^m e^{m-1} m!}{(R-r)^m} \max_{\bar{B}_r} |u|$



$$\forall r=(1-\theta)R, \text{ 则 } |(D^{m+1}u)(x)| \leq \frac{n^{m+1}e^{m+1}m!}{R^{m+1}\theta^m(1-\theta)} \max_{\bar{B}_r} |u|. \quad (10)$$

取 θ 使得 $\theta^m(1-\theta)$ 达到极大值. 即 $\theta = \frac{m}{m+1}$. 则

$$\begin{aligned} |(D^{m+1}u)(x)| &\leq \frac{n^{m+1}e^{m+1}m!}{R^{m+1}} \left(1 + \frac{1}{m}\right)^m (m+1) \max_{\bar{B}_r} |u| \\ &\leq \frac{n^{m+1}(m+1)!e^m}{R^{m+1}} \max_{\bar{B}_r} |u| \end{aligned}$$

定理 (解析性) 调和函数是解析的.

设 u 在 Ω 内调和, $\forall x \in \Omega, \exists R > 0$ s.t. $\bar{B}_{2R}(x) \subset \Omega$. $\forall h, |h| < R$, 由 Taylor 展开,

$$u(x+h) = u(x) + \sum_{i=1}^{m-1} \frac{1}{i!} \left[\left(h_1 \frac{\partial}{\partial x_1} + \dots + h_n \frac{\partial}{\partial x_n} \right)^i u \right](x) + R_m(h)$$

$$R_m(h) = \frac{1}{m!} \left[\left(h_1 \frac{\partial}{\partial x_1} + \dots + h_n \frac{\partial}{\partial x_n} \right)^m u \right](x + h_1\theta_1 + \dots; x_n + \theta_n h_n) \text{ for some } 0 < \theta < 1.$$

$$\begin{aligned} \text{由高阶项估计, } |R_m(h)| &\leq \frac{1}{m!} |h|^m \max_{\bar{B}_R} |D^m u| \leq \frac{1}{m!} |h|^m \frac{n^m e^{m+1} m!}{R^m} \max_{\bar{B}_R} |u| \\ &\leq \frac{1}{e} \left(\frac{|h|ne}{R} \right)^m \max_{\bar{B}_R} |u| \end{aligned}$$

取 h , s.t. $|h| < \frac{R}{ne}$, 则 $|R_m(h)| \rightarrow 0$, as $m \rightarrow +\infty$.

故 u 在 Ω 内解析.

B. Harnack 不等式及应用.

定理 设 u 在 Ω 内调和, 则对于 Ω 中的任意紧集 K , 存在正常数 $C = C(\Omega, K)$

使得若 $u \geq 0$ in Ω , 则 $\frac{1}{C} u(y) \leq u(x) \leq C u(y)$, $\forall x, y \in K$.

证明: Step 1. 取 $R = \frac{1}{4} \text{dist}(K, \partial\Omega)$. 则 $\forall x \in K$, $\bar{B}_{4R}(x) \subset \Omega$.

若 $|x-y| < R$, 则由平均值定理及 $\bar{B}_R(y) \subset \bar{B}_{2R}(x)$. 有

$$u(x) = \frac{1}{4\pi(2R)^2} \int_{\bar{B}_{2R}(x)} u(y) dy \geq \frac{1}{4\pi(2R)^2} \int_{\bar{B}_R(y)} u(y) dy = \frac{1}{2^3} u(y)$$



$$\text{令 } r = (1-\theta)R, \text{ 则 } |(D^{m+1}u)(x_0)| \leq \frac{n^{m+1}e^{m+1}m!}{R^{m+1}\theta^m(1-\theta)} \max_{\overline{B}_R} |u|. \quad (10)$$

取 θ 使得 $\theta^m(1-\theta)$ 达到最大值, 即 $\theta = \frac{m}{m+1}$. 则

$$\begin{aligned} |(D^{m+1}u)(x_0)| &\leq \frac{n^{m+1}e^{m+1}m!}{R^{m+1}} \left(1 + \frac{1}{m}\right)^m (m+1) \max_{\overline{B}_R} |u| \\ &\leq \frac{n^{m+1}(m+1)!e^m}{R^{m+1}} \max_{\overline{B}_R} |u| \end{aligned}$$

定理 (解析性) 调和函数是解析的.

设 u 在 Ω 内调和, $\forall x \in \Omega, \exists R > 0, \text{ s.t. } \overline{B}_{2R}(x) \subset \Omega. \forall h, |h| < R$, 由 Taylor 展开,

$$u(x+h) = u(x) + \sum_{i=1}^{m-1} \frac{1}{i!} \left[\left(h_1 \frac{\partial}{\partial x_1} + \dots + h_n \frac{\partial}{\partial x_n} \right)^i u \right](x) + R_m(h)$$

$$R_m(h) = \frac{1}{m!} \left[\left(h_1 \frac{\partial}{\partial x_1} + \dots + h_n \frac{\partial}{\partial x_n} \right)^m u \right](x + h_1\theta_1 + \dots, x_n + \theta_n) \text{ for some } 0 < \theta < 1.$$

由高阶精度估计, $|R_m(h)| \leq \frac{1}{m!} |h|^m |D^m u| \leq \frac{1}{m!} |h|^m \frac{n^m e^{m+1} m!}{R^m} \max_{\overline{B}_{2R}} |u|$

$$\leq \frac{1}{e} \left(\frac{|h|ne}{R} \right)^m \max_{\overline{B}_{2R}} |u|$$

总取 h , s.t. $|h| < \frac{R}{ne}$, 则 $|R_m(h)| \rightarrow 0$, as $m \rightarrow +\infty$.

故 u 在 Ω 内解析.

B. Harnack 不等式及应用.

定理 设 u 在 Ω 内调和, 则对于 Ω 中的任意紧集 K , 存在正常数 $C = C(\Omega, K)$

使得若 $u \geq 0$ in Ω , 则 $\frac{1}{C} u(y) \leq u(x) \leq C u(y), \forall x, y \in K$.

证明: Step 1. 取 $R = \frac{1}{4} \text{dist}(K, \partial\Omega)$, 则 $\forall x \in K, \overline{B}_{4R}(x) \subset \Omega$.

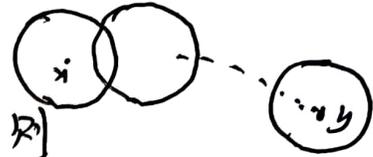
若 $|x-y| < R$, 则由平均值定理及 $\overline{B}_{2R}(y) \subset \overline{B}_{4R}(x)$, 有

$$u(x) = \frac{1}{4\pi(2R)^2} \int_{\overline{B}_{2R}(y)} u(y) dy \geq \frac{1}{4\pi(2R)^2} \int_{\overline{B}_R(y)} u(y) dy = \frac{1}{2^3} u(y)$$



Step 2. 由于 K^c 存在有限个半径为 R 的球 $\{B_i : i=1, \dots, N\}$ 构成 K 的开覆盖.

不断重复 Step 1, 可得 $u(x) \geq \frac{1}{2^{1/n}} u(y)$, $\forall x, y \in K$.



命题 (Harnack 不等式) 设 u 在 $B_R(x_0)$ 内调和且 $u \geq 0$. 则

$$\frac{R}{R+r} \frac{R-r}{R+r} u(x_0) \leq u(x) \leq \frac{R}{R-r} \frac{R+r}{R-r} u(x_0), \text{ 其中 } r = |x - x_0| < R.$$

证明: 不妨设 $x_0 = 0$. 由 Poisson 公式,

$$u(x) = \frac{R^2 - |x|^2}{4\pi R} \int_{\partial B_R} \frac{u(y)}{|x-y|^3} dy, \quad \forall x \in B_R.$$

由于 $|y|=R$, 故 $R-|x| \leq |x-y| \leq R+|x|$. 因此,

$$\begin{aligned} u(x) &\leq \frac{R^2 - |x|^2}{4\pi R (R-|x|)^3} \int_{\partial B_R} u(y) dy = \frac{(R^2 - |x|^2) 4\pi R^2}{4\pi R (R^2 - |x|^2)^3} \frac{1}{4\pi R^2} \int_{\partial B_R} u(y) dy \\ &= \frac{(R+|x|)R}{(R-|x|)^2} u(x_0) \end{aligned}$$

$$\text{且 } u(x) \geq \frac{R^2 - |x|^2}{4\pi R (R+|x|)^3} \int_{\partial B_R} u(y) dy = \frac{R(R-|x|)}{(R+|x|)^2} u(x_0)$$

推论: 若 u 是 \mathbb{R}^n 上的上有界或下有界调和函数, 则 u 是常数.

证: 设 $u \geq 0$. $\forall x \in \mathbb{R}^n$, 在 $B_R(x)$ ($R > |x|$) 上应用 Harnack 不等式,

$$\text{则 } \frac{(R+|x|)R}{(R-|x|)^2} u(x) \geq u(x) \geq \frac{(R-|x|)R}{(R+|x|)^2} u(x)$$

令 $R \rightarrow +\infty$, 则有 $u(x) = u(0)$.

定理 (奇点可去定理) 设 u 在 $B_R \setminus \{0\}$ 调和且满足 $u(x) = \begin{cases} o(|\log|x||) & n=2 \\ o(|x|^{-n}) & n=3 \end{cases}$

as $|x| \rightarrow 0$, 则可令 u 在原点定义使得 $u \in C^2(B_R)$ 且在 B_R 内调和.



证明: 只证明 $n=3$ 的情形. 令 $\begin{cases} \Delta v = 0 & \text{in } B_R \setminus \{0\} \\ v = u & \text{on } \partial B_R \end{cases}$ 由 Poisson

公式, v 存在, 且 $v \in C^2(B_R) \cap C(\bar{B}_R)$. 只需证明 $v = u$ in $B_R \setminus \{0\}$.

则可重新定义 $u(0) = v(0)$ 使得 $u \in C^2(B_R)$ 在 B_R 调和.

令 $w = v - u$ in $B_R \setminus \{0\}$. $\forall c < R$, 令 $M_r = \max_{\partial B_r} |w|$. 则

$$|w(x)| \leq M_r \frac{r}{|x|} \quad \text{on } \partial B_r.$$

则 $w \pm M_r \frac{r}{|x|}$ 在 $r < |x| < R$ 调和. 故 $\max_{\partial B_r} w(x) \geq 0, |x| > r$,

$w(x) = M_r \frac{r}{R} > 0, |x| = R$. 故由极大值原理, $w(x) > 0, \forall r < |x| < R$.

故 $|w(x)| \leq M_r \frac{r}{|x|}, \forall r < |x| < R$.

由于 v 是调和的, $\max_{\partial B_r} |v| = \max_{\partial B_r} |u| = \max_{\partial B_r} |w|$. 故

$$\max_{\partial B_r} |v| \leq \max_{\partial B_r} |w| \triangleq M.$$

于是, $M_r \leq \max_{\partial B_r} |v| + \max_{\partial B_r} u \leq M + \max_{\partial B_r} |u(x)|$.

因此, $|w(x)| \leq \frac{r}{|x|} (M + \max_{\partial B_r} |u(x)|), \forall r < |x| < R$.

由已知条件, $\max_{\partial B_r} |u(x)| \rightarrow 0, \text{ as } r \rightarrow 0$. 因此, $r \max_{\partial B_r} |u(x)| \rightarrow 0, \text{ as } r \rightarrow 0$.

令 $r \rightarrow 0$. 则有 $w(x) = 0$ in $B_R \setminus \{0\}$.

§3. 极大值原理. 第二边值解的唯一性.

定理 3.1 设 $u \in C^2(B) \cap C(\bar{B})$ 是 B 上的次调和函数, 即 $\Delta u \geq 0$. 则有 $\sup_B u \leq \sup_{\partial B} u$.

证明: 令 $u_\varepsilon(x) = u(x) + \varepsilon|x|^2, \varepsilon > 0$. 则 $\Delta u_\varepsilon = \Delta u + 2\varepsilon > 0$

若 u_ε 在 B 的内部达到最大值, 则 $\Delta u_\varepsilon(x) < 0$. $\rightarrow \Delta u_\varepsilon > 0$ 矛盾!



因此, u_ε 的最大值只能在边界取到. 即 $\sup_{x \in B_1} u_\varepsilon = \sup_{x \in \partial B_1} u_\varepsilon \leq \sup_{x \in \partial B_1} u + \varepsilon$
 令 $\varepsilon \rightarrow 0^+$, 则 $\sup_{\bar{B}_1} u \leq \sup_{\partial B_1} u$. $\sup_{\bar{B}_1} u \leq$

定理 3.2 (内部梯度估计) 设 u 在 B_1 内调和, 则有 $\sup_{\bar{B}_{1/2}} |Du| \leq C \sup_{\partial B_1} |u|$.

其中 $C = C(n)$ 是正常数. 特别地, $\forall \alpha \in [0, 1]$,

$$|u(x) - u(y)| \leq C |x - y|^\alpha \sup_{\partial B_1} |u|. \quad \forall x, y \in B_{1/2}, \quad C = C(n, \alpha) > 0.$$

证明: 要估计 $|Du|$, 只需考察 $|Du|^2$ 满足的方程

$$\begin{aligned} \Delta(|Du|^2) &= \sum_{i,j=1}^n \partial_i^2 (|\partial_j u|^2) = \sum_{i,j} \partial_i (2 \partial_j u \partial_i \partial_j u) = \sum_{i,j} (2 \partial_i \partial_j u^2 + 2 \partial_j u \partial_i^2 u) \\ &= 2 \sum_{i,j=1}^n |\partial_i \partial_j u|^2 \geq 0. \end{aligned}$$

但是, 由最大值原理,

$$\max_{\bar{B}_1} |Du| \leq \max_{\partial B_1} |Du|.$$

令 $\varphi \in C_0^\infty(B_1)$, 则

$$\begin{aligned} \Delta(\varphi |Du|^2) &= \Delta\varphi |Du|^2 + 2\nabla\varphi \cdot \nabla(|Du|^2) + \varphi \Delta(|Du|^2) \\ &= \Delta\varphi |Du|^2 + 4\partial_j \varphi \partial_i u \partial_i \partial_j u + 2\varphi \sum_{i,j} |\partial_i \partial_j u|^2 - C |Du|^2 \end{aligned}$$

令 $\eta \in C_0^\infty(B_1)$, $\eta \equiv 1$ on $\bar{B}_{1/2}$. 令 $\varphi = \eta^2$, 则

$$\begin{aligned} \Delta(\eta^2 |Du|^2) &= \Delta(\eta^2) |Du|^2 + 8\eta \partial_j \eta \partial_i u \partial_i \partial_j u + 2\eta^2 \sum_{i,j} |\partial_i \partial_j u|^2 \\ &\geq \Delta(\eta^2) |Du|^2 - \frac{8\eta \sum_{i,j} |\partial_i \partial_j u|^2 + 4\partial_j \eta \partial_i u^2}{2} + 2\eta^2 \sum_{i,j} |\partial_i \partial_j u|^2 \\ &\geq \Delta(\eta^2) |Du|^2 - 8|\nabla\eta|^2 |Du|^2 \geq -C |Du|^2 \end{aligned}$$

$$\Delta(u^2) = 2u\Delta u + 4|Du|^2 \geq 4|Du|^2$$

于是, $\Delta(\eta^2 |Du|^2 + \frac{C}{4} u^2) \geq 0$. 由最大值原理,

$$\begin{aligned} \max_{\bar{B}_1} (\eta^2 |Du|^2 + \frac{C}{4} u^2) &= \max_{\partial B_1} (\eta^2 |Du|^2 + \frac{C}{4} u^2) = \frac{C}{4} (\max_{\partial B_1} |u|)^2 \\ &\leq \max_{\bar{B}_{1/2}} (\eta^2 |Du|^2 + \frac{C}{4} u^2) \\ &\Rightarrow \max_{\bar{B}_{1/2}} |Du| \leq C \max_{\partial B_1} |u|. \end{aligned}$$



引理 3.3. 设 u 是 B_1 上的非负调和函数. 则存在 $C=C(n)$, 使得

$$\sup_{B_{\frac{1}{2}}} |D \log u| \leq C.$$

证明: (不讲).

推论 3.4. 设 u 是 B_1 上的非负调和函数. 则存在 $C=C(n)$, s.t.

$$u(x) \leq C u(x_2), \quad \forall x, x_2 \in B_{\frac{1}{2}}.$$

若 u 在内部一点为零 即 $u \equiv 0$.

证明: 设 $u > 0$ in B_1 . 由引理 3.3, $\forall x_1, x_2 \in B_{\frac{1}{2}}$,

$$|\log u(x_1) - \log u(x_2)| = \left| \int_0^1 D \log u(t x_2 + (1-t)x_1) dt (x_2 - x_1) \right| \leq C |x_1 - x_2| \leq C$$

故 $u(x_1) \leq C u(x_2)$.

命题 3.5 (Hopf 引理) 设 $u \in C(\bar{B}_1)$ 是 $B_1 = B_1(0)$ 上的调和函数. 若有存在 $x_0 \in \partial B_1$, 使得 $u(x) < u(x_0), \forall x \in B_1$. 则存在 $C=C(n)$ 使得 $\frac{\partial u}{\partial n}(x_0) \geq C(u(x_0) - u(0)) > 0$.

证明: Step 1. 令 $v(x) = e^{-\alpha|x|^2} - e^{-\alpha}$, 则 $v(x) > 0, \forall x \in B_1$

$$\text{且 } \partial_i v = -2\alpha x_i e^{-\alpha|x|^2}, \quad \partial_i^2 v = -2\alpha e^{-\alpha|x|^2} + 4\alpha^2 x_i^2 e^{-\alpha|x|^2}$$

$$\Rightarrow \Delta v = (-2\alpha n + 4\alpha^2|x|^2) e^{-\alpha|x|^2}$$

当 $\frac{1}{2} < |x| < 1$ 时, $-2\alpha n + 4\alpha^2|x|^2 > -2\alpha n + \alpha^2 > 0$ 若 $\alpha = 2n+1$.

故 当 $\alpha = 2n+1$ 时, $\Delta v > 0$.

Step 2. $\forall \varepsilon > 0$, 定义 $h_\varepsilon(x) = u(x) - u(x_0) + \varepsilon v(x)$. 则 $\Delta h_\varepsilon = \Delta u + \varepsilon \Delta v = \varepsilon \Delta v > 0$,

$$\forall \frac{1}{2} < |x| < 1. \text{ 且 } h_\varepsilon(x) \leq \max_{|x|=\frac{1}{2}} u(x) - u(x_0) + \varepsilon (e^{-\frac{\alpha}{4}} - e^{-\alpha}) < 0, \quad \text{当 } |x| \leq \frac{1}{2}$$



• $\frac{1}{2}H=1, h_\varepsilon(x) = \max_{\partial B_\varepsilon} u - u(x_0) \leq 0$. 由极大值原理, h_ε 在 $\{x=1\} \cup \{x=-1\}$ 达到最大值. 又 $h_\varepsilon(x_0) = 0$, 故 h_ε 在 x_0 处达到最大值. 于是,

$$\frac{\partial h_\varepsilon}{\partial n}(x_0) \geq 0. \text{ 即 } \frac{\partial u}{\partial n}(x_0) - 2\alpha x e^{-\alpha x} \varepsilon = \frac{\partial u}{\partial n}(x_0) - 2\alpha \varepsilon e^{-\alpha} \geq 0.$$

$$\text{故 } \frac{\partial u}{\partial n}(x_0) \geq 2\alpha \varepsilon e^{-\alpha} > 0.$$

Step 3 估计 ε . 令 $w(x) = u(x) - u(x_0) \stackrel{0}{\geq}$. 则 $\Delta w = 0$ in B_1 . 由Harnack不等式,

$$w(0) \leq C \inf_{B_{1/2}} w(x) \Leftrightarrow u(0) - u(x_0) \leq C \inf_{B_{1/2}} (u(x) - u(x_0))$$

$$\text{即 } \max_{B_{1/2}} u(x) \leq u(x_0) - \frac{1}{C} (u(x_0) - u(0)) = C (u(x_0) - \max_{B_{1/2}} u(x))$$

$$\text{取 } \delta \text{ 充分小, 令 } \varepsilon = \frac{\delta}{C} (u(x_0) - u(0)). \text{ 解即可.}$$

□

称 Ω 满足内切球条件. 如果在它边界 Γ 上的每一点均可作一完全落在 Ω 内的球且与 Γ 在 x_0 相切.

定理 3.6. 设 Ω 具有内切球性质. 若 $u \in C(\bar{\Omega})$, u 不恒为常数且调和, 它在 $x_0 \in \partial\Omega$ 取最大值, 则 $\frac{\partial u}{\partial n}(x_0) > 0$.

证明: 由于 u 不是常数, 由极大值原理, u 只在边界取到最大值.

由于 Ω 具有内切球性质, 在 $x_0 \in \partial\Omega$ 处, 存在球 $B \subset \Omega$ 且 B 在 x_0 处与 $\partial\Omega$ 相切. 且 $\forall x \in B, u(x) < u(x_0)$. 由Hopf引理, $\frac{\partial u}{\partial n}(x_0) > 0$.



定理 2 (等-边值问题解的唯一性) 若 Ω 满足内切球条件, 则第二边值问题的解集 $u \in C(\bar{\Omega}) \cap C^2(\Omega)$ (在相差一个常数意义下) 是唯一的.

证明: 设 u_1, u_2 是两个不同的解, 则 $u = u_1 - u_2$ 满足 $\begin{cases} \Delta u = 0 & \text{in } \Omega \\ \frac{\partial u}{\partial n} = 0 & \text{on } \partial\Omega. \end{cases}$

由极大值原理, 若 u 不是常数, 则 u 的最大值只能在边界上. 设 u 在 $x_0 \in \partial\Omega$ 达到最大值. 由于 Ω 满足内切球性质, 由 Hopf 引理, $\frac{\partial u}{\partial n}(x_0) > 0$. 这与 $\frac{\partial u}{\partial n}(x_0) = 0$ 矛盾! 故 u 只能是常数.

定理 3 (最大模估计). 设 $u \in C^2(\bar{\Omega}) \cap C(\bar{\Omega})$ 是 $\begin{cases} \Delta u = f & \text{in } \Omega \\ u = \varphi & \text{on } \partial\Omega \end{cases}$ 的解

则存在 $C = C(\Omega) > 0$ 使得 $\max_{\bar{\Omega}} |u| \leq \Phi + CF$,

其中 $\Phi = \max_{\partial\Omega} |\varphi|$, $F = \sup_{\Omega} |f|$.

证明: 不妨设 Ω 在条件区域 $0 < x_1 < d$ 中. 作辅助函数 $v(x) = \Phi + (e^{ax} - e^{ax_1})F$, $a > 0$

且在 Ω 中 $\begin{cases} \Delta(u-v) = f + a^2 e^{ax_1} F \geq F - |f| \geq 0 \\ (u-v)|_{\partial\Omega} = \varphi - \Phi - (e^{ax} - e^{ax_1})F \leq 0 \end{cases}$

于是, 由极大值原理, $u-v \leq 0$ in Ω .

因此, $u(x) \leq v(x) = \Phi + (e^{ax} - e^{ax_1})F \leq \Phi + (e^{ad} - 1)F, \forall x \in \Omega$.

对 $-u$ 可类似证明. 因此有 $\max_{\bar{\Omega}} |u(x)| \leq \Phi + (e^{ad} - 1)F$. □

Remark: 最大模估计意味着 Dirichlet 问题解的唯一性和稳定性.

能量法证明 Dirichlet 问题解的唯一性. $\begin{cases} \Delta u = 0 & \text{in } \Omega \\ u|_{\partial\Omega} = 0 \end{cases}$, 要证 $u \equiv 0$ in Ω .

$$0 = \int_{\Omega} u \Delta u = \int_{\partial\Omega} u \frac{\partial u}{\partial n} dS - \int_{\Omega} |\nabla u|^2 = - \int_{\Omega} |\nabla u|^2 dx.$$

故 $\nabla u \equiv 0$. 又因 $u \equiv \text{const}$. 又 $u = 0$ on $\partial\Omega$. 故 $u \equiv 0$, in Ω .

